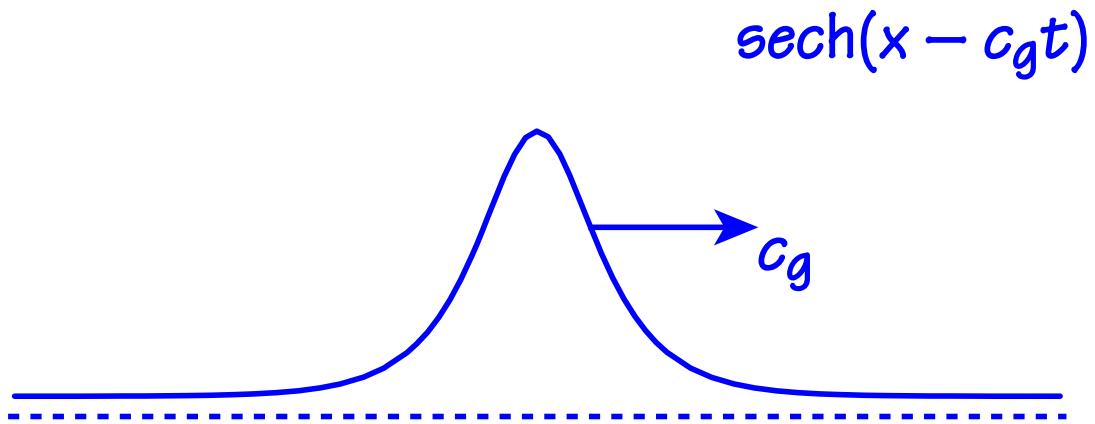
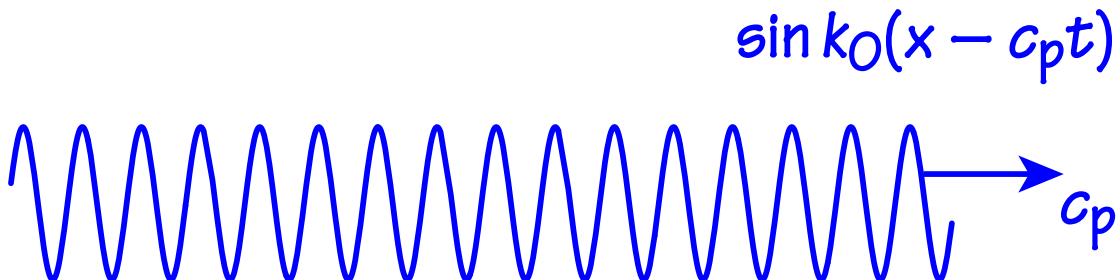


MODULATING PULSES

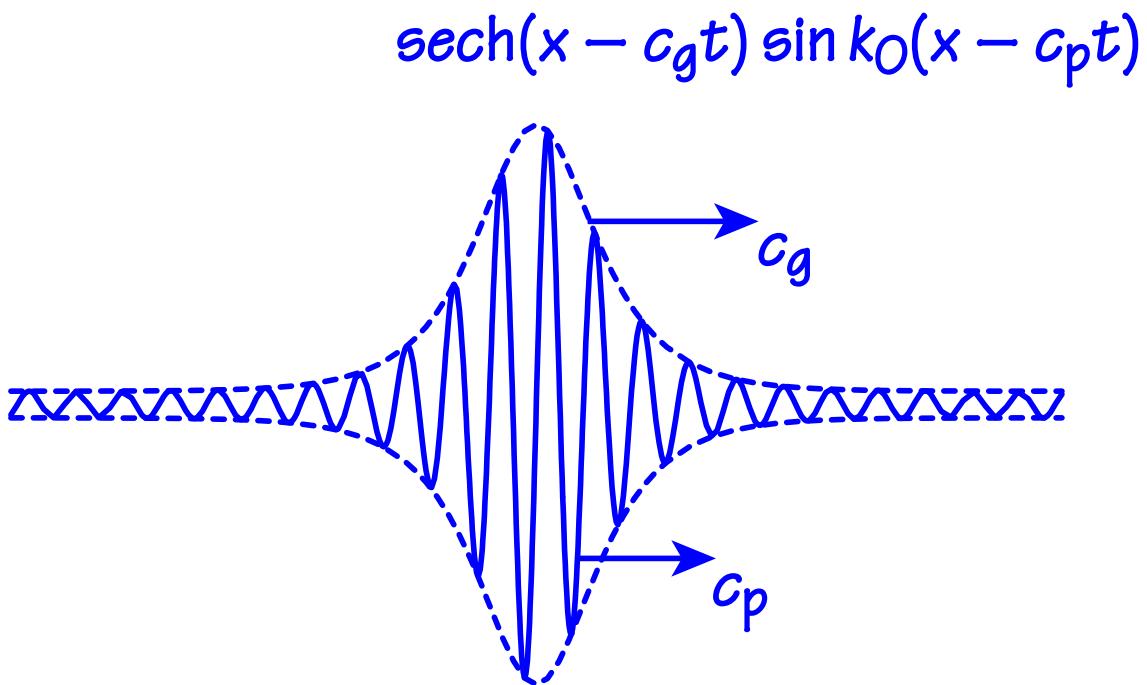
A pulse:



A wavetrain:



A modulating pulse:



WAVE EQUATIONS

We study the equation

$$\partial_t^2 u = \partial_x^2 u - u + f_1(u, \partial_x u, \partial_t u) \partial_x^2 u + f_2(u, \partial_x u, \partial_t u),$$

where

- f_1, f_2 are analytic
- $f_i(a, -b, -c) = f_i(a, b, c), \quad i = 1, 2$

Linear dispersion relation for $\sin k(x - c'_p t)$:

$$c'_p = (1 + k^2)^{1/2} / k$$

$$c'_g = \frac{d}{dk}(k c'_p) = \frac{1}{c'_p}$$

We look for modulating pulse solutions of the form

$$u(x, t) = v_1(x - c_g t, k_0(x - c_p t)),$$

“ $\operatorname{sech}(x - c_g t) \sin k_0(x - c_p t)$ ”

where

- $v_1(\xi, \eta)$ is 2π -periodic in η
- $c_p = c'_p + \gamma_1 \varepsilon^2, \quad 0 < \varepsilon \ll 1$
- $c_g = 1/c_p$

SPATIAL DYNAMICS

We formulate the equation as a system for

$$v = (v_1, v_2), \quad v_2 = \partial_\xi v_1,$$

so that

$$\partial_\xi v_1 = v_2,$$

$$\begin{aligned} \partial_\xi v_2 &= -c_3^\varepsilon k_0^2 \partial_\eta^2 v_1 - c_4^\varepsilon v_1 \\ &\quad + g_0^\varepsilon(v) \partial_\eta^2 v_1 + g_1^\varepsilon(v) + g_2^\varepsilon(v) \partial_\eta v_2, \end{aligned}$$

where

$$g_j^\varepsilon(v) = g_j^\varepsilon(v_1, \partial_\eta v_1, v_2), \quad j = 1, 2, 3.$$

