Universität des Saarlandes



Fachrichtung 6.1 – Mathematik

Preprint Nr. 378

A higher order TV-type variational problem related to the denoising and inpainting of images

Martin Fuchs and Jan Müller

Saarbrücken 2016

A higher order TV-type variational problem related to the denoising and inpainting of images

Martin Fuchs

Saarland University Department of Mathematics P.O. Box 15 11 50 66041 Saarbrücken Germany fuchs@math.uni-sb.de

Jan Müller

Saarland University Department of Mathematics P.O. Box 15 11 50 66041 Saarbrücken Germany jmueller@math.uni-sb.de

Edited by FR 6.1 – Mathematik Universität des Saarlandes Postfach 15 11 50 66041 Saarbrücken Germany

Fax: + 49 681 302 4443 e-Mail: preprint@math.uni-sb.de WWW: http://www.math.uni-sb.de/ AMS Subject Classification: 49 Q 20, 49 N 60, 49 N 15, 26 B 30, 62 H 35 Keywords: higher order bounded variation, variational image inpainting, TVregularization, partial regularity

Abstract

We give a comprehensive survey on a class of higher order variational problems which are motivated by applications in mathematical imaging. The overall aim of this note is to investigate if and in which manner results from the first author's previous work on variants of the TV-regularization model (see e.g. [BF2], [BF3], [BF4] and [FT]) can be extended to functionals which involve higher derivatives. This seems to be not only of theoretical interest, but also relevant to applications since higher order TV-denoising appears to maintain the advantages of the classical model as introduced by Rudin, Osher and Fatemi in [ROF] while avoiding the unpleasant "staircasing" effect (see e.g. [BKP] or [LLT]). Our paper features results concerning generalized solutions in spaces of functions of higher order bounded variation, dual solutions as well as partial regularity of minimizers.

Dedicated to Nicola Fusco on the occasion of his 60th birthday

1 Introduction

Among the fundamental contributions of Nicola Fusco to the basic problems in the Calculus of Variations such as the question of (partial) regularity of weak solutions and the lower semicontinuity of variational integrals in various settings one will also find a number of important results addressing the popular field of free discontinuity problems as they for example occur in image analysis through the study of the Mumford-Shah functional. Without being complete we refer to the papers [AFF], [FF] and advise the reader to consult chapters 6,7 and 8 of the monograph [AFP] for more information on the subject and for further references.

In our note we concentrate on a particular aspect of image analysis, namely the simultaneous denoising and inpainting of images based on variants of the TV-regularization originally proposed by Rudin, Osher and Fatemi [ROF] which in its simplest form consists in the problem of minimizing the functional

$$I[u] := \int_{\Omega} |\nabla u| + \frac{\lambda}{2} \int_{\Omega - D} |u - f|^2 dx$$
(1.1)

among functions $u: \Omega \to \mathbb{R}^M$ with finite total variation (see e.g. [Giu] or [AFP]), where Ω denotes a bounded Lipschitz domain in \mathbb{R}^n , $n \ge 2$. In (1.1) D stands for a fixed subset of Ω , and the given function $f: \Omega - D \to \mathbb{R}^M$ represents the observed data, which might be noisy. The idea is that on the set D no observation is possible, so that by minimizing I this missing observation can be retrieved from the measurement f on $\Omega - D$ combined with a simultaneous denoising forced by the regularizing term $\int_{\Omega} |\nabla u|$. The quantity $\int_{\Omega - D} |u - f|^2 dx$ measures the quality of data fitting, and λ denotes a positive parameter being under our disposal. In case $D = \emptyset$ the minimization of I reduces to pure denoising, whereas for $D \neq \emptyset$ an inpainting procedure is incorporated. A clear interpretation of the above terminology can be given in the context of greyvalued images for which n = 2, M = 1 and $f(x) \in [0, 1], x \in \Omega - D$, measures the intensity of the grey level of the observed image. However, certain applications (see [BC], [SS]) suggest to study even the higher dimensional case together with vectorial data.

From the analytical point of view the quantity $\int_{\Omega} |\nabla u|$ for obvious reasons is rather unpleasant. At the same time - with regard to practical aspects - it seems to be desirable to keep the linear growth of the regularization term with respect to $|\nabla u|$, and as a compromise we replaced in the papers [BF2], [BF3], [BF4] and [FT] the functional I from (1.1) with the energy

$$\tilde{I}[u] := \int_{\Omega} F(\nabla u) + \frac{\lambda}{2} \int_{\Omega - D} |u - f|^2 dx$$
(1.2)

for a strictly convex density F being of linear growth. A typical example (also of computational importance) is given by the formula

$$F(Z) := \Phi_{\mu}(|Z|), \tag{1.3}$$

where for $\mu > 1$ we have set

$$\Phi_{\mu}(r) := \int_{0}^{r} \int_{0}^{s} (1+t)^{-\mu} dt \, ds, \ r \ge 0.$$
(1.4)

Note that we have the identities

$$\begin{cases} \Phi_{\mu}(r) = \frac{1}{\mu - 1}r + \frac{1}{\mu - 1}\frac{1}{\mu - 2}(r + 1)^{-\mu + 2} - \frac{1}{\mu - 1}\frac{1}{\mu - 2}, \ \mu \neq 2, \\ \Phi_{2}(r) = r - \ln(1 + r), \ r \ge 0, \end{cases}$$
(1.5)

from which we deduce that Φ_{μ} approximates the TV-density in the sense that

$$(\mu - 1)\Phi_{\mu}(|Z|) \to |Z| \text{ as } \mu \to \infty.$$
 (1.6)

It should be clear that the functional \tilde{I} from (1.2) has to be studied on the space $BV(\Omega, \mathbb{R}^M) \cap L^2(\Omega - D, \mathbb{R}^M)$ (see e.g. [Giu] or [AFP]) with the interpretation of

 $\int_{\Omega} F(\nabla u)$ as a convex function of a measure as introduced for example in [DT]. Concerning the variational problem

$$\tilde{I} \to \min \text{ in } BV(\Omega, \mathbb{R}^M) \cap L^2(\Omega - D, \mathbb{R}^M)$$
 (1.7)

we obtained the following results (compare e.g. [BF2], [BF3], [BF4], [FT] and [Ti]):

Existence and uniqueness:

Problem (1.7) admits at least one solution being unique on $\Omega - D$. Moreover, the absolutely continuous part $\nabla^a u$ of ∇u with respect to Lebesgue's measure is uniquely determined. Any solution of problem (1.7) occurs as a limit of an \tilde{I} -minimizing sequence from the space $W^{1,1}(\Omega, \mathbb{R}^M) \cap L^2(\Omega - D, \mathbb{R}^M)$. Here and in what follows we use the symbol $W^{m,p}(\Omega)$ for the standard Sobolev space (see [Ad]) which is normed by

$$\|u\|_{m,p;\Omega} := \sum_{k=0}^m \|\nabla^k u\|_{p;\Omega}$$

with $\nabla^0 u := u$ and $\|\cdot\|_{p;\Omega}$ denoting the *p*-norm.

Duality:

The problem dual to (1.7) has a unique solution $\sigma \in L^{\infty}(\Omega, \mathbb{R}^{nM})$. The duality formula $\sigma = DF(\nabla^a u)$ holds almost everywhere on Ω .

Regularity:

Any solution u of problem (1.7) is of class C^1 on an open subset of Ω whose complement is of Lebesgue measure zero. In the particular case of the density (1.3) with Φ_{μ} from (1.4), (1.5) (or for integrands of similar type) we have full interior regularity provided we assume $\mu < 2$.

Apart from the first order TV-model and its extensions described above, higher order variants of the TV-model seem to be not only of theoretical interest as it is for example outlined in the recent paper [BKP]. Roughly speaking, the functionals I and \tilde{I} from (1.1) and (1.2) are now replaced by the expressions

$$I^{m}[u] := \int_{\Omega} |\nabla^{m}u| + \frac{\lambda}{2} \int_{\Omega-D} |u - f|^{2} dx$$

and

$$\tilde{I}^m[u] := \int_{\Omega} F(\nabla^m u) + \frac{\lambda}{2} \int_{\Omega-D} |u - f|^2 \, dx,$$

respectively, where $m \geq 2$ denotes some fixed integer. The functions $u: \Omega \to \mathbb{R}^M$ are taken from the space of *functions with m-th order bounded variation* defined by

$$BV^{m}(\Omega) := \left\{ u \in W^{m-1,1}(\Omega) : \nabla^{m-1} u \in BV(\Omega, S^{m-1}(\mathbb{R}^{n})) \right\},\$$

which means that a function u is of m-th order bounded variation if and only if u belongs to the Sobolev class $W^{m-1,1}(\Omega)$ with the additional property that the tensor of the m-th order generalized derivatives is a tensor valued Radon measure of finite total variation denoted by $|\nabla^m u|(\Omega) < \infty$. Here $S^m(\mathbb{R}^n)$ denotes the space of m-linear symmetric maps $(\mathbb{R}^n)^m \to \mathbb{R}$. For notational simplicity we assume from now on that M = 1.

