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**On Entire Solutions Of The Equations For The
Displacement Fields In The Deformation Theory Of
Plasticity With Logarithmic Hardening**

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Abstract

Let $u : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ denote an entire solution of the homogeneous Euler-Lagrange equation associated to the energy used in the deformation theory of plasticity with logarithmic hardening. If $|u(x)|$ is of slower growth than $|x|$ as $|x| \rightarrow \infty$, then u must be constant. Moreover we show that u is affine if either $\sup_{\mathbb{R}^2} |\nabla u| < \infty$ or $\limsup_{|x| \rightarrow \infty} |x|^{-1} |u(x)| < \infty$.

In their paper [FrSe] Frehse and Seregin propose to approximate the Hencky model used in perfect plasticity (cf. [DL], [He] or [Kl]) by a variational problem formulated in terms of the displacement fields, in which the energy density $G(\varepsilon(u))$ is of quadratic growth with respect to the trace of $\varepsilon(u)$ and of $L \log L$ -growth with respect to the deviator $\varepsilon^D(u) = \varepsilon(u) - \frac{1}{n}(\operatorname{div} u)\mathbf{1}$ of $\varepsilon(u)$. Here u is a displacement field defined on some region in \mathbb{R}^n , $\varepsilon(u)$ denotes the symmetric part of the Jacobian matrix of u and $\mathbf{1}$ is the unit matrix. Modulo physical constants we have in the case of logarithmic hardening

$$(1) \quad G(\varepsilon) = h(|\varepsilon^D|) + \frac{1}{2} (\operatorname{trace} \varepsilon)^2$$

for symmetric $(n \times n)$ -matrices ε , where

$$(2) \quad h(t) = t \ln(1 + t), \quad t \geq 0.$$

Frehse and Seregin discuss solvability of the associated boundary value problems in suitable weak spaces and prove smoothness of local solutions at least in the case that $n = 2$. Later Seregin and the first author (see [FuSe1]) established partial regularity in the 3D case.

A related problem arises in the study of certain models describing the flow of generalized Newtonian fluids, for which the stress-strain relation takes the form

$$(3) \quad T^D = DH(\varepsilon).$$

If we let

$$(4) \quad H(\varepsilon) = h(|\varepsilon|)$$

with h defined in equation (2), then (3) is the constitutive law for the so-called Prandtl–Eyring fluid, which has been the subject of the paper [FuSe1] and also of the monograph [FuSe2]. Very recently the authors discussed the behaviour of entire solutions of this fluid model at least in the stationary case for two spatial variables and proved Liouville-type results (see [FuZ]). The purpose of the present paper now is the investigation of planar entire solutions in the setting of plasticity with logarithmic hardening.

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DEFINITION 1. A field $u : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ of class C^1 is an entire local minimizer of the energy

$$(5) \quad I[v, \Omega] = \int_{\Omega} G(\varepsilon(v)) \, dx$$

with density G defined according to equations (1) and (2), if for any bounded domain $\Omega \subset \mathbb{R}^2$ and all fields $v : \Omega \rightarrow \mathbb{R}^2$ such that $\text{spt}(u - v)$ is compactly contained in Ω it holds

$$I[u, \Omega] \leq I[v, \Omega].$$

REMARK 1. The smoothness assumption concerning u in Definition 1 is justified by the results in [FrSe].

REMARK 2. If u is an entire local I -minimizer, then it holds

$$(6) \quad \int_{\Omega} DH(\varepsilon^D(u)) : \varepsilon^D(\varphi) \, dx + \int_{\Omega} \text{div } u \, \text{div } \varphi \, dx = 0$$

for any domain $\Omega \subset \mathbb{R}^2$ and all fields $\varphi \in C_0^1(\Omega; \mathbb{R}^2)$. In equation (6) the symbol “:” is the scalar product of matrices and H is introduced in equation (4).

Now we can state our main results:

THEOREM 1. Let $u : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ denote an entire local I -minimizer (cf. equation (5)) in the sense of Definition 1. If u satisfies the asymptotic condition

$$(7) \quad \lim_{|x| \rightarrow \infty} \frac{|u(x)|}{|x|} = 0,$$

then the displacement field u is a constant vector. In particular, the boundedness of the field implies its constancy.

