

2. Spectral triples associated to manifolds | 2-1

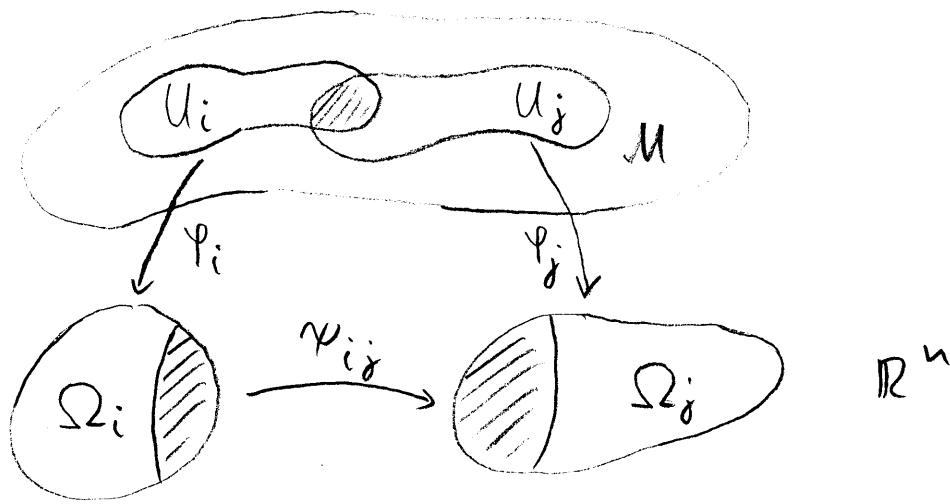
Spectral triples are (supposed to be) the right framework to extend classical differential geometry to the noncommutative world. It is however not clear offhand, how usual manifolds fit into that frame. In this chapter, we will see that indeed each compact oriented smooth manifold induces a commutative spectral triple in a natural way.

2.1. Definition (manifolds):

- (i) An n -dimensional topological manifold is a Hausdorff topological space M which is locally euclidean, i.e., each point $x \in M$ has an open neighborhood that is homeomorphic to an open subset of \mathbb{R}^n .
- (ii) A (local) chart (U, φ) of M consists of an open set $U \subseteq M$ and a homeomorphism $\varphi: U \rightarrow \Omega = \varphi(U)$ onto an open subset Ω of \mathbb{R}^n .
- (iii) A family $\mathcal{A} = \{(U_i, \varphi_i) \mid i \in I\}$ of charts satisfying $M = \bigcup_{i \in I} U_i$ is called atlas of M .

The homeomorphisms $\varphi_{ij}: \varphi_i(U_i \cap U_j) \rightarrow \varphi_j(U_i \cap U_j)$ given

by $\varphi_{ij} := \varphi_j \circ \varphi_i^{-1} \Big|_{\varphi_i(U_i \cap U_j)}$ are called transition maps.



(iv) An atlas \mathcal{A} is called smooth if all its transition maps are smooth (i.e., C^∞).

A chart (U, φ) is said to be smooth with respect to a smooth atlas \mathcal{A} if $\mathcal{A} \cup \{(U, \varphi)\}$ is again a smooth atlas.

A smooth atlas \mathcal{A} is called maximal if every chart (U, φ) that is smooth with respect to \mathcal{A} already belongs to \mathcal{A} .

Every smooth atlas \mathcal{A} induces a maximal one by $\mathcal{A}_{\max} := \{(U, \varphi) \mid (U, \varphi) \text{ chart, smooth w.r.t. } \mathcal{A}\}$.

(v) An n -dimensional smooth manifold is an n -dimensional topological manifold M with a maximal smooth atlas \mathcal{A} .

2.2 Definition (tangent space):

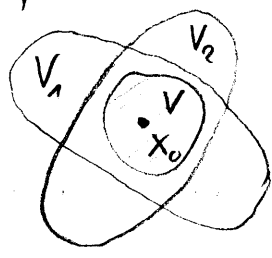
Let M be an n -dimensional smooth manifold. Fix $x_0 \in M$.

(i) A function $f : V \rightarrow \mathbb{R}$ on an open subset $V \subseteq M$ is said to be smooth if

$$f \circ \varphi^{-1} |_{\varphi(U \cap V)} : \varphi(U \cap V) \rightarrow \mathbb{R}$$

is smooth for every smooth chart (U, φ) .