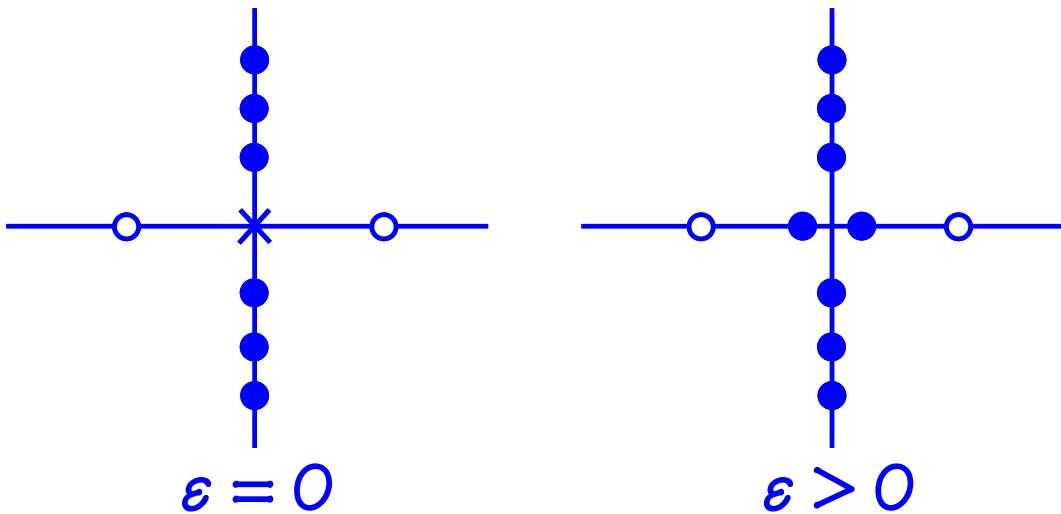
Phase space:

- $X^s = H_{\text{per}}^{s+1}(0, 2\pi) \times H_{\text{per}}^s(0, 2\pi)$, $s > 0$
- The vector field has domain X^{s+1}
- $g_0^\varepsilon, g_1^\varepsilon, g_2^\varepsilon$ are bounded $X^s \rightarrow H_{\text{per}}^s(0, 2\pi)$

Reversibility:

- The system is invariant under
 - $\xi \mapsto -\xi, \quad (v_1, v_2) \mapsto S(v_1, v_2),$
 - $S(v_1(\eta), v_2(\eta)) = (v_1(-\eta), -v_2(-\eta))$
- Symmetric solutions are invariant under this transformation

SPECTRAL ANALYSIS



- Infinitely many imaginary eigenvalues $\pm i\omega_m, \omega_m \sim m$

Notation:

$$z = P_{wh}(v), \quad q = P_{sh,c}(v)$$

Write as a coupled system

$$\partial_\xi z = Kz + F^\varepsilon(z, q), \quad K = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

and

$$\partial_\xi q_1 = q_2, \quad = g_3^\varepsilon(z, q) + h^\varepsilon(z)$$

$$\begin{aligned} \partial_\xi q_2 = & -c_3^\varepsilon k_0^2 \partial_\eta^2 q_1 - c_4^\varepsilon q_1 + \underbrace{P_{sh,c}(g_1^\varepsilon(z, q))}_{+ P_{sh,c}(g_0^\varepsilon(z, q) \partial_\eta^2 q_1) + P_{sh,c}(g_2^\varepsilon(z, q) \partial_\eta q_2)}, \end{aligned}$$

where $g_3^\varepsilon(z, 0) = 0$.

A SIMPLIFIED PROBLEM

- $h^\varepsilon(z) = 0 \Rightarrow \{q = 0\}$ is invariant
- The flow in $\{q=0\}$ is controlled by the fourth-order equation

$$\partial_\xi z = Kz + \underbrace{F^\varepsilon(z, 0)}_{\text{cubic}},$$

Use scaled variables:

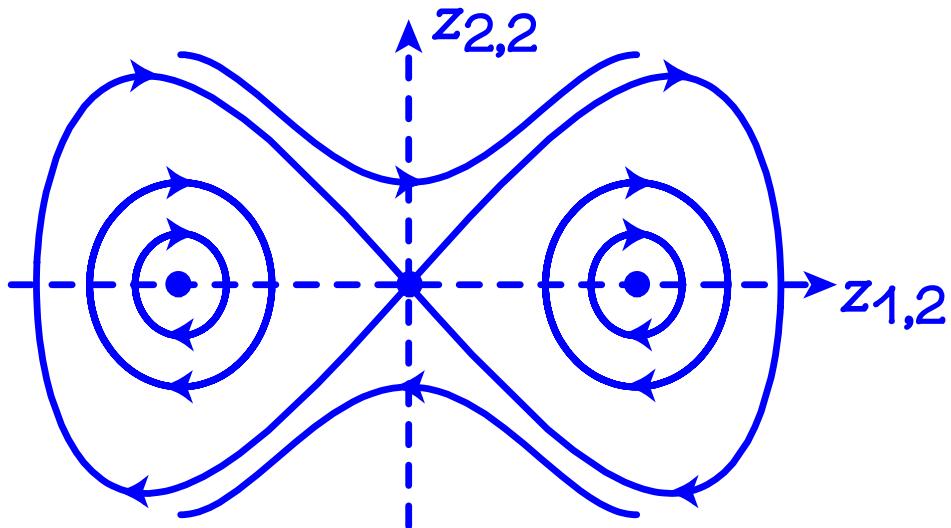
$$\partial_\xi z_{1,1} = z_{2,1},$$

$$\partial_\xi z_{2,1} = C_1 z_{1,1} - C_2 z_{1,1}(z_{1,1}^2 + z_{1,2}^2) + O(\varepsilon),$$

$$\partial_\xi z_{1,2} = z_{2,2},$$

$$\partial_\xi z_{2,2} = C_1 z_{1,2} - C_2 z_{1,2}(z_{1,1}^2 + z_{1,2}^2) + O(\varepsilon)$$

For $\varepsilon = 0$ we have a two-dimensional invariant plane containing two symmetric homoclinics:



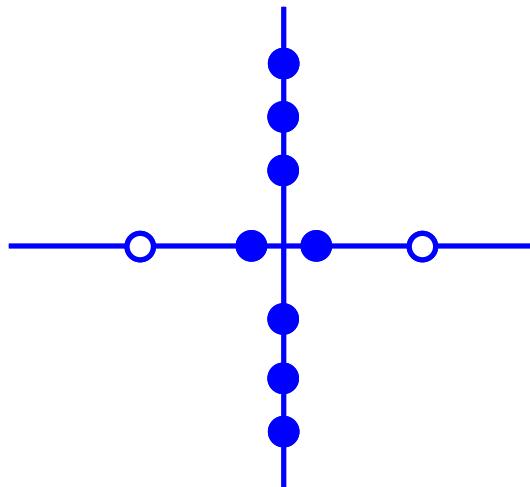
Two symmetric homoclinics p^ε persist for $\varepsilon > 0$ and are estimated by

$$|p^\varepsilon(\xi)| \leq c\varepsilon e^{-\varepsilon|\xi|}$$

A NONEXISTENCE RESULT

The homoclinics found in $\{q = 0\}$ generically do not persist for $h^\varepsilon(z) \neq 0$

- Dynamical systems arguments:



Three-dimensional
stable and unstable
manifolds

The manifolds generically do not intersect in an infinite-dimensional phase space

- Global existence theory for one-dimensional quadratic, quasilinear wave equations?

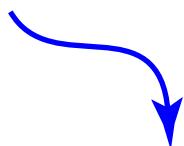
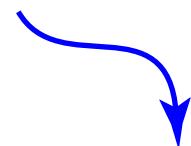
Use a change of variable to make $h^\varepsilon(z)$ ‘small’

Prepare: The scaling $\varepsilon = \mu^2$ and

$$(z'_1, z'_2, q'_1, q'_2) = (\mu^{-1}z_1, \mu^{-3}z_2, \mu^{-2}q_1, \mu^{-2}q_2)$$

yields

$$\partial_\xi z = Kz + F^\varepsilon(z, q), \quad |p^\varepsilon(\xi)| \leq c\varepsilon e^{-\varepsilon|\xi|}$$



$$\partial_\xi z' = F^\mu(z', q'), \quad |p^\mu(\xi)| \leq c\mu e^{-\mu^2|\xi|}$$