The next theorem concerns entire solutions satisfying a global Lipschitz condition:

THEOREM 2. Consider an entire local I -minimizer $u : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ in the sense of Definition 1. If we know that $|\nabla u| \in L^\infty(\mathbb{R}^2)$, then u must be affine.

Finally we relax the global boundedness of the gradient by imposing a growth condition on u :

THEOREM 3. If the entire local I -minimizer $u : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ satisfies $\limsup_{|x| \rightarrow \infty} |x|^{-1}|u(x)| < \infty$, then u must be affine.

REMARK 3. It would be interesting to know what can be said about entire solutions in the 3D-case. Due to the lack of regularity (cf. [FuSe1,2]) one either has to deal with weak local minimizers or the smoothness of u has to be imposed as a severe extra condition. In the latter case we think that for $n = 3$ condition (7) has to be replaced by $\lim_{|x| \rightarrow \infty} \frac{|u(x)|}{\sqrt{|x|}} = 0$ in order to obtain the constancy of u , and this conclusion probably also holds in the case that $\limsup_{|x| \rightarrow \infty} \frac{|u(x)|}{\sqrt{|x|}} < \infty$ (compare the proof of Theorem 3).

For the proof of Theorem 1 we need two auxiliary results:

Lemma 1. (*Korn-type inequality*)

For fields $v : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ with compact support it holds

$$(8) \quad \int_{\mathbb{R}^2} |\nabla v|^2 dx \leq 2 \int_{\mathbb{R}^2} |\varepsilon^D(v)|^2 dx.$$

Korn-type inequalities involving ε^D have been established by Reshetnyak [Re] in a much more general setting. Recently Dain rediscovered these estimates in the L^2 -setting (see [Da]), and the first author together with Bildhauer proved variants in the context of Orlicz-Sobolev spaces (cf. [FuB]).

The next lemma is essentially due to Giaquinta and Modica (compare Lemma 0.5 in [GM]), in the formulation given below it corresponds to Lemma 3.1 in [FuZ].

Lemma 2. Let f, f_1, \dots, f_ℓ denote non-negative functions from the space $L^1_{\text{loc}}(\mathbb{R}^2)$ and suppose that we are given exponents $\alpha_1, \dots, \alpha_\ell > 0$. Then we can find a number $\delta_0 > 0$ depending on $\alpha_1, \dots, \alpha_\ell$ as follows: if for $\delta \in (0, \delta_0)$ it is possible to calculate a constant $c(\delta) > 0$ such that the inequality

$$\int_{Q_R(z)} f dx \leq \delta \int_{Q_{2R}(z)} f dx + c(\delta) \sum_{j=1}^{\ell} R^{-\alpha_j} \int_{Q_{2R}(z)} f_j dx$$

holds for any choice of $Q_R(z) := \{x \in \mathbb{R}^2 : |x_i - z_i| < R, i = 1, 2\}$, then there is a constant $c > 0$ with the property

$$\int_{Q_R(z)} f dx \leq c \sum_{j=1}^{\ell} R^{-\alpha_j} \int_{Q_{2R}(z)} f_j dx$$

again for all squares $Q_R(z)$.

REMARK 4. Of course Lemma 2 extends to \mathbb{R}^n , $n \geq 3$, replacing squares by cubes, and it is easy to see that estimate (8) remains valid in higher dimensions.

Now we pass to the **proof of Theorem 1** proceeding in several steps.