(ii) On the set of all pairs (V, f) consisting of
• an open neighborhood V of x_0 and
• a smooth function $f : V \rightarrow \mathbb{R}$,



we introduce an equivalence relation \sim by

$$(V_1, f_1) \sim (V_2, f_2) : \Leftrightarrow \exists V \subseteq V_1 \cap V_2 \text{ open, } x_0 \in V; \\ f_1|_V = f_2|_V$$

The equivalence class of (V, f) , denoted by $[f]_{x_0}$, is called the germ of f at x_0 .

We denote by $C_{x_0}^\infty(M)$ the \mathbb{R} -algebra of germs at x_0

(iii) The \mathbb{R} -vector space $T_{x_0}M$ of all linear maps $\delta : C_{x_0}^\infty(M) \rightarrow \mathbb{R}$ satisfying the product rule

$$\delta([f]_{x_0} \cdot [g]_{x_0}) = \delta([f]_{x_0})g(x_0) + f(x_0)\delta([g]_{x_0})$$

for all $[f]_{x_0}, [g]_{x_0} \in C_{x_0}^\infty(M)$ is called the tangent space to M at x_0 .

2.3. Remark:

In the situation of Definition 2.2, let $\gamma : (-\varepsilon, \varepsilon) \rightarrow \mathcal{M}$ be a smooth path, i.e. γ is continuous and

$$\varphi \circ \gamma |_{\gamma^{-1}(U)} : \gamma^{-1}(U) \rightarrow \mathbb{R}^n$$

is smooth for every smooth chart (U, φ) , such that $\gamma(0) = x_0$. We call $\gamma'(0) \in T_{x_0}\mathcal{M}$ given by

$$\gamma'(0)([f]_{x_0}) := (f \circ \gamma)'(0) \quad \forall [f]_{x_0} \in C_{x_0}^\infty(\mathcal{M})$$

(the velocity vector of γ at x_0 .)

For every $\delta \in T_{x_0}\mathcal{M}$, there exists a smooth path $\gamma : (-\varepsilon, \varepsilon) \rightarrow \mathcal{M}$ such that $\gamma(0) = x_0$ and $\gamma'(0) = \delta$.

Next, we "glue" the tangent spaces, yielding the so-called tangent bundle.

2.4. Definition (topological vector bundle)

Let X be a Hausdorff topological space.

- (i) An n -dimensional (real/complex) vector bundle over X is given by a topological space E and a continuous map $\pi : E \rightarrow X$ such that
- the fibre $E_x := \pi^{-1}(\{x\})$ is a (real/complex) vector space of dimension n for each $x \in X$,

• for each $x_0 \in X$, there is an open neighborhood U of x_0 and a homeomorphism

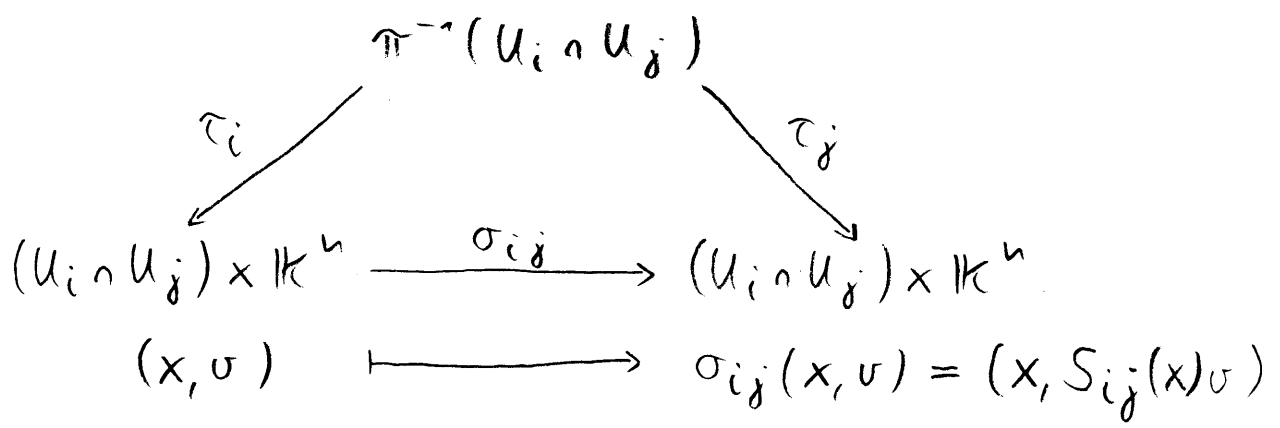
$$\tau: \pi^{-1}(U) \rightarrow U \times \mathbb{K}^n \quad (\mathbb{K} = \mathbb{R}, \mathbb{C})$$