NORMAL-FORM THEORY

$$\partial_\xi z = F^\mu(z, q),$$

$$\partial_\xi q_1 = q_2 + g_6^\mu(z, q) + h_1^\mu(z),$$

$$\begin{aligned} \partial_\xi q_2 = & -c_3^\mu k_0^2 \partial_\eta^2 q_1 - c_4^\mu q_1 + g_4^\mu(z, q) + h_2^\mu(z) \\ & + P_{\text{sh},c}(g_3^\mu(z, q) \partial_\eta^2 q_1) + P_{\text{sh},c}(g_3^\mu(z, q) \partial_\eta q_2) \end{aligned}$$

Try to eliminate the term $h^n(z, \mu)$ by substituting

$$\tilde{q} = q + \Phi^n(z, \mu)$$

Homological equation:

$$L^n \Phi^n(z, \mu) = h^n(z, \mu),$$

$$L^n \begin{pmatrix} \Phi_{1,k}^n \\ \Phi_{2,k}^n \end{pmatrix} z^i \mu^j = \begin{pmatrix} 0 & 1 \\ \omega_k^2 & 0 \end{pmatrix} \begin{pmatrix} \Phi_{1,k}^n \\ \Phi_{2,k}^n \end{pmatrix} z^i \mu^j, \quad i + j = n$$

This equation can always be solved:

- $\Phi^n = (L^n)^{-1} h^n$
- $\|(L^n)^{-1}\| \leq a$
- Gain of one derivative

The change of variable preserves the structure, and there is an optimal choice of n such that

$$\|h^\mu(z)\| \leq c\mu^2 e^{-c^*/\mu}$$

CENTRE-STABLE MANIFOLD

We look for solutions of the form

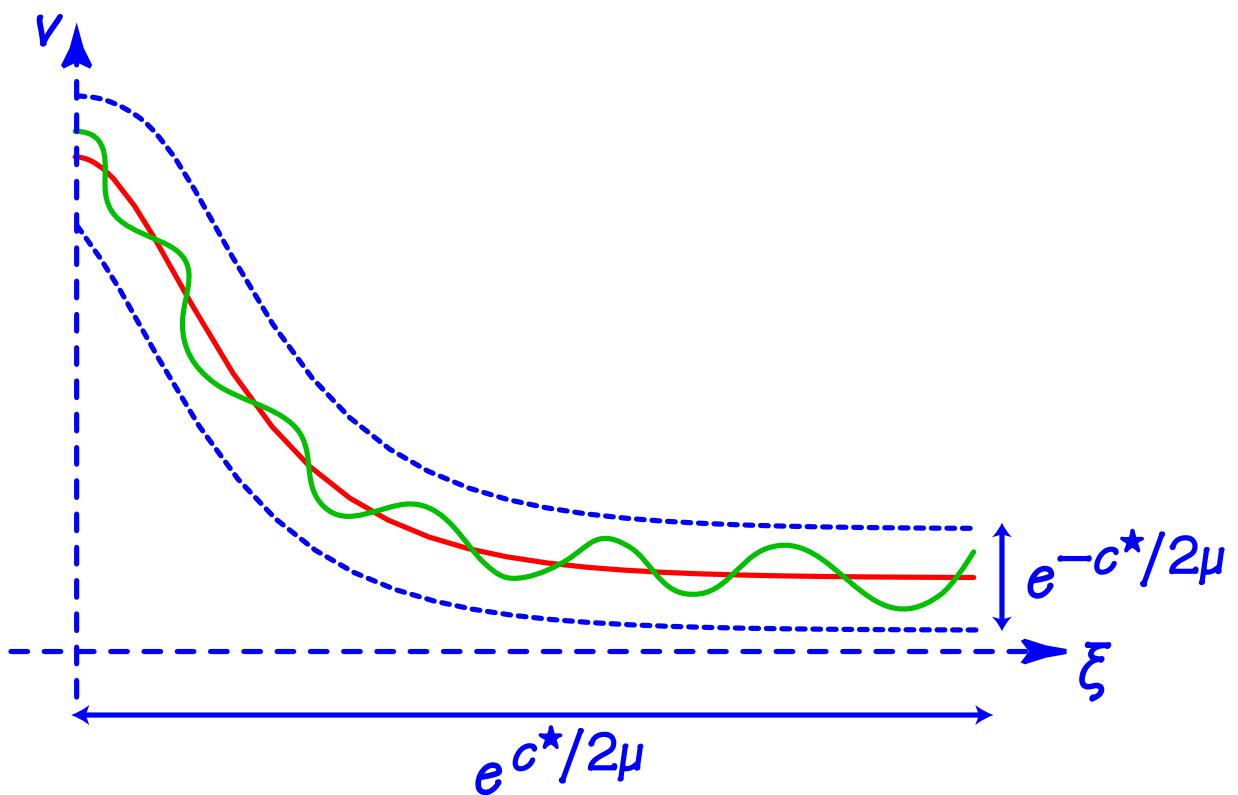
$$(z, q) = (p^\mu + Z, q), \quad (Z, q) \in C([0, e^{c^*/2\mu}], X^{s+1})$$