Step 1. a growth estimate for the energy

We fix a square $Q_{2R}(x_0)$ and choose $\eta \in C^1_0(Q_{2R}(x_0))$ such that $\eta = 1$ on $Q_R(x_0)$, $0 \leq \eta \leq 1$, $|\nabla \eta| \leq c/R$. Then we apply equation (6) by selecting $\varphi = \eta^2 u$. We get with H defined

in (4)

$$\begin{aligned}
(9) \quad & \int_{Q_{2R}(x_0)} \eta^2 DH(\varepsilon^D(u)) : \varepsilon^D(u) dx + \int_{Q_{2R}(x_0)} \eta^2 (\operatorname{div} u)^2 dx \\
& = -2 \int_{Q_{2R}(x_0)} \eta DH(\varepsilon^D(u)) : (\nabla \eta \otimes u)^D dx - 2 \int_{Q_{2R}(x_0)} \eta \operatorname{div} u \nabla \eta \cdot u dx \\
& \leq c \left[\int_{Q_{2R}(x_0)} \eta h'(|\varepsilon^D(u)|) |\nabla \eta| |u| dx + \int_{Q_{2R}(x_0)} \eta |\operatorname{div} u| |\nabla \eta| |u| dx \right].
\end{aligned}$$

Using Young's inequality we obtain for any $\delta > 0$

$$\begin{aligned}
\eta h'(|\varepsilon^D(u)|) |\nabla \eta| |u| & \leq \delta \eta^2 h'(|\varepsilon^D(u)|) |\varepsilon^D(u)| + \delta^{-1} |\nabla \eta|^2 \frac{h'(|\varepsilon^D(u)|)}{|\varepsilon^D(u)|} |u|^2, \\
\eta |\operatorname{div} u| |\nabla \eta| |u| & \leq \delta \eta^2 (\operatorname{div} u)^2 + \delta^{-1} |\nabla \eta|^2 |u|^2.
\end{aligned}$$

Inserting these estimates in inequality (9) observing that $\frac{h'(t)}{t} \leq 2$, we deduce after appropriate choice of δ and recalling the properties of η

$$\begin{aligned}
(10) \quad \int_{Q_R(x_0)} G(\varepsilon(u)) dx & = \int_{Q_R(x_0)} \left[H(\varepsilon^D(u)) + \frac{1}{2} (\operatorname{div} u)^2 \right] dx \\
& \leq cR^{-2} \int_{Q_{2R}(x_0) - \overline{Q}_R(x_0)} |u|^2 dx.
\end{aligned}$$

In particular, if we choose $x_0 = 0$ and abbreviate

$$\Theta(R) := \sup \{ |x|^{-1} |u(x)| : x \in \mathbb{R}^2 - \overline{Q}_R \},$$

then (10) implies

$$(11) \quad \int_{Q_R} G(\varepsilon(u)) dx \leq cR^2 \Theta(R)^2$$

with $\lim_{R \rightarrow \infty} \Theta(R) = 0$ according to our hypothesis (7).

Step 2. discussion of the second derivatives

Returning to equation (6) and performing an integration by parts we get for $\alpha = 1, 2$ and $\varphi \in C_0^1(Q_{\frac{3}{2}R}(x_0))$

$$(12) \quad 0 = \int_{Q_{\frac{3}{2}R}(x_0)} D^2 H(\varepsilon^D(u)) (\varepsilon^D(\partial_\alpha u), \varepsilon^D(\varphi)) dx + \int_{Q_{\frac{3}{2}R}(x_0)} \operatorname{div}(\partial_\alpha u) \operatorname{div} \varphi dx.$$

In equation (12) we choose $\varphi = \eta^2 \partial_\alpha u$ (from now on summation with respect to $\alpha = 1, 2$), where η is as in Step 1 with $2R$ replaced by $\frac{3}{2}R$. From (12) we easily obtain by applying the Cauchy-Schwarz inequality to the quantity

$$D^2 H(\varepsilon^D(u)) (\eta \varepsilon^D(\partial_\alpha u), (\nabla \eta \otimes \partial_\alpha u)^D)$$

and appropriate use of Young's inequality (observing the boundedness of $|D^2H(\varepsilon^D(u))|$)

$$\begin{aligned} & \int_{Q_{\frac{3}{2}R}(x_0)} D^2H(\partial_\alpha \varepsilon^D(u), \partial_\alpha \varepsilon^D(u)) \eta^2 dx \\ & + \int_{Q_{\frac{3}{2}R}(x_0)} \eta^2 |\nabla(\operatorname{div} u)|^2 dx \leq c \int_{Q_{\frac{3}{2}R}(x_0)} |\nabla \eta|^2 |\nabla u|^2 dx, \end{aligned}$$