The purpose of our note is the extension of the previously indicated results valid for the first order TV-model and its modifications formulated in (1.7) to the higher order setting. To do so, we first fix our assumptions. In what follows Ω always denotes a bounded Lipschitz domain in \mathbb{R}^n , $n \geq 2$. We consider either the case $D = \emptyset$ ("pure denoising") or we assume that D is a nonvoid subset of Ω . In contrast to the first order case it might not be enough to require the set D to be simply measurable: whenever the dimension n of the ambient space \mathbb{R}^n exceeds 2m, the additional constraint $u \in L^2(\Omega - D)$ becomes nontrivial in the sense that the integrability does not follow from embedding theorems anyway. The same problem may occur when we consider more general data-fitting terms as considered in [MT]. In both cases, our techniques rely on the following density result:

Theorem 1.1

Let $\Omega \subset \mathbb{R}^n$ be a bounded Lipschitz domain and $D \subsetneq \Omega$ an open subset such that $\Omega - D$ has Lipschitz boundary as well. Then it holds for $1 \le p, q < \infty$:

(a) Any function $u \in W^{m,p}(\Omega) \cap L^q(\Omega - D)$ can be approximated by a sequence of smooth functions $(\varphi_k)_{k=1}^{\infty} \subset C^{\infty}(\overline{\Omega})$ such that

$$||u - \varphi_k||_{m,p;\Omega} + ||u - \varphi_k||_{q;\Omega-D} \to 0 \text{ for } k \to \infty.$$

(b) Any function $u \in BV^m(\Omega) \cap L^q(\Omega - D)$ can be approximated by a sequence of smooth functions $(\varphi_k)_{k=1}^{\infty} \subset C^{\infty}(\overline{\Omega})$ such that

$$\begin{aligned} \|u-\varphi_k\|_{m-1,1;\Omega} + \|u-\varphi_k\|_{q;\Omega-D} + \left| |\nabla^m u|(\Omega) - \int_{\Omega} |\nabla^m \varphi_k| \, dx \right| \\ + \left| \sqrt{1+|\nabla^m u|^2}(\Omega) - \int_{\Omega} \sqrt{1+|\nabla^m \varphi_k|^2} \, dx \right| \to 0 \quad for \quad k \to \infty. \end{aligned}$$

Here, the term $\sqrt{1 + |\nabla^m u|^2}(\Omega)$ has to be understood in the sense of convex functions of a measure; we once again refer to [DT]. The reader should note that our hypotheses imposed on Ω and D in particular imply that $\Omega - D$ is a set of positive Lebesgue measure, since the usual definition of "Lipschitz boundary" (cf., e.g. [Ad], 4.5, p. 66) requires the set to have nonempty interior.

Remark 1.1

In the earlier work [Mü], this theorem has been proved under stronger restrictions on the geometry of Ω and D. Nonetheless, quite recently we succeeded in generalizing this result towards the above assumptions. The proof is given in the subsequent section.

For $m \geq 2$ we consider a density $F : S^m(\mathbb{R}^n) \to [0,\infty)$ of class $C^1(S^m(\mathbb{R}^n))$ satisfying the following assumptions

$$F$$
 is strictly convex and (w.l.o.g.) $F(0) = 0,$ (1.8)

$$|DF(Z)| \le \nu_1,\tag{1.9}$$

$$F(Z) \ge \nu_2 |Z| - \nu_3 \tag{1.10}$$

with constants $\nu_1, \nu_2 > 0, \nu_3 \in \mathbb{R}$, for all $Z \in S^m(\mathbb{R}^n)$. In accordance with (1.9) and F(0) = 0 we directly get

$$F(Z) \le \nu_1 |Z|$$

for all $Z \in S^m(\mathbb{R}^n)$, and this inequality together with (1.10) shows that F is of linear growth in the sense that

$$\nu_2|Z| - \nu_3 \le F(Z) \le \nu_1|Z|, \ Z \in S^m(\mathbb{R}^n).$$
(1.11)

Note that our example from (1.3)-(1.5) satisfies (1.8)-(1.11). Suppose further that we are given a function f at least of class $L^2(\Omega - D)$ and let λ as before (see (1.1) and (1.2)) denote a positive parameter. With these data we introduce the problem

$$J^{m}[u] := \int_{\Omega} F(\nabla^{m} u) \, dx + \frac{\lambda}{2} \int_{\Omega - D} |u - f|^{2} \, dx \to \min$$

$$\text{in } W^{m,1}(\Omega) \cap L^{2}(\Omega - D),$$
(1.12)

which due to the non-reflexivity of the Sobolev space $W^{m,1}(\Omega)$ admits in general no solution. As in the first order case we therefore pass to a suitable relaxed version: for functions w from the space $BV^m(\Omega) \cap L^2(\Omega - D)$ we let

$$K[w] := \int_{\Omega} F(\mu^a) \, dx + \int_{\Omega} F^{\infty}\left(\frac{\mu^s}{|\mu^s|}\right) d|\mu^s| + \frac{\lambda}{2} \int_{\Omega-D} |w - f|^2 \, dx, \qquad (1.13)$$

where we have abbreviated

$$F^{\infty}: S^m(\mathbb{R}^n) \to [0,\infty), \ F^{\infty}(Z):=\lim_{t \to \infty} \frac{F(tZ)}{t}, \ Z \in S^m(\mathbb{R}^n).$$

 F^{∞} is known as the recession function of the density F. In formula (1.13) the symbol μ just denotes the measure $\nabla^m w$, for which we have the Lebesgue decomposition $\mu = \mu^a(\mathcal{L}^n \sqcup \Omega) + \mu^s$ with $\mu^a \in L^1(\Omega, S^m(\mathbb{R}^n))$ and $\mu^s \perp (\mathcal{L}^n \sqcup \Omega)$, $\mathcal{L}^n \sqcup \Omega$ denoting the restriction to Ω of Lebesgue's measure. Now we can state our first result concerning the relaxed version of problem (1.12).

Theorem 1.2

Let the assumptions concerning Ω and D stated in Theorem 1.1 hold and let F satisfy (1.8)-(1.10). Then it holds:

(a) The problem

$$K \to \min \ in \ BV^m(\Omega) \cap L^2(\Omega - D)$$
 (1.14)

with K from (1.13) admits at least one solution u.

- (b) Suppose that u and \tilde{u} are solutions of (1.14). Then $u = \tilde{u}$ almost everywhere on ΩD and $(\nabla^m u)^a = (\nabla^m \tilde{u})^a$ almost everywhere on Ω .
- (c) We have

$$\inf_{W^{m,1}(\Omega)\cap L^2(\Omega-D)} J^m = \inf_{BV^m(\Omega)\cap L^2(\Omega-D)} K$$

where the functional J^m is defined in (1.12).

- (d) Let \mathcal{M} denote the set of all $W^{m-1,1}$ -cluster points of J^m -minimizing sequences from the space $W^{m,1}(\Omega) \cap L^2(\Omega - D)$. Then \mathcal{M} coincides with the set of all K-minimizers in $BV^m(\Omega) \cap L^2(\Omega - D)$.
- (e) If \mathcal{M} contains a function u from the space $W^{m,1}(\Omega) \cap L^2(\Omega D)$, then it holds $\mathcal{M} = \{u\}$.

