Basics from Linear Algebra and Analysis	The Spaces	The maps	de Rham Cohomology

# Examples are Manifold de Rham Cohomology

#### Friedrich Günther, Eileen Oberringer, Nikolaos Tsakanikas

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Examples are Manifold de Rham Cohomology

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Sketching physical origins

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 Sketching physical origins and seeing natural examples for

Cochain complexes,

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- Sketching physical origins
- and seeing natural examples for
  - Cochain complexes,
  - Homology,
  - Chain maps,
  - Induced Maps on cohomology.

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## Section 1

# Physical motivation

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▶ Consider negative point charge q located in  $0 \in \mathbb{R}^3$ 

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- ▶ Consider negative point charge q located in  $0 \in \mathbb{R}^3$
- ▶ By "experiment", Coulomb verified that *q* excerts the force

$$\mathbf{F}_C = \frac{1}{4\pi\varepsilon_0} q Q \frac{x_0}{\|x_0\|_2^3}$$

on negative point charge Q located at  $x_0 \in \mathbb{R}^3 - \{0\}$ 

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on negative point charge Q located at  $x_0 \in \mathbb{R}^3 - \{0\}$ > Using assignment

$$\mathbf{E} \colon \mathbb{R}^3 - \{0\} \longrightarrow \mathbb{R}^3 - \{0\}, \qquad x_0 \longmapsto \frac{1}{4\pi\varepsilon_0} q \frac{x_0}{\|x_0\|_2^3}$$

the force on negative point charge Q at  $x_0$  can be expressed as  $Q\mathbf{E}(x_0)$ . **E** is eletrical field of point charge q

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 Because of superposition principle (i.e. "linearity of forces") this toy example is useful even for more complicated setups

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 The function

$$\phi \colon \mathbb{R}^3 - \{0\} \longrightarrow \mathbb{R}^3 - \{0\}, \qquad x_0 \longmapsto \frac{1}{4\pi\varepsilon_0} \frac{q_0}{\|x_0\|_2}$$

satisfies  $- \operatorname{grad} \phi = \mathbf{E}. \phi$  is called potential for **E**, fields with potentials are called *conservative* 

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Work W (work = force × distance) required to move negative point charge Q along (smooth) path γ throught E is given by

$$W = \int_{\gamma} (Q\mathbf{E}|\,d\mathbf{x}) := Q \int_{a}^{b} (\mathbf{E}(\gamma(t))|\dot{\gamma}(t))\,dt$$

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▶ Intuition for this formula: For partition a = t<sub>0</sub> < · · · < t<sub>n</sub> = b of [a, b], consider

$$\sum_{i=1}^{n} (\mathsf{E}(\gamma(t_{i-1})|\gamma(t_i) - \gamma(t_{i-1})),$$

each summand gives work required to move Q (at constant force) along cycle  $\gamma(t_i) - \gamma(t_{i-1})$ . Passing to limit gives  $\int_{\gamma} (\mathbf{E} | d\mathbf{x})$ 

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▶ Think of  $(\mathbf{E}(\gamma(t))|\dot{\gamma}(t))$  as part of  $\mathbf{E}(\gamma(t))$  tangential  $\gamma$  in t

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- ▶ Think of  $(\mathbf{E}(\gamma(t))|\dot{\gamma}(t))$  as part of  $\mathbf{E}(\gamma(t))$  tangential  $\gamma$  in t
- ▶ Because  $\mathbf{E} = -\operatorname{grad} \phi$ , have

$$(\mathsf{E}(\gamma(t))|\dot{\gamma}(t)) = -(\operatorname{\mathsf{grad}} \phi(\gamma(t))|\dot{\gamma}(t)) = -(\phi \circ \gamma)'(t)$$

i.e. W only depends on start and end point of path  $\gamma$ 

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# **Ulomb** Theory

Natural questions: How to determine if given field is conservative? Classification of conservative/non-conservative fields possible? Construction of potential possible in case field is conservative?

