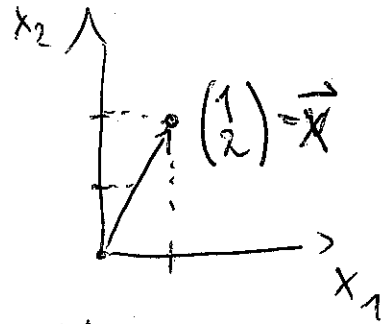


# Vektorrechnung

$$\vec{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \in \mathbb{R}^n \quad x_i \in \mathbb{R}$$

Vektor / n-Tupel  
vector / n-tuple

$\mathbb{R}^2$  Ebene plane



$\mathbb{R}^3$  Raum space



Vektoraddition  
vector addition

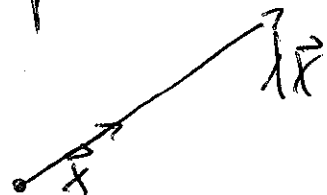
$$\begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} + \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix} = \begin{pmatrix} x_1 + y_1 \\ \vdots \\ x_n + y_n \end{pmatrix}$$



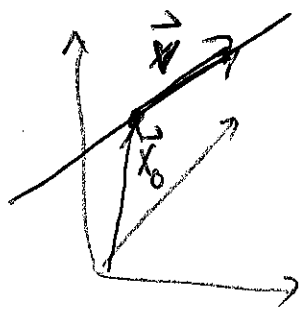
Skalarmultiplikation

scalar multiplication

$$\lambda \cdot \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} \lambda x_1 \\ \vdots \\ \lambda x_n \end{pmatrix}$$



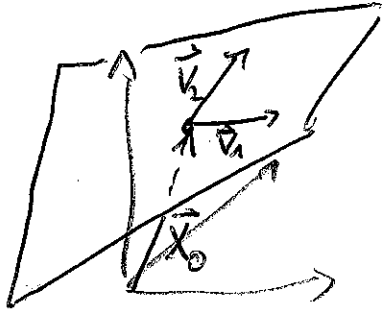
Geraden  
gleichung  
Equation of  
a line



$$\vec{x}(t) = \vec{x}_0 + t \vec{v}$$

Aufpunkt base point    Parameter parameter    Richtung vekt direction vec

Ebenen-  
gleichung  
Equation of a  
plane

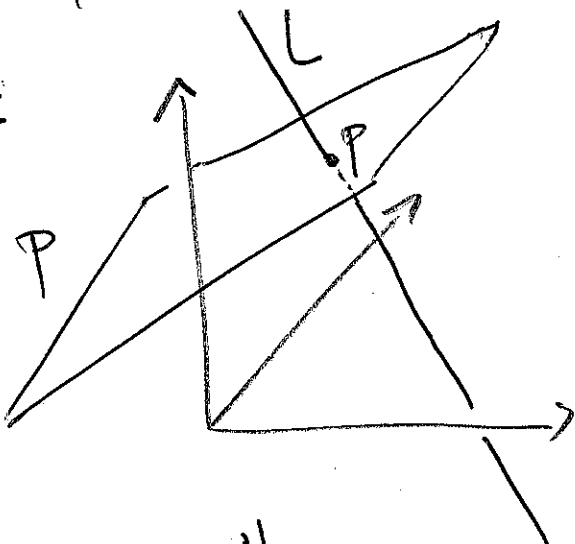


$$\vec{x}(\lambda, \mu) = \vec{x}_0 + \lambda_1 \vec{v}_1 + \lambda_2 \vec{v}_2$$

2 Parameter

Schnittpunkte intersection points

~~Bsp~~



$$P \cap L = \{p\}$$

$P = ?$

→ lineares Gleichungssystem  
linear sys. of equations

Bsp:

$$P = \left\{ \vec{x} = \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix} + \lambda_1 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + \lambda_2 \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix} \right\}$$

$$L = \left\{ \vec{x} = \begin{pmatrix} 4 \\ 1 \\ 0 \end{pmatrix} + \mu \begin{pmatrix} -1 \\ -1 \\ 3 \end{pmatrix} \right\}$$