hence by the properties of η

$$(13) \quad \begin{aligned} & \int_{Q_R(x_0)} D^2H(\varepsilon^D(u)) (\varepsilon^D(\partial_\alpha u), \varepsilon^D(\partial_\alpha u)) dx \\ & + \int_{Q_R(x_0)} |\nabla(\operatorname{div} u)|^2 dx \leq cR^{-2} \int_{Q_{\frac{3}{2}R}(x_0)} |\nabla u|^2 dx, \end{aligned}$$

and inequality (13) holds for all squares $Q_R(x_0)$. Note that (13) implies that entire local minimizers having finite Dirichlet integral must be affine. This follows by letting $R \rightarrow \infty$ and observing that on the right-hand side of (13) the domain of integration can be replaced by $Q_{\frac{3}{2}R}(x_0) - \overline{Q_R(x_0)}$. In order to control $\int_{Q_{\frac{3}{2}R}(x_0)} |\nabla u|^2 dx$ we choose $\Psi \in C_0^1(Q_{2R}(x_0))$ such that $0 \leq \Psi \leq 1$, $\Psi = 1$ on $Q_{\frac{3}{2}R}(x_0)$ and $|\nabla \Psi| \leq c/R$. From estimate (8) in Lemma 1 we obtain

$$\begin{aligned} & \int_{Q_{\frac{3}{2}R}(x_0)} |\nabla u|^2 dx \leq c \left[\int_{Q_{2R}(x_0)} |\nabla(\Psi u)|^2 dx + \int_{Q_{2R}(x_0)} |\nabla \Psi|^2 |u|^2 dx \right] \\ & \leq c \left[\int_{Q_{2R}(x_0)} |\varepsilon^D(\Psi u)|^2 dx + \int_{Q_{2R}(x_0)} |\nabla \Psi|^2 |u|^2 dx \right] \\ & \leq c \left[\int_{Q_{2R}(x_0)} \Psi^2 |\varepsilon^D(u)|^2 dx + R^{-2} \int_{Q_{2R}(x_0)} |u|^2 dx \right] \end{aligned}$$

or by the support properties of Ψ

$$(14) \quad \int_{Q_{\frac{3}{2}R}(x_0)} |\nabla u|^2 dx \leq c \left[\int_{Q_{2R}(x_0)} \Psi^2 |\varepsilon^D(u)|^2 dx + R^{-2} \int_{Q_{2R}(x_0) - \overline{Q_{\frac{3}{2}R}(x_0)}} |u|^2 dx \right].$$

In order to proceed we observe

$$\varepsilon_{ij}^D(u) = \frac{1}{2} \left(\frac{\partial u^j}{\partial x_i} + \frac{\partial u^i}{\partial x_j} \right) - \frac{1}{2} (\operatorname{div} u) \delta_{ij},$$

hence by the symmetry of $\varepsilon^D(u)$ and the fact that $\varepsilon_{ij}^D(u) \delta_{ij} = 0$

$$\begin{aligned} & \int_{Q_{2R}(x_0)} \Psi^2 |\varepsilon^D(u)|^2 dx \\ & = \frac{1}{2} \int_{Q_{2R}(x_0)} \Psi^2 \left\{ \left(\frac{\partial u^i}{\partial x_j} + \frac{\partial u^j}{\partial x_i} \right) - (\operatorname{div} u) \delta_{ij} \right\} \varepsilon_{ij}^D(u) dx \\ & = - \int_{Q_{2R}(x_0)} \partial_i (\Psi^2 \varepsilon_{ij}^D(u)) u^j dx. \end{aligned}$$