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# **Ulomb** Theory

- Natural questions: How to determine if given field is conservative? Classification of conservative/non-conservative fields possible? Construction of potential possible in case field is conservative?
- Answers to all questions: Yes

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# **Ulomb** Theory

- Natural questions: How to determine if given field is conservative? Classification of conservative/non-conservative fields possible? Construction of potential possible in case field is conservative?
- Answers to all questions: Yes
- In the following will concern with dual concept of differential forms instead of fields, i.e. will be studying Ulomb theory

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# Section 2

# Basics from Linear Algebra and Analysis

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Examples are Manifold de Rham Cohomology

## Finite-dimensional speciality

#### Remark 1

For finite-dimensional K-vector space V have

$$\bigwedge^{n} V^{*} \cong \operatorname{Alt}_{K}^{n}(V, K) = \{ \mu \colon V^{n} \to K \text{ alternating, multilinear} \}.$$

Will regard *n*-forms on  $V^*$  as *n*-times multilinear forms on V when convenient

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#### The Functor " $\wedge^{n}$ "

#### Lemma 2

Let  $n \in \mathbb{N}$ , let V and W be finite-dimensional K-vector spaces and let  $f \in \text{Hom}_{K}(V, W)$ . Have linear map  $\bigwedge^{n} f \colon \bigwedge^{n} V \to \bigwedge^{n} W$  such that for all  $v_{1}, \ldots, v_{n} \in V$ :

$$\bigwedge^n f(v_1 \wedge \cdots \wedge v_n) = f(v_1) \wedge \cdots \wedge f(v_n).$$

#### Pullback of an *n*-form

#### Definition 3

In the situation of Lemma 2: Have dual map  $f^* \colon W^* \to V^*$ ,  $\psi \mapsto \psi \circ f$  and linear map  $\bigwedge^n f^* \colon \bigwedge^n W^* \to \bigwedge^n V^*$  uniquely determined by

$$\bigwedge^n f^*(\psi^1 \wedge \cdots \wedge \psi^n) = f^*(\psi^1) \wedge \cdots \wedge f^*(\psi^n).$$

For *n*-form  $\omega \in \bigwedge^n W^*$ ,  $\bigwedge^n f^*(\omega)$  is called *pullback of*  $\omega$  *along* f.

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For *n*-form  $\omega \in \bigwedge^n W^*$ ,  $\bigwedge^n f^*(\omega)$  is called *pullback of*  $\omega$  *along* f.

**Note:** Often  $f^*\omega$  instead of  $\bigwedge^n f^*(\omega)$  by abuse of notation.

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# Differentiability for $f : \mathbb{R}^N \to \mathbb{R}$

Let  $U \subseteq \mathbb{R}^N$  be open, let  $f: U \to \mathbb{R}$  and let  $p_0 \in U$ .

▶ If there is linear  $L: \mathbb{R}^N \to \mathbb{R}$  with

$$\lim_{p \to p_0} \frac{\|f(p) - f(p_0) - L(p_0)(p - p_0)\|}{\|p - p_0\|} = 0,$$

then f is differentiable at  $p_0$ .  $df(p_0) := L$  is called *differential* of f at  $p_0$ .

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For  $v \in \mathbb{R}^N$  the limit (if it exists)

$$D_{v}f(p_{0}) = \lim_{t \to 0} \frac{f(p_{0} + tv) - f(p_{0})}{t}$$

is called *directional derivative of* f *in direction* v *at*  $p_0$ . For  $1 \le i \le N$  and  $v = e_i$ ,  $\partial_i f(p_0) := D_v f(p_0)$  are called *partial derivatives of* f *at*  $p_0$ .