Let us pass to the variational problem being in duality to (1.12) and (1.14), respectively. To this purpose we introduce the Lagrangian by defining

$$\begin{split} l(w,\kappa) &:= \int\limits_{\Omega} \left[\kappa : \nabla^m w - F^*(\kappa)\right] dx + \frac{\lambda}{2} \int\limits_{\Omega-D} |w - f|^2 dx, \\ &w \in W^{m,1}(\Omega) \cap L^2(\Omega - D), \; \kappa \in L^\infty(\Omega, S^m(\mathbb{R}^n)), \end{split}$$

 F^* denoting the convex conjugate of F and ":" the standard scalar product on $S^m(\mathbb{R}^n).$ It holds

$$J^{m}[w] = \sup_{\kappa \in L^{\infty}(\Omega, S^{m}(\mathbb{R}^{n}))} l(w, \kappa), \ w \in W^{m,1}(\Omega) \cap L^{2}(\Omega - D),$$
(1.15)

and we define the dual functional $R:L^\infty(\Omega,S^m(\mathbb{R}^n))\to [-\infty,\infty]$ through the formula

$$R[\kappa] := \inf_{w \in W^{m,1}(\Omega) \cap L^2(\Omega - D)} l(w, \kappa).$$

Theorem 1.3

Consider Ω , D and F as in Theorem 1.2. Then we have:

(a) The dual problem

$$R \to \max in L^{\infty}(\Omega, S^m(\mathbb{R}^n))$$

admits a unique solution σ .

- (b) σ satisfies the duality relation $\sigma = DF((\nabla^m u)^a)$ almost everywhere on Ω , where u denotes any K-minimizer from the space $BV^m(\Omega) \cap L^2(\Omega - D)$.
- (c) The "inf-sup relation" holds, i.e. we have

$$\inf_{W^{m,1}(\Omega)\cap L^2(\Omega-D)} J^m = \sup_{L^{\infty}(\Omega, S^m(\mathbb{R}^n))} R.$$

We finish our survey by adding a particular regularity result.

Theorem 1.4

Let Ω denote a bounded Lipschitz domain in \mathbb{R}^2 and fix a measurable subset D of Ω with $\mathcal{L}^2(\Omega - D) > 0$. Consider an observed image f in the space $L^{\infty}(\Omega - D)$. Moreover, suppose that F is of class C^2 satisfying (1.8)-(1.10) as well as the condition of μ -ellipticity

$$\nu_4 (1+|Z|)^{-\mu} |X|^2 \le D^2 F(Z) (X, X) \le \nu_5 \frac{1}{1+|Z|} |X|^2$$
(1.16)

for some exponent $\mu > 1$ and with positive constants ν_4, ν_5 for all $X, Z \in S^m(\mathbb{R}^2)$. Then, if

either :
$$\mu < 2$$
 together with $D = \emptyset$
or : $\mu < \frac{3}{2}$ in case of general D ,

the following statements hold:

- (a) Problem (1.12) admits a unique solution u in the space $W^{m,1}(\Omega)$.
- (b) The function u belongs to any class $W^{m,p}_{\text{loc}}(\Omega)$, $p < \infty$.
- (c) There is an open subset Ω_0 of Ω with full \mathcal{L}^2 -measure such that the minimizer u is of class $C^{m,\alpha}(\Omega_0)$ for any $\alpha \in (0,1)$. In fact it holds \mathcal{H} -dim $(\Omega - \Omega_0) = 0$, i.e. $\mathcal{H}^{\varepsilon}(\Omega - \Omega_0) = 0$ for any $\varepsilon > 0$.
- (d) If σ denotes the solution of the dual problem from Theorem 1.3 (a), then the first weak partial derivatives of σ exist in the space $L^2_{loc}(\Omega)$.

Remark 1.2

Condition (1.16) holds for our example (1.3) with Φ_{μ} from (1.4). It is easy to check that any density F with (1.16) for some $\mu > 1$ is of linear growth in the sense of (1.11).

Remark 1.3

Motivated by the results outlined in [BF3], [FT] and [Ti] we conjecture that actually $\mu < 2$ is sufficient for obtaining the statements of Theorem 1.4 even in the case $D \neq \emptyset$. Moreover we think that (c) can be improved to $u \in C^{m,\alpha}(\Omega)$, $0 < \alpha < 1$.

Remark 1.4

From the point of view of numerical applications it is desirable to replace the energies J^m (from (1.12)) and K (from (1.13)) by functionals of lower order involving appropriate coupling terms. This might also concern the aspect of regularity addressed in Remark 1.3. The reader is referred to [BFW].

The rest of this article is organized as follows: in the next section we introduce the space $BV^m(\Omega)$ of functions of *m*-th order bounded variation along with two auxiliary results and prove our density result Theorem 1.1. This is followed by a short section in which we sketch the proofs of both Theorem 1.2 and 1.3. Since they only differ by the use of Theorem 1.1 from the first order case studied in [BF4] and [FT], we decided not to go into the details but rather to point out where the density result finds application. The last part is entirely devoted to the proof of our regularity result Theorem 1.4.

2 The space BV^m , proof of Theorem 1.1

Several authors have conceptualized the notion of higher order bounded variation in varying ways, e.g. via the distributional Jacobian (cf. [JS]). Despite that, the most natural generalization of this term appears to be saying an L^1 -function is of m-th order bounded variation if it is m-1 times weakly differentiable in L^1 and its m-th order distributional gradient, i.e. the symmetric Tensor $(\partial_{i_1,\ldots,i_m} u)_{i_1,\ldots,i_m=1}^n$ is represented by a tensor valued finite Radon measure. As previously mentioned, we designate the space of all functions of m-th order bounded variation by

$$BV^{m}(\Omega) := \left\{ u \in W^{m-1,1}(\Omega) : \nabla^{m-1} u \in BV(\Omega, S^{m}(\mathbb{R}^{n})) \right\}$$

and note, that together with the norm

$$||u||_{BV^{m}(\Omega)} := ||u||_{m-1,1;\Omega} + |\nabla^{m}u|(\Omega)$$

it becomes a Banach space. Further aspects of these (and even more general spaces) concerning also the approximation by smooth functions have been outlined in [DT] and [De].

Remark 2.1

In the special case m = 2 the term "functions of bounded Hessian" has been established in [De] by Demengel, and many authors prefer to write $HB(\Omega)$ (for "hessien borné") instead of $BV^2(\Omega)$, since.

By the nature of its definition, the space $BV^m(\Omega)$ inherits the following compactness property which can be proved exactly as the corresponding first order result (see [AFP], Theorem 3.23, p. 132):

Lemma 2.1 (compactness in BV^m) Let $\Omega \subset \mathbb{R}^n$ be a bounded Lipschitz domain and $(u_k)_{k=1}^{\infty} \subset BV^m(\Omega)$ a sequence with

$$||u_k||_{BV^m(\Omega)} \le M$$

for some constant M > 0. Then there is a subsequence $(u_{k_l})_{l=1}^{\infty}$ and a function $u \in BV^m(\Omega)$ such that

 $||u - u_{k_l}||_{m-1,1;\Omega} \to 0 \text{ for } l \to \infty \text{ and } ||u||_{BV^m(\Omega)} \le M.$

The following observation on equivalent norms in higher order spaces will be useful throughout our survey:

Lemma 2.2

Let $\Omega \subset \mathbb{R}^n$ be a bounded Lipschitz domain, $m \in \mathbb{N}$, $1 \leq p < \infty$ and let $D \subset \Omega$ be a measurable subset with $0 \leq \mathcal{L}^n(D) < \mathcal{L}^n(\Omega)$. (a) There is a constant C > 0, depending only on Ω , D, m, n and p such that for all $u \in W^{m,p}(\Omega)$

$$||u||_{m,p;\Omega} \le C (||\nabla^m u||_{p;\Omega} + ||u||_{1,\Omega-D}).$$

(b) There is a constant C > 0, depending only on Ω , D, m and n such that for all $u \in BV^m(\Omega)$

$$||u||_{BV^m(\Omega)} \le C(|\nabla^m u|(\Omega) + ||u||_{1,\Omega-D}).$$

Proof. (a) is a direct consequence of Theorem 1.1.15 in [Ma] with the choice $\mathcal{F}(u) := \int_{\Omega-D} |u| dx$, since no non-trivial polynomial of degree m-1 vanishes on a set of positive Lebesgue measure.

(b) follows from part (a) by approximation with smooth functions. \Box

For all $u, v \in BV^m(\Omega)$ we define a distance d(.,.) by

$$d(u,v) := \|u-v\|_{m-1,1;\Omega} + \left| \int_{\Omega} |\nabla^m u| - \int_{\Omega} |\nabla^m v| \right| + \left| \int_{\Omega} f(\nabla^m u) - \int_{\Omega} f(\nabla^m v) \right|$$

with $f(X) := \sqrt{1+|X|^2} - 1$ for $X \in S^m(\mathbb{R}^n)$.