Search with  
Suchen  $\lambda_1, \lambda_2, \mu$  mit  $\vec{x}(\lambda_1, \lambda_2) = \vec{x}(\mu)$

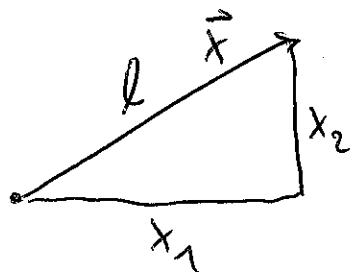
3

$$\begin{aligned} \Rightarrow \quad 2\lambda_2 + \mu &= 4 \\ \lambda_1 + \mu &= 1 \\ \lambda_2 - 3\mu &= -2 \end{aligned} \quad \text{Lösen!}$$

Länge / Norm  
 Length ~~Abstand~~  
~~distance~~

$$\|\vec{x}\| = \sqrt{x_1^2 + \dots + x_n^2}$$

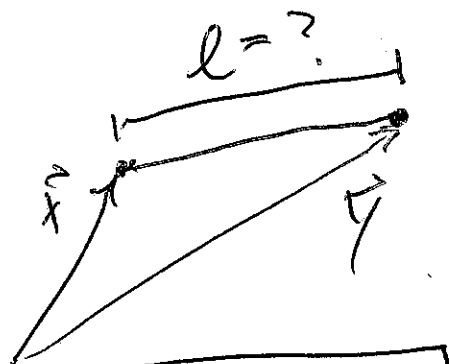
Idee: Satz v. Pythagoras



$$l^2 = x_1^2 + x_2^2$$

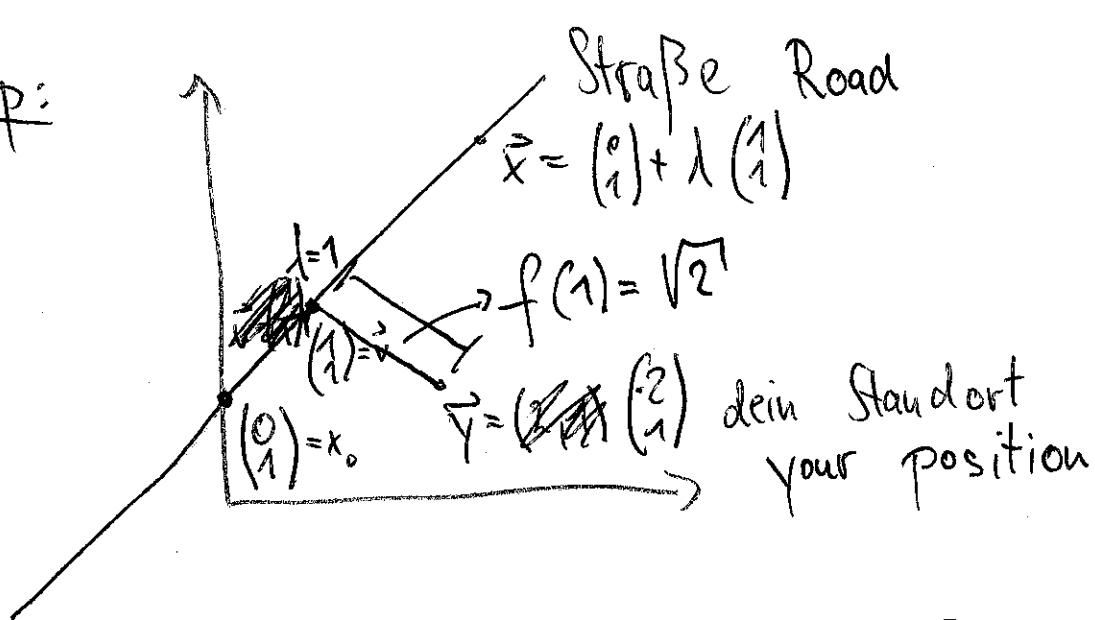
Abstand distance

zwischen  $\vec{x}$  und  $\vec{y}$   
 between



$$d(\vec{x}, \vec{y}) = \|\vec{y} - \vec{x}\| = \sqrt{(y_1 - x_1)^2 + \dots + (y_n - x_n)^2}$$

Bsp:



Frage: Entfernung zu Straße?  
Distance to Road?