such that $\pi|_{\pi^{-1}(U)} = \text{pr}_U \circ \tau$, where $\text{pr}_U: U \times \mathbb{K}^n \rightarrow U$ is the projection on the first component, i.e., $\text{pr}_U(x, v) = x$, and $\tau|_{E_x}: E_x \rightarrow \{x\} \times \mathbb{K}^n = \mathbb{K}^n$ is a vector space isomorphism for all $x \in U$.

We call (U, τ) a bundle chart (or local trivialization).

(ii) A family $\mathcal{A} = \{(U_i, \tau_i) \mid i \in I\}$ of bundle charts satisfying $X = \bigcup_{i \in I} U_i$ is called bundle atlas.

The transition maps $\sigma_{ij}: (U_i \cap U_j) \times \mathbb{K}^n \rightarrow (U_i \cap U_j) \times \mathbb{K}^n$ given by $\sigma_{ij} := \tau_j \circ \tau_i^{-1}|_{(U_i \cap U_j) \times \mathbb{K}^n}$ satisfy



for a continuous map $S_{ij}: U_i \cap U_j \rightarrow GL_n(\mathbb{K})$, called the transition matrices.

2.5. Definition (smooth vector bundle):

Let M be a smooth manifold. An n -dimensional smooth vector bundle over M is an n -dimensional

topological vector bundle over M with a (maximal) 2-6
 bundle atlas \mathcal{A} for which all transition maps are smooth.

2.6. Definition (tangent bundle):

Let M be an n -dimensional smooth manifold with maximal smooth atlas $\mathcal{A} = \{(U_i, \varphi_i) \mid i \in I\}$. We put

$$TM := \coprod_{x \in M} T_x M = \{(x, \delta) \mid x \in M, \delta \in T_x M\}$$

and define $\pi: TM \rightarrow M$ by $\pi(x, \delta) := x$; often, we identify (x, δ) and δ .

~ We define (candidates for) local trivializations by

$$\tau_i: \pi^{-1}(U_i) \rightarrow U_i \times \mathbb{R}^n, \quad (x, \delta) \mapsto (x, \Theta_{i,x}^{-1}(\delta))$$