We now give the **proof of Theorem 1.1** which states that smooth functions are dense in $BV^m(\Omega) \cap L^q(\Omega - D)$ with respect to this distance and the L^q -norm.

ad (a). We start with the following special case: Assume that Ω is a cuboid in \mathbb{R}^n ,

$$\Omega = (a_1, b_1) \times \dots \times (a_n, b_n)$$

and $\Omega - D$ is given by

$$\Omega - D = \{ (x_1, ..., x_n) \in \Omega \mid x_n < \phi(x_1, ..., x_{n-1}) \},\$$

where $\phi : (a_1, b_1) \times ... \times (a_{n-1}, b_{n-1}) \to (a_n, b_n)$ is a Lipschitz continuous function with Lipschitz constant $L := \text{Lip}(\phi)$. Consider now the sets

$$\Omega_{-1} := \emptyset,$$

$$\Omega_i := \left\{ x \in \Omega \, \big| \, \operatorname{dist}(x, \partial \Omega) > \frac{1}{i+1} \right\}, \ i \in \mathbb{N}_0$$

and consider the covering of Ω through the open sets $A_j := \Omega_{j+1} - \overline{\Omega_{j-1}}$ for $j \in \mathbb{N}_0$. Let $(\eta_j)_{j=0}^{\infty} \subset C_0^{\infty}(\Omega)$ denote a partition of unity with respect to that covering, i.e. spt $\eta_j \Subset A_j$ and $\sum_{j=0}^{\infty} \eta_j \equiv 1$. Let further *C* denote the cone

$$C := \left\{ (x_1, ..., x_n) \in \mathbb{R}^n \, \big| \, x_n < -L | (x_1, ..., x_{n-1}, 0) | \right\}$$

and ρ_{ε} a symmetric mollifier supported in the ball $B_{\varepsilon}(0)$. Note that for any $x \in \partial(\Omega - D)$ we have $(C + x) \cap \Omega \subset \Omega - D$. For a given $\delta > 0$, we will construct a function $\varphi_{\delta} \in C^{\infty}(\Omega)$ such that

$$\|u - \varphi_{\delta}\|_{m,p;\Omega} + \|u - \varphi_{\delta}\|_{q;\Omega-D} < \delta.$$

$$(2.1)$$

To this purpose, we consider $u_j := \eta_j u$ and the shifted functions

$$u_j^{h_j} := u_j(x_1, ..., x_n - h_j)$$

for $h_j > 0$ s.t. $\operatorname{spt}(\eta_j) + h_j \Subset \Omega$. Since translations act continuously on $L^p(\mathbb{R}^n)$ (and hence, so they do on Sobolev spaces), we can choose a decreasing sequence of positive numbers h_j such that $\operatorname{spt} u_j + h_j \Subset A_j$ and

$$\|u_j - u_j^{h_j}\|_{m,p;\Omega} + \|u_j - u_j^{h_j}\|_{q;\Omega-D} < \delta 2^{-(j+2)}.$$
(2.2)

Further we can select a decreasing sequence of positive numbers ε_i which satisfy

$$B_{\varepsilon_i}(0) - (0, ..., 0, h_j) \in C,$$
 (2.3)

$$\left(\operatorname{spt}(\eta_j) + h_j\right)^{\varepsilon_j} \Subset A_{j+1} - A_{j-1} \tag{2.4}$$

and in addition

$$\|\rho_{\varepsilon_j} * u_j^{h_j} - u_j^{h_j}\|_{m,p;\Omega} + \|\rho_{\varepsilon_j} * u_j^{h_j} - u_j^{h_j}\|_{q;\Omega-D} < \delta 2^{-(j+2)}.$$
 (2.5)

Note that due to (2.3) it actually holds $\rho_{\varepsilon_j} * u_j^{h_j} \in L^q(\Omega - D)$ since $u_j^{h_j}$ is q-integrable on $\{x \in \Omega \mid x_n < \phi(x_1, ..., x_{n-1}) + h_j\}$. By (2.2) and (2.5) we have

$$\|u_j - \rho_{\varepsilon_j} * u_j^{h_j}\|_{m,p;\Omega} + \|u_j - \rho_{\varepsilon_j} * u_j^{h_j}\|_{q;\Omega-D} < \delta 2^{-(j+1)}.$$
 (2.6)

Consequently, $\varphi_{\delta} := \sum_{j=0}^{\infty} \rho_{\varepsilon_j} * u_j^{h_j}$ is a smooth function that satisfies (2.1). Furthermore, by our construction we find that $u - \varphi_{\delta} \in \mathring{W}^{m,p}(\Omega)$.

Now we consider the general case. Let $\delta > 0$ be given. We can extend u outside of Ω to a function in $W^{m,p}(\mathbb{R}^n)$ and therefore, w.l.o.g. assume that $\Omega - D$ is a compact subset of Ω . We cover $\partial(\Omega - D)$ by a finite number of cuboids Q_1, \ldots, Q_N such that $(\Omega - D) \cap Q_i$ lies beneath the graph of a Lipschitz function, i.e. on each of the cuboids we are in the situation of our special case. Starting with Q_1 , we can thus find a smooth function $\varphi_1 \in C^{\infty}(Q_1)$ such that

$$||u - \varphi_1||_{m,p;Q_1} + ||u - \varphi_1||_{q;(\Omega - D) \cap Q_1} < \frac{\delta}{2N}$$

and since $u - \varphi_1 \in \mathring{W}^{m,p}(Q_1)$, the function u_1 defined through

$$u_1(x) := \begin{cases} u(x), & x \in \Omega - Q_1 \\ \varphi_1(x), & x \in Q_1 \end{cases}$$

is in $W^{m,p}(\Omega) \cap L^q(\Omega - D)$ and such that

$$||u - u_1||_{m,p;\Omega} + ||u - u_1||_{q;\Omega-D} < \frac{\delta}{2N}.$$

Continuing this process on Q_2 with u replaced by u_1 and so on, we finally end up with a function u_N for which it holds

$$||u - u_N||_{m,p;\Omega} + ||u - u_N||_{q;\Omega-D} < \frac{\delta}{2}$$

and which is smooth in an open neighbourhood U of $\partial(\Omega - D)$. Choosing an open set $U_c \in U$ with $\partial(\Omega - D) \subset U_c$ and such that ∂U_c is sufficiently regular, we get our desired approximating function by patching a suitable $C^{\infty}(\overline{\Omega} - \overline{U_c})$ -approximation of $u|_{\overline{\Omega} - \overline{U_c}}$ with $u_N|_{U_c}$.

ad (b). We keep the notation from part (a). Again it will suffice to prove the claim in the special case of Ω being an *n*-dimensional cuboid and $\partial(\Omega - D)$ being the graph of a Lipschitz continuous function. For a given $\delta > 0$ we choose a sequence $(h_j)_{j=0}^{\infty}$ of positive numbers such that $\operatorname{spt}(\eta_j) + h_j \Subset A_j$ and the following conditions are satisfied:

$$\|(\eta_j u)^{h_j} - \eta_j u\|_{m-1,1;\Omega} + \|(\eta_j u)^{h_j} - \eta_j u\|_{q;\Omega-D} < \delta 2^{-(j+2)},$$
(2.7)

$$\left\| \left(\nabla^m(\eta_j u) - \eta_j \nabla^m u \right)^{h_j} - \left(\nabla^m(\eta_j u) - \eta_j \nabla^m u \right) \right\|_{1;\Omega} < \delta 2^{-(j+2)}.$$
(2.8)

Note that $\nabla^m(\eta_j u) - \eta_j \nabla^m u \in L^1(\Omega)$ so that we can require h_j to satisfy (2.8). Furthermore, since $\sum_{j=0}^{\infty} \eta_j \equiv 1$ on Ω it holds $\sum_{j=0}^{\infty} \left(\nabla^m(\eta_j u) - \eta_j \nabla^m u \right) \equiv 0$. Consider now

$$u_{\delta} := \sum_{j=0}^{\infty} (\eta_j u)^{h_j}.$$

We claim that u_{δ} approximates u in $BV^m(\Omega) \cap L^q(\Omega - D)$ with respect to the metric d(.,.). First, from (2.7) it follows

$$||u - u_{\delta}||_{m-1,1;\Omega} + ||u - u_{\delta}||_{q;\Omega-D} < \delta/2.$$

Let us compute the total variation of $\nabla^m u_{\delta}$. For a measure μ let μ^{h_j} denote the image measure under translation by h_j in the *n*-th coordinate direction.