This yields

$$\begin{aligned}
& \int_{Q_{2R}(x_0)} \Psi^2 |\varepsilon^D(u)|^2 dx \leq c \left[\int_{Q_{2R}(x_0)} |\nabla \Psi^2| |u| |\varepsilon^D(u)| dx \right. \\
& \quad \left. + \int_{Q_{2R}(x_0)} \Psi^2 |\nabla \varepsilon^D(u)| |u| dx \right] \\
& \leq c \left[R^{-1} \int_{Q_{2R}(x_0)} |u| |\varepsilon^D(u)| dx + \delta \int_{Q_{2R}(x_0)} \frac{|\nabla \varepsilon^D(u)|^2}{1 + |\varepsilon^D(u)|} dx \right. \\
& \quad \left. + \delta^{-1} \int_{Q_{2R}(x_0)} |u|^2 (1 + |\varepsilon^D(u)|) dx \right].
\end{aligned}$$

Let $\omega := D^2 H(\varepsilon^D(u))(\partial_\alpha \varepsilon^D(u), \partial_\alpha \varepsilon^D(u))$. If we combine (13), (14) and the inequalities from above, we obtain for any $\delta > 0$ and all squares $Q_R(x_0)$

$$\begin{aligned}
(15) \quad & \int_{Q_R(x_0)} \omega dx + \int_{Q_R(x_0)} |\nabla(\operatorname{div} u)|^2 dx \\
& \leq c \left[R^{-4} \int_{Q_{2R}(x_0)} |u|^2 dx + R^{-2} \delta \int_{Q_{2R}(x_0)} \omega dx \right. \\
& \quad \left. + R^{-3} \int_{Q_{2R}(x_0)} |u| |\varepsilon^D(u)| dx + R^{-2} \delta^{-1} \int_{Q_{2R}(x_0)} |u|^2 (1 + |\varepsilon^D(u)|) dx \right].
\end{aligned}$$

Replacing δ by $\delta' R^2$ an application of Lemma 2 yields

$$\begin{aligned}
(15') \quad & \int_{Q_R(x_0)} \omega dx + \int_{Q_R(x_0)} |\nabla(\operatorname{div} u)|^2 dx \\
& \leq c \left[R^{-4} \int_{Q_{2R}(x_0)} |u|^2 dx + R^{-3} \int_{Q_{2R}(x_0)} |u| |\varepsilon^D(u)| dx \right. \\
& \quad \left. + R^{-4} \int_{Q_{2R}(x_0)} |u|^2 (1 + |\varepsilon^D(u)|) dx \right].
\end{aligned}$$

Let $x_0 = 0$ and $R \geq 1$. From our hypothesis (7) we obtain $|u(x)| \leq cR$ on Q_{2R} . Therefore (15') implies

$$(16) \quad \int_{Q_R} \omega dx + \int_{Q_R} |\nabla(\operatorname{div} u)|^2 dx \leq c \left[R^{-4} R^4 + R^{-2} \int_{Q_{2R}} |\varepsilon^D(u)| dx \right].$$

Clearly we have ($Q^+ := Q_{2R} \cap [|\varepsilon^D(u)| \geq 1]$, $Q^- := \dots$)

$$\begin{aligned}
& \int_{Q_{2R}} |\varepsilon^D(u)| dx = \int_{Q^+} |\varepsilon^D(u)| dx + \int_{Q^-} |\varepsilon^D(u)| dx \\
& \leq \left(\int_{Q^-} 1 dx \right)^{1/2} \left(\int_{Q^-} |\varepsilon^D(u)|^2 dx \right)^{1/2} + \frac{1}{\ln 2} \int_{Q^+} H(\varepsilon^D(u)) dx \\
& \leq cR \left(\int_{Q_{2R}} H(\varepsilon^D(u)) dx \right)^{1/2} + \frac{1}{\ln 2} \int_{Q_{2R}} H(\varepsilon^D(u)) dx,
\end{aligned}$$

and if we use (10), we find

$$(17) \quad \int_{Q_{2R}} |\varepsilon^D(u)| dx \leq cR^2.$$

This shows that the right-hand side of (16) stays bounded as $R \rightarrow \infty$, which means

$$(18) \quad \int_{\mathbb{R}^2} \omega dx + \int_{\mathbb{R}^2} |\nabla(\operatorname{div} u)|^2 dx < \infty.$$