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# Differentiability of $f : \mathbb{R}^N \to \mathbb{R}$

▶ If *f* is differentiable at  $p_0 \in U$ , then for any  $v \in \mathbb{R}^N$ :

 $D_v f(p_0) = df(p_0)v.$ 

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# Differentiability of $f : \mathbb{R}^N \to \mathbb{R}$

▶ If *f* is differentiable at  $p_0 \in U$ , then for any  $v \in \mathbb{R}^N$ :

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► The transformation matrix of  $df(p_0)$  w.r.t the canonical basis of  $\mathbb{R}^N$  is

$$\left(\frac{\partial f}{\partial x^1}(p_0),\ldots,\frac{\partial f}{\partial x^n}(p_0)\right).$$

Transformation matrix is called the Jacobian.

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Transformation matrix is called the Jacobian.

▶ If *f* is differentiable on *U* then

$$\mathit{df} \colon U \longrightarrow (\mathbb{R}^N)^*, \qquad p \longmapsto (\mathit{df})(p)$$

is called Fréchet derivative of f or derivative of f.

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## Section 3

# The Spaces

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Definition 4 (Differential Form of Degree n) Let  $n \in \mathbb{N}$ , let  $U \subseteq \mathbb{R}^N$  be open. A map

$$\omega \colon U \longrightarrow \bigwedge^{n} (\mathbb{R}^{N})^{*},$$
$$u \longmapsto \sum_{1 \leq i_{1} < \cdots < i_{n} \leq N} f_{(i_{1}, \dots, i_{n})}(u) \, dx^{i_{1}} \wedge \cdots \wedge dx^{i_{n}},$$

where  $f_{(i_1,...,i_n)}$ :  $U \to \mathbb{R}$ , is differential form of degree n on U; briefly *n*-form. Put

$$\Omega^n(U) := \{ \omega \colon U \to \bigwedge^n (\mathbb{R}^N)^* \text{ smooth differential form} \}.$$

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#### Note:

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$$\Omega^n(U)$$
 is free  $C^{\infty}(U)$ -module of dimension  $\binom{N}{n}$ ,

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•  $\Omega^0(U) = C^{\infty}(U)$ .

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$$\omega \wedge \eta \colon U \longrightarrow \bigwedge^{n+m} (\mathbb{R}^N)^*, \qquad u \longmapsto \omega(u) \wedge \eta(u)$$

is called wedge product of  $\omega$  and  $\eta$ .

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- "∧" is associative,
- "∧" is distributive,
- " $\wedge$ " is  $C^{\infty}(U)$ -bilinear,
- " $\wedge$ " is anticommutative, i.e. for  $\omega \in \Omega^n(U), \eta \in \Omega^m(U)$ :  $\omega \wedge \eta = (-1)^{nm} \eta \wedge \omega.$

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 $\Omega(U) := \bigoplus_{n=0}^{\infty} \Omega^n(U)$  together with " $\wedge$ " is a graded algebra.

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## Section 4

## The maps

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Examples are Manifold de Rham Cohomology

## Fréchet Derivative Reinterpreted

#### Remark 6

Let  $U \subseteq \mathbb{R}^N$  be open, let  $f \in C^{\infty}(U)$ . The derivative df of f is 1-form on U and w.r.t. the canonical basis of  $\mathbb{R}^N$ :

$$df(p) = \sum_{i=1}^{n} \frac{\partial f}{\partial x^{i}}(p) dx^{i}.$$

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Rephrasing: Have a map

$$d: \Omega^0(U) \longrightarrow \Omega^1(U), \qquad f \longmapsto df.$$

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In the following: Generalise this to arbitrary forms.

## Fréchet Derivative Reinterpreted

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**Note:** The Fréchet derivative of  $\operatorname{pr}_i \colon \mathbb{R}^N \to \mathbb{R}$ ,  $(x^1, \ldots, x^N)^t \mapsto x^i$  is  $d\operatorname{pr}_i = \sum_{j=1}^N \delta_{ij} \varepsilon^j = \varepsilon^i$ , hence  $dx^i \coloneqq \varepsilon^i$ .