By Proposition 3.18 in [AFP] it holds $\nabla^m(\eta_j u)^{h_j} = (\nabla^m(\eta_j u))^{h_j}$ and thus $(\operatorname{recall}\sum_{j=0}^{\infty}\eta_j \equiv 1)$ $\nabla^m u_{\delta} = \sum_{j=0}^{\infty} \nabla^m(\eta_j u)^{h_j} = \sum_{j=0}^{\infty} (\nabla^m(\eta_j u))^{h_j}$ $= \sum_{j=0}^{\infty} [(\eta_j \nabla^m u)^{h_j} + (\nabla^m(\eta_j u) - \eta_j \nabla^m u)^{h_j} (\mathcal{L}^n \sqcup \Omega)]$ $= \sum_{j=0}^{\infty} [(\eta_j \nabla^m u)^{h_j} + \{(\nabla^m(\eta_j u) - \eta_j \nabla^m u)^{h_j} - (\nabla^m(\eta_j u) - \eta_j \nabla^m u)\} (\mathcal{L}^n \sqcup \Omega)]$

so that

$$\begin{split} &\int_{\Omega} |\nabla^m u_{\delta}| \leq \sum_{j=0}^{\infty} \int_{\Omega} \left| (\eta_j \nabla^m u)^{h_j} \right| \\ &+ \sum_{j=0}^{\infty} \int_{\Omega} \left| (\nabla^m (\eta_j u) - \eta_j \nabla^m u)^{h_j} - (\nabla^m (\eta_j u) - \eta_j \nabla^m u) \right| dx \\ &\leq \sum_{j=0}^{\infty} \int_{\Omega} \left| (\eta_j \nabla^m u)^{h_j} \right| + \frac{\delta}{2} = \sum_{j=0}^{\infty} \int_{\Omega} \eta_j |\nabla^m u| + \frac{\delta}{2} = \int_{\Omega} |\nabla^m u| + \frac{\delta}{2} \end{split}$$

Thus, for a sequence $\delta \downarrow 0$ we find a corresponding sequence of functions u_{δ} for which $\limsup_{\delta \to 0} |\nabla^m u_{\delta}|(\Omega) \leq |\nabla^m u|(\Omega)$ and it follows from the lower semicontinuity of the total variation and $u_{\delta} \to u$ in $W^{m-1,1}(\Omega)$ that

$$|\nabla^m u_\delta|(\Omega) \to |\nabla^m u|(\Omega).$$

Moreover, we claim that it even holds

$$(\nabla^m u_\delta)^a \to (\nabla^m u)^a$$
 in $L^1(\Omega, S^m(\mathbb{R}^n))$

for $\delta \downarrow 0$ where, as before, for a tensor valued measure μ on Ω we denote by $\mu = \mu^a (\mathcal{L}^n \sqcup \Omega) + \mu^s$ its Lebesgue decomposition. To justify this, we first observe that on Ω_i we have

$$\nabla^m u_\delta|_{\Omega_i} = \left(\left. \sum_{j=0}^i \left(\nabla^m (\eta_j u) \right)^{h_j} \right) \right|_{\Omega}$$

and since for two measures μ and ν it holds $(\mu + \nu)^a = \mu^a + \nu^a$ as well as $(\mu^{h_j})^a = (\mu^a)^{h_j}$, it follows

$$\chi_{\Omega_i}(\nabla^m u_\delta)^a = \chi_{\Omega_i}\left(\sum_{j=0}^i \left(\nabla^m (\eta_j u)^a\right)^{h_j}\right) = \chi_{\Omega_i}\left(\sum_{j=0}^\infty \left(\nabla^m (\eta_j u)^a\right)^{h_j}\right).$$

But due to $\chi_{\Omega_i}(\nabla^m u_\delta)^a \xrightarrow{i \to \infty} (\nabla^m u_\delta)^a$ in $L^1(\Omega, S^m(\mathbb{R}^n))$, it holds

$$(\nabla^m u_\delta)^a = \sum_{j=0}^\infty \left(\nabla^m (\eta_j u)^a \right)^{h_j}.$$

Since $\nabla^m(\eta_j u)^a \in L^1(\Omega, S^m(\mathbb{R}^n))$, we can choose h_j small enough such that

$$\| \left(\nabla^m (\eta_j u)^a \right)^{h_j} - \nabla^m (\eta_j u)^a \|_{1;\Omega} < \delta 2^{-(j+1)}$$

and therefore $\|(\nabla^m u_{\delta})^a - (\nabla^m u)^a\|_{1;\Omega} < \delta$. From $(\nabla^m u_{\delta})^a \to (\nabla^m u)^a$ in $L^1(\Omega)$ it follows

$$\int_{\Omega} \sqrt{1 + |(\nabla^m u_{\delta})^a|^2} \, dx \xrightarrow{\delta \downarrow 0} \int_{\Omega} \sqrt{1 + |(\nabla^m u)^a|^2} \, dx \tag{2.9}$$

and due to $|\nabla^m u_\delta|(\Omega) \to |\nabla^m u|(\Omega)$ and $|(\nabla^m u_\delta)^a|(\Omega) \to |(\nabla^m u)^a|(\Omega)$ it also holds

$$|(\nabla^m u_\delta)^s|(\Omega) \to |(\nabla^m u)^s|(\Omega).$$
(2.10)

Together with (2.9), this proves $\sqrt{1+|\nabla^m u_\delta|^2}(\Omega) \to \sqrt{1+|\nabla^m u|^2}(\Omega)$ for $\delta \downarrow 0$.

Now choose h_j such that

$$d(u, u_{\delta}) + \|u - u_{\delta}\|_{q;\Omega-D} < \delta/2.$$

Note that $\eta_j u_{\delta}$ is q-integrable on $\{x \in \Omega \mid x_n < \phi(x_1, ..., x_{n-1}) + \tilde{h}_j\}$ with

$$\tilde{h}_j := \min\{h_{j-1}, h_j, h_{j+1}\}.$$

As outlined in [DT] (after possibly adjusting Ω_0), we can choose a sequence of positive numbers $(\varepsilon_j)_{j=1}^{\infty}$ such that the smooth functions

$$\tilde{u}_{\delta} := \sum_{j=0}^{\infty} \rho_{\varepsilon_j} * (\eta_j u_{\delta})$$

approximate u_{δ} in the sense that $d(u_{\delta}, \tilde{u}_{\delta}) < \delta/4$. Further, we can choose ε_j small enough to fulfill $B_{\varepsilon_j}(0) - (0, ..., 0, \tilde{h}_j) \Subset C$ and $\|u_{\delta} - \tilde{u}_{\delta}\|_{q;\Omega} < \delta/4$. Altogether, \tilde{u}_{δ} approximates u as required. The general case now follows as in part (a). \Box

3 Generalized and dual solutions

In this section we are dealing with Theorems 1.2 and 1.3 concerning generalized solutions in $BV^m(\Omega)$ and dual solutions, respectively. Just for notational simplicity, we will confine ourselves to the case m = 2 even though all results apply to

arbitrary $m \in \mathbb{N}$ as well and abbreviate $J := J^2$ in (1.12). As already mentioned in the introduction, both theorems will follow basically from the same arguments as in the first order case using the density result Theorem 1.1. Thus, we are not going to give the details of the proofs but rather advise the reader to consult the work [BF4] or [FT] and restrict ourselves to an outline of how the density result is involved in each case.

ad Theorem 1.2. First, using part (b) of Lemma 2.2 it is clear that any Kminimizing sequence (u_k) is uniformly bounded in $BV^2(\Omega) \cap L^2(\Omega - D)$ and hence, by the BV^2 -compactness theorem and after passing to a suitable subsequence, there is a function $u \in BV^2(\Omega)$ such that $u_k \to u$ in $W^{1,1}(\Omega)$ and a.e. on Ω . Furthermore, by an application of Fatou's lemma we see that in fact $u \in$ $BV^2(\Omega) \cap L^2(\Omega - D)$. Note that we have the following generalization of Lemma 3.1 in [FT], which is a special case of the continuity theorem by Reshetnyak (see [Re] or [AG] for a corrected version; compare also [BS], Theorem 2.4 and Remark 2.5):

Lemma 3.1 For $w \in BV^2(\Omega)$ let

$$\tilde{K}[w] := \int_{\Omega} F\left((\nabla^2 w)^a\right) dx + \int_{\Omega} F^{\infty}\left(\frac{d(\nabla^2 w)^s}{d|(\nabla^2 w)^s|}\right) d|(\nabla^2 w)^s|.$$