Step 3. conclusion

We claim that the integral in (18) vanishes. In order to prove this we choose $x_0 = 0$ and return to inequality (13) recalling that in place of (13) we actually have

$$\int_{Q_R} |\nabla(\operatorname{div} u)|^2 dx + \int_{Q_R} \omega dx \leq cR^{-2} \int_{Q_{\frac{3}{2}R} - \bar{Q}_R} |\nabla u|^2 dx.$$

Let $\Psi \in C_0^1(Q_{2R} - \bar{Q}_{R/2})$ such that $0 \leq \Psi \leq 1$ and $\Psi = 1$ on $Q_{\frac{3}{2}R} - \bar{Q}_R$ together with $|\nabla \Psi| \leq c/R$. Observing

$$\int_{Q_{\frac{3}{2}R} - \bar{Q}_R} |\nabla u|^2 dx \leq c \left[\int_{Q_{2R} - \bar{Q}_{R/2}} |\nabla(\Psi u)|^2 dx + R^{-2} \int_{Q_{2R} - \bar{Q}_{R/2}} |u|^2 dx \right]$$

we obtain a variant of (14), in which now the term $\int_{Q_{2R} - \bar{Q}_{R/2}} \Psi^2 |\varepsilon^D(u)|^2 dx$ occurs on the right-hand side. Proceeding as before we get in place of (15)

$$(19) \quad \int_{Q_R} \omega dx + \int_{Q_R} |\nabla(\operatorname{div} u)|^2 dx \\ \leq c \left[R^{-4} \int_{Q_{2R} - \bar{Q}_{R/2}} |u|^2 dx + R^{-2} \delta \int_{Q_{2R} - \bar{Q}_{R/2}} \omega dx \right. \\ \left. + R^{-3} \int_{Q_{2R} - \bar{Q}_{R/2}} |u| |\varepsilon^D(u)| dx + R^{-2} \delta^{-1} \int_{Q_{2R} - \bar{Q}_{R/2}} |u|^2 (1 + |\varepsilon^D(u)|) dx \right].$$

Let $\delta := \frac{1}{2c}R^2$. Inequality (19) then yields

$$(20) \quad \int_{Q_R} \omega dx + \int_{Q_R} |\nabla(\operatorname{div} u)|^2 dx \leq \frac{1}{2} \int_{Q_{2R} - \bar{Q}_{R/2}} \omega dx \\ + c \left[\Theta^2(R/2) + \Theta(R/2)R^{-2} \int_{Q_{2R}} |\varepsilon^D(u)| dx \right. \\ \left. + \Theta^2(R/2)R^{-2} \int_{Q_{2R}} (1 + |\varepsilon^D(u)|) dx \right],$$

and if we use (17) and (18) together with the hypothesis that $\lim_{R \rightarrow \infty} \Theta(R) = 0$, estimate (20) implies after passing to the limit $R \rightarrow \infty$ that ω as well as $\nabla(\operatorname{div} u)$ must vanish, thus $\nabla \varepsilon(u) \equiv 0$. But then it holds $\nabla^2 u \equiv 0$, which means that u is affine and thereby constant on account of our assumption (7). This completes the proof of Theorem 1.

For **proving Theorem 2** we observe that boundedness of $|\nabla u|$ implies the estimate

$$|u(x)| \leq cR, \quad x \in Q_{2R},$$

provided $R \geq 1$. Using this information we again arrive at inequality (18), and this estimate can be restated in the form (recall (1) and (2))

$$\int_{\mathbb{R}^2} D^2 G(\varepsilon(u))(\partial_\alpha \varepsilon(u), \partial_\alpha \varepsilon(u)) \, dx < \infty.$$