Antwort:

$$f(\lambda) = d(\vec{x}(\lambda), \vec{y}) = \sqrt{(\lambda-2)^2 + \lambda^2}$$
$$= \left\| \begin{pmatrix} \lambda-2 \\ \lambda \end{pmatrix} \right\| = \sqrt{(\lambda-2)^2 + \lambda^2}$$
$$= \sqrt{2\lambda^2 - 4\lambda + 4}$$

$g(\lambda)$

Suchen Minimum von  $f(\lambda) \hat{=}$  Minimum von  $g(\lambda)$   
Search " of " " of

Ableitung  
derivative

$$g(\lambda) = g'(\lambda) = 4\lambda - 4 \stackrel{!}{=} 0$$
$$\Rightarrow \lambda = 1$$

$$\Rightarrow f(1) = \sqrt{2} \hat{=} \text{Entfernung zur Straße}$$

oder mit  
Skalarprodukt  
Scalar product

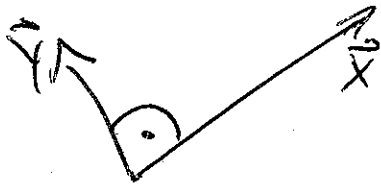
$$\vec{x} \cdot \vec{y} = x_1 y_1 + \dots + x_n y_n \in \mathbb{R}$$

Spezialfälle:

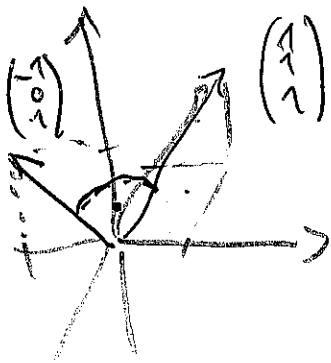
1)  $\vec{x} = \vec{y}$  :

$$\vec{x} \cdot \vec{x} = \|\vec{x}\|^2$$

2)  $\vec{x} \perp \vec{y}$ ,  $\vec{x}$  und  $\vec{y}$  sind orthogonal  
are orthogonal



$$\vec{x} \cdot \vec{y} = 0$$

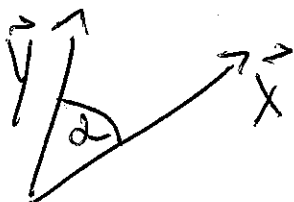


$$\begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = -1 + 1 = 0$$

$\Leftrightarrow$

allgemein:

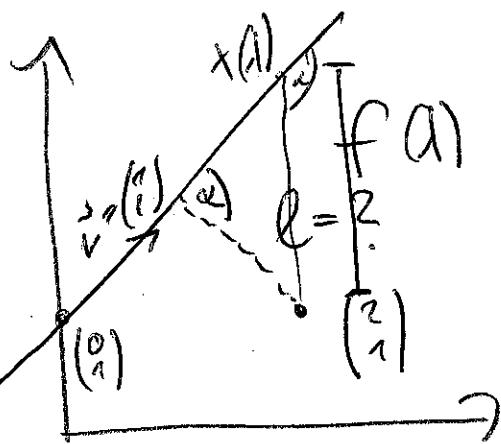
$$\vec{x} \cdot \vec{y} = \cos(\alpha) \cdot \|\vec{x}\| \cdot \|\vec{y}\|$$



1)  $\alpha = 0^\circ$      $\cos(\alpha) = 1$

2)  $\alpha = 90^\circ$      $\cos(\alpha) = 0$

nochmal BSP:

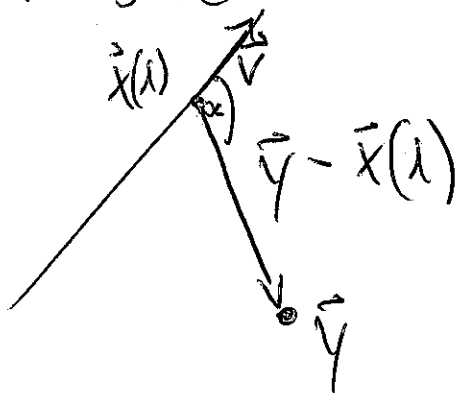


Suche  $l = \hat{=}$  Entfernung zur Straße

Idee: Betrachte Winkel  $\alpha$ .