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#### Definition 7

Let 
$$U \subseteq \mathbb{R}^N$$
 be open and let  $n \in \mathbb{N}$ . For  
 $\omega = \sum_{1 \leq i_1 < \dots < i_n \leq N} f_{(i_1,\dots,i_n)} dx^{i_1} \wedge \dots \wedge dx^{i_n} \in \Omega^n(U)$ ,

$$d\omega := \sum_{1 \le i_1 < \cdots < i_n \le N} \left( \sum_{j=1}^N \frac{\partial f_{(i_1, \dots, i_n)}}{\partial x^j} \, dx^j \right) \wedge dx^{i_1} \wedge \cdots \wedge dx^{i_n}$$

is called *exterior derivative of*  $\omega$ .

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- Definition of exterior derivative does not depend on choice of coordinates
- Exterior derivative is linear

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- Definition of exterior derivative does not depend on choice of coordinates
- Exterior derivative is linear
- ►  $d \circ d = 0$ , i.e. d is differential for a certain cochain complex

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#### **Definition 8**

Let  $U \subseteq \mathbb{R}^N$ ,  $V \subseteq \mathbb{R}^M$  be open, let  $\varphi \colon U \to V$  be smooth and let  $\omega \in \Omega^n(V)$ . Then,

$$(\varphi^*\omega)\colon U \longrightarrow \bigwedge^n (\mathbb{R}^N)^*, u \longmapsto [(v_1, \ldots, v_n) \mapsto \omega(\varphi(u))[(D\varphi)(u)(v_1), \ldots, (D\varphi)(u)(v_n)]]$$

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$$\varphi^*(\omega \wedge \eta) = \varphi^*(\omega) \wedge \varphi^*(\eta),$$

#### **Definition 8**

Let  $U \subseteq \mathbb{R}^N$ ,  $V \subseteq \mathbb{R}^M$  be open, let  $\varphi \colon U \to V$  be smooth and let  $\omega \in \Omega^n(V)$ . Then,

$$\begin{aligned} (\varphi^*\omega)\colon U &\longrightarrow \bigwedge^n (\mathbb{R}^N)^*, \\ u &\longmapsto [(v_1,\ldots,v_n) \mapsto \omega(\varphi(u))[(D\varphi)(u)(v_1),\ldots,(D\varphi)(u)(v_n)]] \end{aligned}$$

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$$\varphi^*(\omega + \eta) = \varphi^*(\omega) + \varphi^*(\eta),$$
  
•  $\varphi^*(\omega \wedge \eta) = \varphi^*(\omega) \wedge \varphi^*(\eta),$   
•  $\varphi^*(d\omega) = d\varphi^*(\omega).$ 

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#### Section 5

# de Rham Cohomology

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Examples are Manifold de Rham Cohomology

# Definition de Rham Cohomology

#### Definition 9

Let  $U \subseteq \mathbb{R}^N$  be open. Have the cochain complex

$$0 \longrightarrow \Omega^{0}(U) \stackrel{d^{0}}{\longrightarrow} \Omega^{1}(U) \stackrel{d^{1}}{\longrightarrow} \dots \stackrel{d^{N-1}}{\longrightarrow} \Omega^{N}(U) \longrightarrow 0$$

Put  $H^n(U) := \ker d^n / \operatorname{im} d^{n-1}$ , the *n*-th de Rham cohomology of U, and put  $H^{\bullet}(U) := \bigoplus_{n=0}^{N} H^n(U)$ , the de Rham Cohomology of U.

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# Definition de Rham Cohomology

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**Note:** Let  $[\omega] \in H^n(U)$ ,  $[\eta] \in H^m(U)$ . Then

$$[\omega] \wedge [\eta] := [\omega \wedge \eta] \in H^{n+m}(U)$$

is well-defined making  $H^{\bullet}(U)$  a graded algebra.