Note that this is also a direct consequence of estimate (13). Using $|\nabla^2 u| \leq c|\nabla \varepsilon(u)|$ together with the boundedness of $\varepsilon(u)$ we get

$$(21) \quad \int_{\mathbb{R}^2} |\nabla^2 u|^2 \, dx < \infty.$$

Similar to equation (12) it holds ($\alpha = 1, 2$)

$$0 = \int_{Q_{2R}} D^2 G(\varepsilon(u))(\partial_\alpha \varepsilon(u), \varepsilon(\varphi)) \, dx,$$

and we may choose $\varphi = \eta^2 \partial_\alpha u$ with $\eta \in C_0^1(Q_{2R})$ such that $\eta = 1$ on Q_R , $0 \leq \eta \leq 1$ and $|\nabla \eta| \leq c/R$. We get

$$\begin{aligned} & \int_{Q_{2R}} D^2 G(\varepsilon(u))(\partial_\alpha \varepsilon(u), \partial_\alpha \varepsilon(u)) \eta^2 \, dx \\ &= -2 \int_{Q_{2R} - \overline{Q}_R} D^2 G(\varepsilon(u))(\partial_\alpha \varepsilon(u), \nabla \eta \otimes \partial_\alpha u) \eta \, dx, \end{aligned}$$

and the boundedness of $\varepsilon(u)$ yields (recall $|\nabla^2 u| \leq c|\nabla \varepsilon(u)|$)

$$\begin{aligned} \int_{Q_R} |\nabla^2 u|^2 \, dx &\leq cR^{-1} \int_{Q_{2R} - \overline{Q}_R} |\nabla^2 u| |\nabla u| \, dx \\ &\leq cR^{-1} \left(\int_{Q_{2R} - \overline{Q}_R} |\nabla^2 u|^2 \, dx \right)^{1/2} \left(\int_{Q_{2R} - \overline{Q}_R} |\nabla u|^2 \, dx \right)^{1/2}, \end{aligned}$$

hence by the boundedness of the gradient

$$(22) \quad \int_{Q_R} |\nabla^2 u|^2 \, dx \leq c \left(\int_{Q_{2R} - \overline{Q}_R} |\nabla^2 u|^2 \, dx \right)^{1/2}.$$

On account of (21) the right-hand side of (22) vanishes as $R \rightarrow \infty$, thus $\nabla^2 u \equiv 0$, which proves Theorem 2. \square

Let us finally discuss the **proof of Theorem 3**. As remarked in the beginning of the proof of Theorem 2 the growth condition imposed now on u is still sufficient to get

$$(23) \quad \int_{\mathbb{R}^2} D^2 G(\varepsilon(u)) (\partial_\alpha \varepsilon(u), \partial_\alpha \varepsilon(u)) dx < \infty.$$

We return to equation (12) choosing $x_0 = 0$, $R \geq 1$, and select η as done after (12). The Cauchy-Schwarz inequality together with Hölder's estimate implies $(\xi_\alpha := \partial_\alpha u \otimes \nabla \eta^2)$

$$\begin{aligned} & \int_{Q_R} D^2 G(\varepsilon(u)) (\partial_\alpha \varepsilon(u), \partial_\alpha \varepsilon(u)) dx \\ &= \int_{Q_R} \omega dx + \int_{Q_R} |\nabla(\operatorname{div} u)|^2 dx \\ &\leq c \left[\left(\int_{Q_{\frac{3}{2}R} - \bar{Q}_R} \omega dx \right)^{1/2} \left(\int_{Q_{\frac{3}{2}R} - \bar{Q}_R} D^2 H(\varepsilon^D(u)) (\xi_\alpha^D, \xi_\alpha^D) dx \right)^{1/2} \right. \\ &\quad \left. + \left(\int_{Q_{\frac{3}{2}R} - \bar{Q}_R} |\nabla(\operatorname{div} u)|^2 dx \right)^{1/2} \left(\int_{Q_{\frac{3}{2}R} - \bar{Q}_R} |\nabla u|^2 |\nabla \eta|^2 dx \right)^{1/2} \right], \end{aligned}$$

hence we find

$$(24) \quad \int_{Q_R} \omega dx + \int_{Q_R} |\nabla(\operatorname{div} u)|^2 dx \leq cR^{-1} \left(\int_{Q_{\frac{3}{2}R} - \bar{Q}_R} |\nabla u|^2 dx \right)^{1/2} \left\{ \int_{Q_{\frac{3}{2}R} - \bar{Q}_R} \omega dx + \int_{Q_{\frac{3}{2}R} - \bar{Q}_R} |\nabla(\operatorname{div} u)|^2 dx \right\}^{1/2},$$