Idea:  $f$  minimal  $\Leftrightarrow \alpha = 90^\circ$

$\Rightarrow$  Suchen  $\lambda$  mit  $\vec{y} - \vec{x}(\lambda) \perp \vec{v}$



$$(\vec{y} - \vec{x}(\lambda)) \cdot \vec{v} = \begin{pmatrix} 2-\lambda \\ -\lambda \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 1 \end{pmatrix} = 2-\lambda-\lambda = 2-2\lambda \stackrel{!}{=} 0$$

$$\Rightarrow \lambda = 1 \dots$$

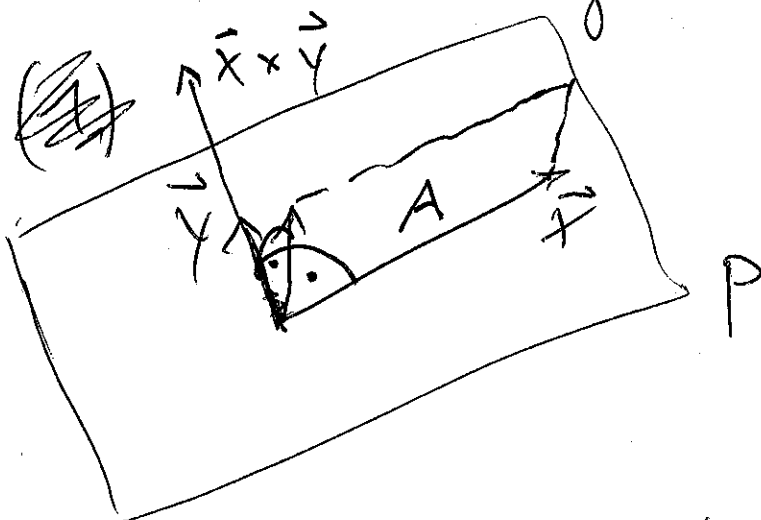
Kreuzprodukt  
cross product

(NUR IM  $\mathbb{R}^3$ )  
ONLY IN  $\mathbb{R}^3$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \times \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} x_2 y_3 - x_3 y_2 \\ x_3 y_1 - x_1 y_3 \\ x_1 y_2 - x_2 y_1 \end{pmatrix}$$

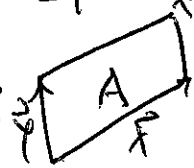
Bsp  $\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \times \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 - 0 \\ -1 - 1 \\ 0 + 1 \end{pmatrix} = \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}$

geometrische Bedeutung:  
geometrical meaning



$$A = \|\vec{x} \times \vec{y}\|$$

- 1)  $\vec{x} \times \vec{y}$  ist orthogonal zu  $\mathcal{P} = \{\lambda_1 \vec{x} + \lambda_2 \vec{y}\}$
- 2)  $\|\vec{x} \times \vec{y}\| =$  Fläche des Parallelogramms  
area of parallelogram



Beweis: Proof

nur ein Beispiel:

$(\vec{x} \times \vec{y}) \perp \vec{x}$  denn:

$$\begin{aligned} \vec{x} (\vec{x} \times \vec{y}) &= \cancel{x_2 x_1} x_2 y_3 - \cancel{x_1 x_2} x_1 y_3 \\ &+ \cancel{x_1 x_3} x_3 y_1 - \cancel{x_2 x_1} x_2 y_3 \\ &+ \cancel{x_3 x_1} x_3 y_2 - \cancel{x_3 x_2} x_3 y_1 = 0 \end{aligned}$$