with

$$\|(Z(\xi), q(\xi))\| \leq e^{-c^*/2\mu}$$

Combine

- Dynamical-systems arguments
- Kato's iteration scheme



“Centre-stable manifold”:

- Define $W^{cs} = \{v(0) \text{ for such solutions } v\}$
- W^{cs} is given as a graph $v_u(O) = f(v_s(O), v_c(O))$

EXISTENCE THEORY

Consider

$$\begin{aligned}\partial_\xi w_1 &= w_2, \\ \partial_\xi w_2 &= -c_3^\mu k_0^2 \partial_\eta^2 w_1 - c_4^\mu w_1 \\ &\quad + \mu P_c((w_1 + \mu e^{-\mu^2 \xi}) \partial_\eta w_2) + h^\mu\end{aligned}$$

in the phase space $P_c X^s$.

We show that this system has a unique solution $w \in C([0, e^{c^*}/2\mu], P_c X^{s+1})$, with

$$\|w(\xi)\| \leq e^{-c^*/2\mu}, \quad \xi \in [0, e^{c^*}/2\mu].$$

- Use the Kato iteration scheme

$$\begin{aligned}\partial_\xi w_{2(m+1)} &= w_{2(m+1)}, \\ \partial_\xi w_{2(m+1)} &= -c_3^\mu k_0^2 \partial_\eta^2 w_{1(m+1)} - c_4^\mu w_{1(m+1)} \\ &\quad + \mu P_c((w_{1(m)} + \mu e^{-\mu^2 \xi}) \partial_\eta w_{2(m+1)}) + h^\mu\end{aligned}$$

with $(w_{1(0)}, w_{2(0)}) = (0, 0)$ and initial data

$$(w_{1(m+1)}(0), w_{2(m+1)}(0)) = (w_1^0, w_2^0)$$

- Show that

$$\|w_{(m)}(\xi)\| \leq e^{-c^*/2\mu} \Rightarrow \|w_{(m+1)}(\xi)\| \leq e^{-c^*/2\mu},$$

$$\|w_{(m+1)}(\xi) - w_{(m)}(\xi)\| \leq \frac{1}{2} \|w_{(m)}(\xi) - w_{(m-1)}(\xi)\|$$

for $\xi \in [0, e^{c^*}/2\mu]$.

EXISTENCE THEORY

$$\partial_\xi w_{2(m+1)} = w_{2(m+1)},$$

$$\partial_\xi w_{2(m+1)} = -c_3^\mu k_0^2 \partial_\eta^2 w_{1(m+1)} - c_4^\mu w_{1(m+1)}$$

$$+ \mu P_c((w_{1(m)} + \mu^2 e^{-\mu^2 \xi}) \partial_\eta w_{2(m+1)}) + h^\mu$$

Define

$$E(w) = \int \{(\partial_\eta^{s+1} w_2)^2 - c_3^\mu k_0^2 (\partial_\eta^{s+2} w_1)^2 + c_4^\mu (\partial_\eta^{s+1} w_1)^2\} d\eta$$