(a) Suppose $w_k, w \in BV^2(\Omega)$ are such that $w_k \to w$ in $W^{1,1}(\Omega)$ for $k \to \infty$. Then

$$\tilde{K}[w] \le \liminf_{k \to \infty} \tilde{K}[w_k]. \tag{3.1}$$

(b) If we know in addition

the

$$\int_{\Omega} \sqrt{1 + |\nabla^2 w_k|^2} \to \int_{\Omega} \sqrt{1 + |\nabla^2 w|^2} \quad \text{for } k \to \infty,$$
$$n \ \tilde{K}[w] = \lim_{k \to \infty} \tilde{K}[w_k].$$

Hence, by (3.1) we see that our limit function u is in fact a minimizer of the generalized functional K and from part (b) of the above lemma in combination with our density Theorem 1.1 (b) we conclude by the same reasoning as in [FT], that the infima of J on $W^{2,1}(\Omega) \cap L^2(\Omega - D)$ and K on $BV^2(\Omega) \cap L^2(\Omega - D)$ coincide. The remaining parts of Theorem 1.2 are proved following the lines of [BF4].

ad Theorem 1.3. As in the first order case, we will obtain a maximizer of the dual functional R from a sequence of solutions to a family of regularized problems. For $1 > \delta > 0$ we consider

$$J_{\delta}[u] := \int_{\Omega} F_{\delta}(\nabla^2 u) \, dx + \frac{\lambda}{2} \int_{\Omega-D} |u - f|^2 \, dx = \delta \int_{\Omega} |\nabla^2 u|^2 \, dx + I[u].$$

where

$$F_{\delta}(P) := \delta |P|^2 + F(P) \text{ for } P \in S^2(\mathbb{R}^n).$$

Then we have

Lemma 3.2 (a) The problem $J_{\delta} \to \min$ in $W^{2,2}(\Omega)$ admits a unique solution u_{δ} .

(b) We have the uniform bound

$$\sup_{\delta>0} \|u_{\delta}\|_{2,1;\Omega} < \infty. \tag{3.2}$$

(c) It holds (not necessarily uniform in δ)

$$u_{\delta} \in W^{3,2}_{\mathrm{loc}}(\Omega).$$

Proof. (a): For fixed δ consider a J_{δ} -minimizing sequence $v_k \in W^{2,2}(\Omega)$ for which we have

$$\sup_{k} \|\nabla^2 v_k\|_{2;\Omega} < \infty, \tag{3.3}$$

$$\sup_{k} \|v_k\|_{2;\Omega-D} < \infty. \tag{3.4}$$

Thus, by quoting Lemma 2.2 it is

$$\sup_{k} \|v_k\|_{2,2;\Omega} < \infty.$$
(3.5)

After passing to a subsequence we may therefore assume $v_k \rightarrow : \overline{v}$ in $W^{2,2}(\Omega)$ for a function \overline{v} from this space and standard results on lower semicontinuity imply the J_{δ} -minimality of \overline{v} . If \tilde{v} denotes a second J_{δ} -minimizer, then the structure of J_{δ} clearly implies $\nabla^2 \tilde{v} = \nabla^2 \overline{v}$ on Ω together with $\tilde{v} = \overline{v}$ on $\Omega - D$, and since we assume $\mathcal{L}^2(\Omega - D) > 0$ we get that $\tilde{v} = \overline{v}$ on Ω . Thus (a) of Lemma 3.2 is established.

(b): We essentially adopt the arguments used in part (a): in place of (3.3) and

(3.4) it holds

$$\sup_{\delta > 0} \|\nabla^2 u_\delta\|_{1;\Omega} < \infty, \tag{3.6}$$

$$\sup_{\delta>0} \|u_{\delta}\|_{2;\Omega-D} < \infty, \tag{3.7}$$

$$\sup_{\delta>0} \delta \int_{\Omega} |\nabla^2 u_{\delta}|^2 \, dx < \infty, \tag{3.8}$$

which is a consequence of $J_{\delta}[u_{\delta}] \leq J_{\delta}[0] = \frac{\lambda}{2} \int_{\Omega-D} f^2 dx$. The $W^{2,1}(\Omega)$ -version of Lemma 2.2 then yields

$$\sup_{\delta>0} \|\nabla u_{\delta}\|_{1;\Omega} < \infty \tag{3.9}$$

and

$$\sup_{\delta>0} \|u_{\delta}\|_{1;\Omega} < \infty.$$
(3.10)

Now our claim (3.2) follows from (3.6), (3.9) and (3.10). (c): This is a standard application of the difference quotient technique (compare, e.g. [BF1], 'Step 2' on p. 353).

By the compactness property of $BV^2(\Omega)$ (cf. Lemma 2.1) and (3.2) we thus infer that there is a function $u \in BV^2(\Omega)$ such that for a suitable sequence $\delta \downarrow 0$ it holds $u_{\delta} \to u$ in $W^{1,1}(\Omega)$. Furthermore, an application of Fatou's Lemma gives $u \in BV^2(\Omega) \cap L^2(\Omega - D)$. In view of the duality relation stated in Theorem 1.3 (b) it is reasonable to consider $\sigma_{\delta} := DF_{\delta}(\nabla^2 u_{\delta})$ and $\tau_{\delta} := DF(\nabla^2 u_{\delta})$ and to investigate their limiting behavior as $\delta \downarrow 0$. Indeed, by the same arguments as in [BF4] we can verify that (for a subsequence) σ_{δ} has a weak limit $\sigma \in L^2(\Omega, S^2(\mathbb{R}^n))$ and τ_{δ} has a weak-*-limit in $L^{\infty}(\Omega, S^2(\mathbb{R}^n))$. Moreover, it holds $\sigma = \tau$ a.e.

Our density Theorem 1.1 (a) comes into play when proving that τ in fact maximizes R. Revising the steps of the proof in [BF4], we find that the critical point is exactly the following: after passing to the limit $\delta \downarrow 0$ in the Euler-Lagrange equation satisfied by the J_{δ} -minimizer u_{δ}

$$\delta \int_{\Omega} \nabla^2 u_{\delta} : \nabla^2 \varphi \, dx + \int_{\Omega} \tau_{\delta} : \nabla^2 \varphi \, dx + \lambda \int_{\Omega - D} (u_{\delta} - f) \varphi \, dx = 0, \qquad (3.11)$$

which holds for all $\varphi \in W^{2,2}(\Omega)$, we obtain (recall (3.8) as well as the definition of u)

$$\int_{\Omega} \tau : \nabla^2 \varphi \, dx + \lambda \int_{\Omega - D} (u - f) \varphi \, dx = 0.$$

We actually need the validity of this equation for all φ in the domain of definition of J, i.e. for functions $\varphi \in W^{2,1}(\Omega) \cap L^2(\Omega - D)$. But this can easily be obtained by approximating $\varphi \in W^{2,1}(\Omega) \cap L^2(\Omega - D)$ with a sequence of smooth functions $(\varphi_k) \subset C^{\infty}(\overline{\Omega})$ in the sense of Theorem 1.1 (a). All the remaining statements of Theorem 1.3 can be verified without further difficulties following the lines of [BF4].

4 Partial regularity: proof of Theorem 1.4

As before, for the sake of simplicity we shall confine ourselves to the case m = 2and remark, that throughout this section summation convention with respect to Greek indices is applied. In order to carry out the calculations during the proof of Theorem 1.4, we rely on the δ -approximation as introduced in the preceding section, cf. Lemma 3.2. The next lemma is of crucial importance:

Lemma 4.1

Let the assumptions of Theorem 1.4 hold, in particular we have (1.16) with parameter $\mu \in (1, \frac{3}{2})$ in case $D \neq \emptyset$ and $\mu \in (1, 2)$, if the case $D = \emptyset$ is considered. Then (with u_{δ} as in Lemma 3.2) it holds

$$\varphi_{\delta} := \left(1 + |\nabla^2 u_{\delta}|\right)^{1 - \frac{\mu}{2}} \in W^{1,2}_{\text{loc}}(\Omega) \text{ uniformly in } \delta, \tag{4.1}$$

which means

$$\sup_{\delta>0} \|\varphi_{\delta}\|_{1,2;\Omega^*} = c(\Omega^*) < \infty$$

for any subdomain $\Omega^* \subseteq \Omega$. Moreover, we have the uniform estimate

$$\sup_{\delta>0} \int_{\Omega^*} D^2 F_{\delta}(\nabla^2 u_{\delta}) \left(\partial_{\alpha} \nabla^2 u_{\delta}, \partial_{\alpha} \nabla^2 u_{\delta} \right) dx \le c(\Omega^*) < \infty.$$
(4.2)