$\underset{\substack{\cap \\ T_x M}}{\delta}$

with the isomorphism $\Theta_{i,x}: \mathbb{R}^n \rightarrow T_x M$ given by

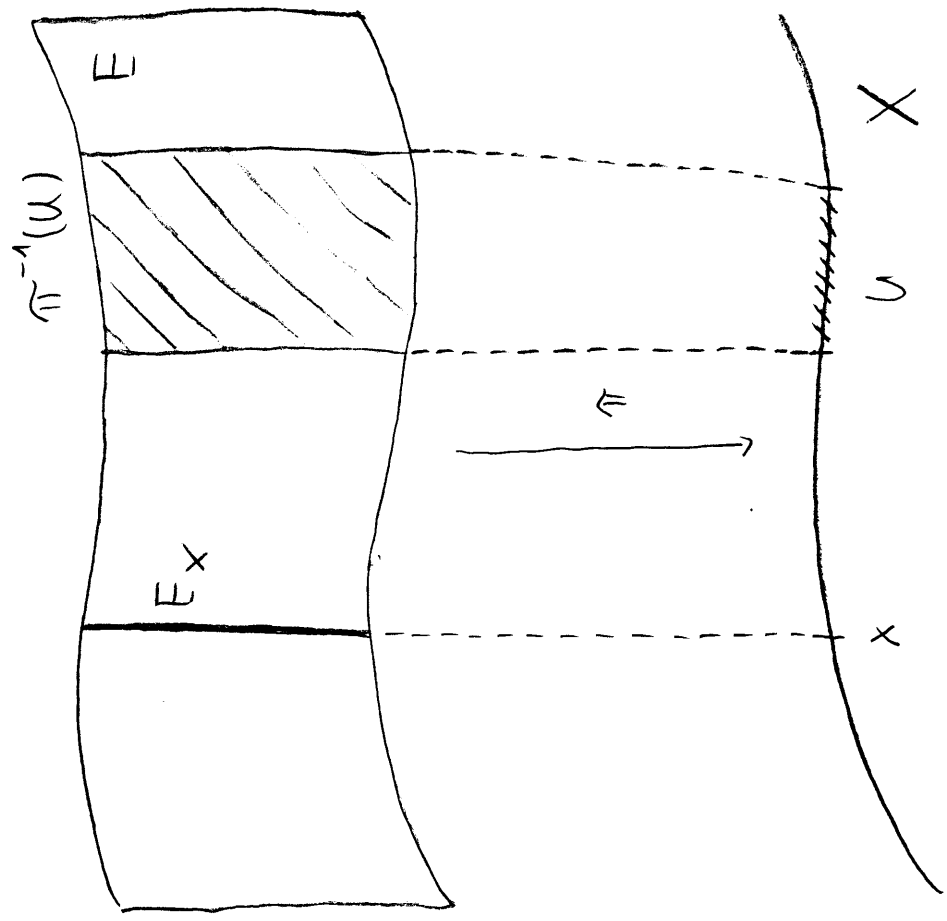
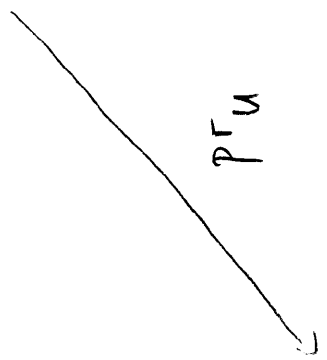
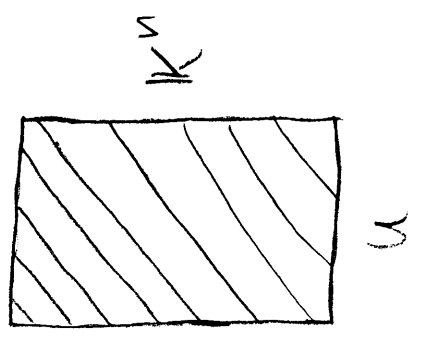
$$\Theta_{i,x}(v) ([f]_x) := \sum_{j=1}^n v_j \partial_j (f \circ \varphi_i^{-1})(\varphi_i(x))$$

~ for $v = (v_1, \dots, v_n) \in \mathbb{R}^n$, $[f]_x \in C_x^\infty(M)$.

We endow TM the topology defined by

$$W \subseteq TM \text{ open} \iff \forall i \in I: \tau_i(U_i \cap W) \subseteq U_i \times \mathbb{R}^n \text{ open.}$$

Then TM is a n -dimensional smooth vector bundle over M , called the tangent bundle of M .



2.7. Definition (smooth sections):

Let $\pi: E \rightarrow M$ be a smooth vector bundle over a smooth manifold M and let $V \subseteq M$ be open.

A map $s: V \rightarrow E$ is called a smooth section if

(i) $\pi \circ s = \text{id}_V$,

(ii) for each local trivialization $\tau: \pi^{-1}(U) \rightarrow U \times \mathbb{K}^n$, we have a smooth composition

$$\tau \circ s|_{U \cap V}: U \cap V \rightarrow (U \cap V) \times \mathbb{K}^n$$

In fact, $(\tau \circ s)(x) = (x, f(x))$ for all $x \in U \cap V$

with $f: U \cap V \rightarrow \mathbb{K}^n$ being a smooth function.

We write $\Gamma^\infty(V, E)$ for the set of all smooth sections $s: V \rightarrow E$, which is a \mathbb{K} -vector space.

2.8. Definition (vector fields):

Let M be a smooth manifold. A vector field on M is a smooth section of the tangent bundle TM .

We write $\mathfrak{X}(V) := \Gamma^\infty(V, TM)$ for $V \subseteq M$ open.

2.9. Theorem:

Let M be a smooth manifold of dimension n and let $V \subseteq M$ be open. Then

$$\Phi: \mathfrak{X}(V) \rightarrow \text{der } C^\infty(V), \quad (\Phi(X)f)(x) = X(x)([f]_x),$$

is an isomorphism of \mathbb{R} -vector spaces