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#### Pullback as Chain Map

#### Example 10

Let  $U, V \subseteq \mathbb{R}^N$  be open and let  $\varphi \colon U \to V$  be smooth. For each *n*, obtain  $\varphi^* \colon \Omega^n(V) \to \Omega^n(U)$  and the diagram

Because of  $\varphi^*(d\omega) = d\varphi^*\omega$ , the pullback is a chain map. Also get induced map  $\varphi^* \colon H^n(V) \to H^n(U), \ [\omega] \mapsto [\varphi^*\omega].$ 

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#### Hands on Pullback

#### Example 11

• Consider  $\omega \in \Omega^1(U)$  (and fix  $\omega$  in the following) with

$$\omega(x,y) = \frac{x}{x^2 + y^2} \, dy - \frac{y}{x^2 + y^2} \, dx \, .$$

(Of interest for differential geometry, "winding form")

#### Hands on Pullback

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(Of interest for differential geometry, "winding form")
► This form is closed (i.e. dω = 0):

$$d\omega(x,y) = rac{y^2 - x^2}{(x^2 + y^2)^2} \, dx \wedge dy - rac{x^2 - y^2}{(x^2 + y^2)^2} \, dy \wedge dx = 0$$

## Hands on Pullback

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▶ Is  $\omega$  exact? No, but how do we see this?

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▶ **Reminder:** For  $\eta \in \Omega^1(U)$  and  $\gamma : [a, b] \to U$ ,

$$\int_{\gamma} \eta := \int_{a}^{b} \gamma^{*} \eta(t) \, dt = \int_{a}^{b} \langle \eta(\gamma(t)), \gamma'(t) \rangle \, dt$$

is called *line integral of*  $\eta$  *along*  $\gamma$ .

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is called *line integral of*  $\eta$  *along*  $\gamma$ .

▶ Fact: If  $\eta = df$  for some  $f \in \Omega^0(U)$ , then

$$\int_{\gamma} df = \int_{a}^{b} \gamma^{*}(df)$$
$$= \int_{a}^{b} d(\gamma^{*}f) = \int_{a}^{b} (f \circ \gamma)'(t) dt = f(\gamma(b)) - f(\gamma(a))$$

In particular, for closed paths  $\gamma$  it holds  $\int_{\gamma} df = 0$ .

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▶ For pullback of 1-form, we need to understand two things:

$$\gamma^* f := f \circ \gamma, \qquad \gamma^* dx^i = d(\gamma^* \circ \mathrm{pr}_i) = d(\mathrm{pr}_i \circ \gamma) = d\gamma^i$$

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▶ For  $\gamma : [0, 2\pi] \to \mathbb{R}^2 - \{0\}$ ,  $t \mapsto (\cos(t), \sin(t))^\top$  and  $\omega$  have

$$\gamma^* dx = d\gamma^1 = -\sin t \, dt, \qquad \gamma^* dy = d\gamma^2 = \cos t \, dt,$$
  
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Alternatively,

$$egin{aligned} &\langle \omega(\gamma(t)),\gamma'(t)
angle &= \cos(t)\langle dy,-\sin(t)e_x+\cos(t)e_y
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• Get  $\int_{\gamma} \omega = \int_{0}^{2\pi} dt = 2\pi \neq 0$ , i.e.  $\omega$  can't be exact.

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# Conclusion

▶ In general, the form

$$\omega = \frac{1}{\|x\|^N} \sum_{i=1}^N (-1)^{i-1} x_i \, dx^1 \wedge \dots \wedge \widehat{dx^i} \wedge \dots \wedge dx^N$$

is closed but not exact

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is closed but not exact

► It can be shown that the non-trivial cohomology spaces of ℝ<sup>N</sup> - {0} are

$$H^0(\mathbb{R}^N - \{0\}) = \mathbb{R}, \qquad H^{N-1}(\mathbb{R}^N - \{0\}) = \mathbb{R}\omega \cong \mathbb{R}$$