Accepting Lemma 4.1 for the moment, we present the

proof of Theorem 1.4 part (a) and (b). As seen in section 3, due to (3.2) there is a function $u \in BV^2(\Omega)$ such that (for a suitable sequence $\delta \to 0$) we have $u_{\delta} \to u$ in $W^{1,1}(\Omega)$ (and even stronger convergences by the embedding theorem valid for $BV^2(\Omega)$). Quoting (4.1) we find for any $p < \infty$

$$\nabla^2 u_{\delta} \in L^p_{\text{loc}}(\Omega, S^2(\mathbb{R}^2)) \text{ uniformly in } \delta, \tag{4.3}$$

and by (4.3) it is immediate that

$$u \in W^{2,p}_{\text{loc}}(\Omega), \ p < \infty.$$

$$(4.4)$$

The estimate (4.2) together with the condition of μ -ellipticity (1.16) implies

$$\sup_{\delta>0} \int_{\Omega^*} \left(1 + |\nabla^2 u_\delta| \right)^{-\mu} |\nabla^3 u_\delta|^2 \, dx \le c(\Omega^*) < \infty.$$

For $s \in (1, 2)$, in connection with (4.3) this yields

$$\int_{\Omega^{*}} |\nabla^{3} u_{\delta}|^{s} dx = \int_{\Omega^{*}} (1 + |\nabla^{2} u_{\delta}|)^{-\mu \frac{s}{2}} |\nabla^{3} u_{\delta}|^{s} (1 + |\nabla^{2} u_{\delta}|)^{\mu \frac{s}{2}} dx$$

$$\leq \left(\int_{\Omega^{*}} (1 + |\nabla^{2} u_{\delta}|)^{-\mu} |\nabla^{3} u_{\delta}|^{2} dx \right)^{\frac{s}{2}} \left(\int_{\Omega^{*}} (1 + |\nabla^{2} u_{\delta}|)^{\frac{\mu s}{2-s}} dx \right)^{\frac{2-s}{2}}$$

$$\leq c(\Omega^{*}) < \infty,$$

thus

$$\sup_{\delta>0} \|u_{\delta}\|_{3,s;\Omega^*} \le c(s,\Omega^*) < \infty \quad \forall s < 2$$

and we therefore have strong convergence $u_{\delta} \to u$ in $W^{2,p}_{\text{loc}}(\Omega)$. All in all, we find that the following convergences hold true:

$$\begin{cases} u_{\delta} \to u \text{ in } W^{3,s}_{\text{loc}}(\Omega), \ s < 2, \\ u_{\delta} \to u \text{ in } W^{2,p}_{\text{loc}}(\Omega), \ p < \infty, \\ \varphi_{\delta} \to \varphi \text{ in } W^{1,2}_{\text{loc}}(\Omega) \end{cases}$$

with $\varphi = \left(1 + |\nabla^2 u|\right)^{1 - \frac{\mu}{2}}$, so that

$$(1+|\nabla^2 u|)^{1-\frac{\mu}{2}} \in W^{1,2}_{\text{loc}}(\Omega).$$
 (4.5)

At the same time we have $W^{2,p}_{\text{loc}}(\Omega) \cap BV^2(\Omega) \subset W^{2,1}(\Omega)$ so that

$$u \in W^{2,1}(\Omega) \tag{4.6}$$

on account of (4.4). Thus J[u] is well defined (recall (1.12) and $J = J^2$) and by lower semicontinuity it holds

$$J[u] \le \liminf_{\delta \to 0} J[u_{\delta}] \tag{4.7}$$

which is a consequence of $u_{\delta} \rightarrow u$ in $W^{2,p}_{\text{loc}}(\Omega)$ for any finite p. Quoting the J_{δ} -minimality of u_{δ} we deduce from (4.7)

$$J[u] \le \liminf_{\delta \to 0} J_{\delta}[u_{\delta}] \le J[v]$$

for any $v \in W^{2,2}(\Omega)$. Therefore it holds

$$J[u] \le J[w], \ w \in W^{2,1}(\Omega),$$

since $||w - v_k||_{2,1;\Omega} \to 0$ for a suitable sequence $v_k \in W^{2,2}(\Omega)$. Altogether it is shown (recall (4.6)) that u solves (1.12). Assume that we have another minimizer $\tilde{u} \neq u$ on a set of positive measure. From strict convexity we infer $\nabla^2 \tilde{u} = \nabla^2 u$ a.e. on Ω as well as $\tilde{u} = u$ a.e. on $\Omega - D$. Hence u and \tilde{u} differ by a polynomial of degree at most 1 which vanishes on $\Omega - D$. Since $\mathcal{L}^2(\Omega - D) > 0$ it follows $\tilde{u} = u$ a.e. This proves (a) of Theorem 1.4. For part (b) we just refer to (4.4). \Box

We proceed with the

proof of Lemma 4.1. From Lemma 3.2 (c) and the J_{δ} -minimality of u_{δ} it follows ($\alpha = 1, 2$)

$$\int_{\Omega} D^2 F_{\delta}(\nabla^2 u_{\delta}) (\partial_{\alpha} \nabla^2 u_{\delta}, \nabla^2 v) \, dx = \lambda \int_{\Omega - D} (u_{\delta} - f) \partial_{\alpha} v \, dx \tag{4.8}$$

for any $v \in W^{2,2}(\Omega)$ such that spt v is compactly contained in Ω . Let us fix a disk $B_{2r}(x_0)$ contained in some arbitrary subregion $\Omega^* \subseteq \Omega$. Consider a cut-off function η such that

$$\begin{cases} 0 \le \eta \le 1, \text{ spt } \eta \subset B_{2r}(x_0), \\ \eta = 1 \text{ on } B_r(x_0), \ |\nabla^l \eta| \le cr^{-l}, \ l = 1, 2 \end{cases}$$

and choose $v = \eta^6 \partial_{\alpha} u_{\delta}$ in equation (4.8). Abbreviating

$$T_1 := \int_{\Omega} D^2 F_{\delta}(\nabla^2 u_{\delta}) (\partial_{\alpha} \nabla^2 u_{\delta}, \partial_{\alpha} \nabla^2 u_{\delta}) \eta^6 dx$$
(4.9)

$$T_2 := \int_{\Omega} D^2 F_{\delta}(\nabla^2 u_{\delta}) (\partial_{\alpha} \nabla^2 u_{\delta}, 2\nabla \eta^6 \otimes \nabla \partial_{\alpha} u_{\delta}) \, dx, \qquad (4.10)$$

$$T_3 := \int_{\Omega} D^2 F_{\delta}(\nabla^2 u_{\delta}) (\partial_{\alpha} \nabla^2 u_{\delta}, \nabla^2 \eta^6 \partial_{\alpha} u_{\delta}) \, dx \tag{4.11}$$

with an obvious meaning of " \otimes ", we obtain from (4.8)-(4.11)

$$T_1 + T_2 + T_3 = \lambda \int_{\Omega - D} (u_{\delta} - f) \partial_{\alpha} (\eta^6 \partial_{\alpha} u_{\delta}).$$
(4.12)

Applying the Cauchy-Schwarz inequality to the bilinear form $D^2 F_{\delta}(\nabla^2 u_{\delta})$ we get

$$\begin{aligned} |T_2| &\leq \int_{\Omega} \left(D^2 F_{\delta}(\nabla^2 u_{\delta}) \left(\eta^3 \partial_{\alpha} \nabla^2 u_{\delta}, \eta^3 \partial_{\alpha} \nabla^2 u_{\delta} \right) \right)^{\frac{1}{2}} \\ & \cdot \left(D^2 F_{\delta}(\nabla^2 u_{\delta}) \left(12\eta^2 \nabla \eta \otimes \partial_{\alpha} \nabla u_{\delta}, 12\eta^2 \nabla \eta \otimes \partial_{\alpha} \nabla u_{\delta} \right) \right)^{\frac{1}{2}} dx, \end{aligned}$$

hence, by Young's inequality

$$|T_2| \le \varepsilon T_1 + c(\varepsilon) \int_{\Omega} \left| D^2 F_{\delta}(\nabla^2 u_{\delta}) \right| \eta^4 |\nabla \eta|^2 |\nabla^2 u_{\delta}|^2 dx$$