- $E(w)^{1/2}$ is the norm on $P_c X_{s+1}$
- Show that

$$\|w_{(m)}(\xi)\| \leq e^{-c^*/2\mu} \Rightarrow \|w_{(m+1)}(\xi)\| \leq e^{-c^*/2\mu}$$

Apply $\partial_\eta^{s+1} w_{2(m+1)} \partial_\eta^{s+1}$ to the second equation and integrate with respect to η :

$$\begin{aligned} \partial_\xi E(w_{(m+1)}) &\leq c\mu e^{-c^*/\mu} E(w_{(m+1)})^{1/2} \\ &\quad + c\mu(e^{-c^*/2\mu} + \mu^2 e^{-\mu^2 \xi}) E(w_{(m+1)}) \end{aligned}$$

Integration yields

$$\begin{aligned} &\sup_{\xi \in [0, e^{c^*/2\mu}]} E(w_{(m+1)}(\xi)) \\ &\leq E(w_{(m+1)}(0)) + c\mu e^{-c^*/\mu} + c\mu \sup_{\xi \in [0, e^{c^*/2\mu}]} E(w_{(m+1)}(\xi)) \end{aligned}$$

and hence

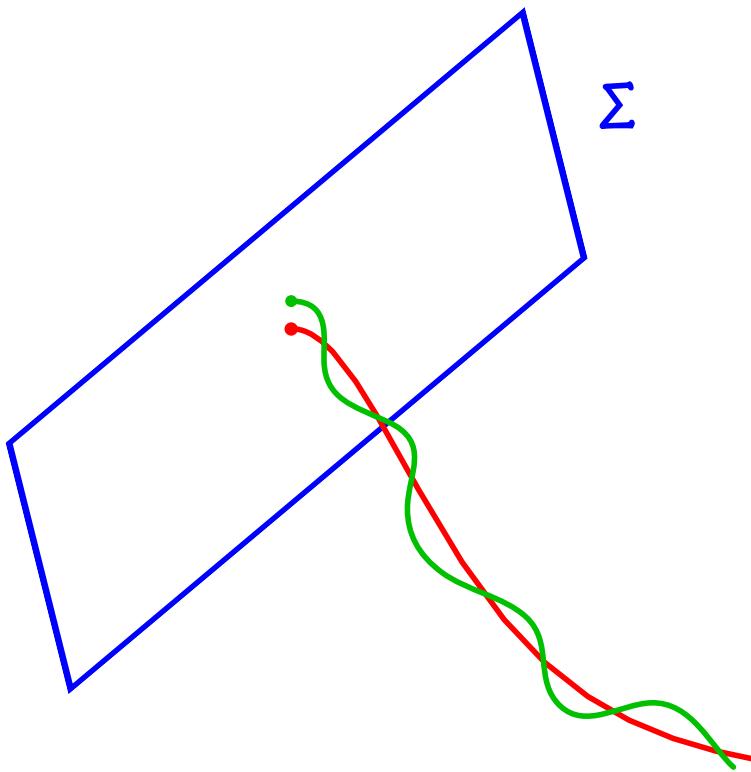
$$\sup_{\xi \in [0, e^{c^*/2\mu}]} E(w_{(m+1)}(\xi)) \leq e^{-c^*/\mu}.$$

SYMMETRIC PULSES

- Define the “symmetric section” $\Sigma = \text{Fix } S$
- A solution $v(\xi)$ on $[0, e^{c^*/2\mu}]$ with $v(0) \in \Sigma$ can be extended to a symmetric solution

$$\tilde{v}(\xi) = \begin{cases} v(\xi), & \xi \geq 0 \\ Sv(-\xi), & \xi < 0 \end{cases}$$

on $[-e^{c^*/2\mu}, e^{c^*/2\mu}]$.



- Solve

$$(I - S)v(0) = 0, \quad v(0) \in W^{cs}$$

perturbatively around $p^\mu(0)$.

- W^{cs} intersects Σ in an infinite family of points (parameterised by $P_c(I - S)v(0)$)