and with (23) and (24) our claim will follow by letting $R \rightarrow \infty$ as soon as we can show

$$(25) \quad \int_{Q_R} |\nabla u|^2 dx \leq cR^2$$

for all $R \geq 1$. For proving (25) we recall that by (14) it holds

$$(26) \quad \int_{Q_{\frac{3}{2}R}} |\nabla u|^2 dx \leq c \left\{ \int_{Q_{2R}} \Psi^2 |\varepsilon^D(u)|^2 dx + R^{-2} \int_{Q_{2R} - \bar{Q}_{\frac{3}{2}R}} |u|^2 dx \right\}$$

with Ψ defined after (13), and from (26) in combination with our growth assumption imposed on u we infer that it remains to bound the quantity $\int_{Q_{2R}} \Psi^2 |\varepsilon^D(u)|^2 dx$ in terms

of R^2 . Proceeding as done after inequality (14) we find

$$\begin{aligned} \int_{Q_{2R}} \Psi^2 |\varepsilon^D(u)|^2 dx &\leq c \left\{ \int_{Q_{2R}} |\nabla \Psi^2| |u| |\varepsilon^D(u)| dx \right. \\ &\quad \left. + \int_{Q_{2R}} \Psi^2 |u| |\nabla \varepsilon^D(u)| dx \right\} \\ &\leq c \left\{ \frac{1}{R} \int_{Q_{2R}} |u| |\varepsilon^D(u)| dx + \left(\int_{Q_{2R}} \frac{|\nabla \varepsilon^D(u)|^2}{1 + |\varepsilon^D(u)|} dx \right)^{1/2} \right. \\ &\quad \left. \cdot \left(\int_{Q_{2R}} |u|^2 (1 + |\varepsilon^D(u)|) dx \right)^{1/2} \right\}. \end{aligned}$$

On Q_{2R} it holds $|u(x)| \leq cR$, hence

$$(27) \quad \int_{Q_{2R}} \Psi^2 |\varepsilon^D(u)|^2 dx \leq c \left\{ \int_{Q_{2R}} |\varepsilon^D(u)| dx + R \left(\int_{Q_{2R}} (1 + |\varepsilon^D(u)|) dx \right)^{1/2} \right\},$$

where we also made use of (23) to bound the term involving $\nabla \varepsilon^D(u)$. The discussion following inequality (16) shows

$$(28) \quad \int_{Q_{2R}} |\varepsilon^D(u)| dx \leq cR \left(\int_{Q_{2R}} H(\varepsilon^D(u)) dx \right)^{1/2} + \frac{1}{\ln 2} \int_{Q_{2R}} H(\varepsilon^D(u)) dx,$$

and if we go back to estimate (10) (being valid without any growth hypothesis imposed on u) we find that now this inequality yields

$$(29) \quad \int_{Q_{2R}} H(\varepsilon^D(u)) dx \leq cR^2.$$

Finally, we combine the inequalities (28) and (29) with the result that

$$(30) \quad \int_{Q_{2R}} |\varepsilon^D(u)| dx \leq cR^2,$$

and we see that (27) and (30) imply the correct bound for $\int_{Q_{2R}} \Psi^2 |\varepsilon^D(u)|^2 dx$. Thus we have established (25) and the proof of Theorem 3 is complete. \square

REMARK 5. We leave it to the reader to discuss Theorem 1, 2 and 3 for nonlinear Hencky materials, which means that the energy density from equation (1) is replaced by

$$W(\varepsilon) := \Phi(|\varepsilon^D|) + \frac{1}{2}(\text{tr } \varepsilon)^2$$

for a “general” N -function Φ (compare, e.g. [Ad] for a definition). We refer to the article [BF], where one will find natural hypotheses to be imposed on Φ under which one can expect a Liouville-type result.

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