=: $\varepsilon T_1 + c(\varepsilon) T_4.$

In T_4 we make use of inequality (1.16), the bound stated in (3.2) and the fact that

$$\sup_{\delta>0} \delta \int_{\Omega} |\nabla^2 u_{\delta}|^2 \, dx < \infty$$

(see (3.8)) with the result $T_4 \leq c(\eta)$, so that

$$|T_2| \le \varepsilon T_1 + c(\varepsilon, \eta). \tag{4.13}$$

In a similar way we obtain

$$|T_3| \le \varepsilon T_1 + c(\varepsilon, \eta) \int_{\Omega} |D^2 F_{\delta}(\nabla^2 u_{\delta})| |\nabla u_{\delta}|^2 dx$$

and since for example

$$\sup_{\delta>0} \|\nabla u_{\delta}\|_{2;\Omega} < \infty$$

on account of (3.2) and Sobolev's embedding theorem, we find

$$|T_3| \le \varepsilon T_1 + c(\varepsilon, \eta). \tag{4.14}$$

Putting together (4.12)-(4.14) and choosing $\varepsilon = \frac{1}{4}$ it follows

$$\int_{B_{2r}(x_0)} D^2 F_{\delta}(\nabla^2 u_{\delta}) (\partial_{\alpha} \nabla^2 u_{\delta}, \partial_{\alpha} \nabla^2 u_{\delta}) \eta^6 dx$$

$$\leq c(\eta) + 2\lambda \int_{\Omega - D} (u_{\delta} - f) \partial_{\alpha} (\eta^6 \partial_{\alpha} u_{\delta}) dx.$$

$$\underbrace{=: T_5}$$

$$(4.15)$$

Case 1: $D = \emptyset$

It holds

$$T_{5} = \int_{B_{2r}(x_{0})} u_{\delta} \partial_{\alpha} (\eta^{6} \partial_{\alpha} u_{\delta}) \, dx - \int_{B_{2r}(x_{0})} f \partial_{\alpha} (\eta^{6} \partial_{\alpha} u_{\delta}) \, dx$$
$$= -\int_{B_{2r}(x_{0})} \eta^{6} |\nabla u_{\delta}|^{2} \, dx - \int_{B_{2r}(x_{0})} f \partial_{\alpha} (\eta^{6} \partial_{\alpha} u_{\delta}) \, dx,$$

and by the boundedness of f we get from (4.15)

$$\int_{B_{2r}(x_0)} D^2 F_{\delta}(\nabla^2 u_{\delta}) (\partial_{\alpha} \nabla^2 u_{\delta}, \partial_{\alpha} \nabla^2 u_{\delta}) \eta^6 dx + 2\lambda \int_{B_{2r}(x_0)} \eta^6 |\nabla u_{\delta}|^2 dx$$

$$\leq c(\eta) + \|f\|_{\infty;\Omega} \left\{ \int_{B_{2r}(x_0)} |\nabla \eta^6| |\nabla u_{\delta}| dx + \int_{B_{2r}(x_0)} \eta^6 |\nabla^2 u_{\delta}| dx \right\}.$$
(4.16)

Clearly all terms on the right-hand side of (4.16) are bounded independent of δ , hence (4.16) implies

$$\sup_{\delta>0} \int_{\Omega^*} D^2 F_{\delta}(\nabla^2 u_{\delta}) (\partial_{\alpha} \nabla^2 u_{\delta}, \partial_{\alpha} \nabla^2 u_{\delta}) \, dx < \infty.$$
(4.17)

Recalling the definition of φ_{δ} stated in (4.1) it is immediate that

$$\sup_{\delta>0} \|\varphi_{\delta}\|_{2;\Omega} < \infty. \tag{4.18}$$

At the same time we obtain from (1.16) and (4.17)

$$\sup_{\delta>0} \|\nabla \varphi_{\delta}\|_{2;\Omega^*} < \infty,$$

which together with (4.18) proves our claims (4.1) and (4.2). We wish to note that the requirement $\mu < 2$ just enters through the fact that in the definition of φ_{δ} the exponent $1 - \frac{\mu}{2}$ must be positive.

Case 2: $D \neq \emptyset$

Again we look at the relevant item T_5 in (4.15) and recall that the part $\int_{\Omega-D} f \partial_{\alpha} (\eta^6 \partial_{\alpha} u_{\delta}) dx$ is uncritical since by (3.2) its absolute value can be bounded by a constant $c(\eta)$. So let

$$\widetilde{T}_5 := \int_{\Omega - D} u_{\delta} \partial_{\alpha} (\eta^6 \partial_{\alpha} u_{\delta}) \, dx$$

and observe

$$|\widetilde{T}_5| \le \int_{\Omega} |u_{\delta}| |\nabla \eta^6| |\nabla u_{\delta}| \, dx + \int_{\Omega} |u_{\delta}| \eta^6 |\nabla^2 u_{\delta}| \, dx =: T_6 + T_7. \tag{4.19}$$

From (3.2) and Sobolev's embedding theorem it is immediate that

$$T_6 \le c(\eta). \tag{4.20}$$

To the quantity T_7 we apply Young's inequality

$$T_{7} \leq c \left(\int_{\Omega} |u_{\delta}|^{\frac{\mu}{\mu-1}} \eta^{6} dx + \int_{\Omega} \eta^{6} |\nabla^{2} u_{\delta}|^{\mu} dx \right)$$

$$\leq c \left(1 + \int_{\Omega} \eta^{6} |\nabla^{2} u_{\delta}|^{\mu} dx \right)$$

$$\leq c \left(1 + \int_{\Omega} (\eta^{3} \psi_{\delta})^{2} dx \right)$$

$$(4.21)$$

with $\psi_{\delta} := \left(1 + |\nabla^2 u_{\delta}|\right)^{\frac{\mu}{2}}$. Sobolev's inequality yields

$$\int_{\Omega} (\eta^3 \psi_{\delta})^2 \, dx \le c \left(\int_{\Omega} |\nabla(\eta^3 \psi_{\delta})| \, dx \right)^2 \le c(\eta) + c \left(\int_{\Omega} \eta^3 |\nabla \psi_{\delta}| \, dx \right)^2, \quad (4.22)$$

where in the last step we used (3.2) together with $\mu < 2$. Observing (recall (4.1)) the relation

$$\psi_{\delta} = \varphi_{\delta}^{\frac{\mu}{2-\mu}}$$

we obtain

$$\int_{B_{2r}(x_0)} \eta^3 |\nabla \psi_{\delta}| \, dx \le c \int_{B_{2r}(x_0)} \eta^3 |\nabla \varphi_{\delta}| \varphi_{\delta}^{\frac{\mu}{2-\mu}-1} \, dx$$
$$\le c \left(\int_{B_{2r}(x_0)} \eta^6 |\nabla \varphi_{\delta}|^2 \, dx \right)^{\frac{1}{2}} \left(\int_{B_{2r}(x_0)} \varphi_{\delta}^{\frac{4\mu-4}{2-\mu}} \, dx \right)^{\frac{1}{2}}. \tag{4.23}$$

Inserting (4.23) into (4.22) and going back to (4.21) we obtain

$$T_7 \le c(\eta) + c \int_{B_{2r}(x_0)} \varphi_{\delta}^{\frac{4\mu-4}{2-\mu}} dx \int_{B_{2r}(x_0)} \eta^6 |\nabla \varphi_{\delta}|^2 dx.$$
(4.24)

Recalling (4.19) and (4.20), we deduce from (4.24)

$$\left|\widetilde{T}_{5}\right| \leq c(\eta) + c \int_{B_{2r}(x_0)} \varphi_{\delta}^{\frac{4\mu-4}{2-\mu}} dx \int_{B_{2r}(x_0)} \eta^{6} |\nabla\varphi_{\delta}|^{2} dx.$$

$$(4.25)$$

With (4.25) at hand we return to (4.15) observing first

$$|\nabla \varphi_{\delta}|^{2} \leq c D^{2} F_{\delta}(\nabla^{2} u_{\delta}) (\partial_{\alpha} \nabla^{2} u_{\delta}, \partial_{\alpha} \nabla^{2} u_{\delta}).$$

Second we note

$$\varphi_{\delta}^{\frac{4\mu-4}{2-\mu}} = \left(1 + |\nabla^2 u_{\delta}|\right)^{\frac{2-\mu}{2}\frac{4\mu-4}{2-\mu}} \sim |\nabla^2 u_{\delta}|^{2\mu-2}$$

with exponent $2\mu - 2 < 1$ on account of our assumption $\mu < \frac{3}{2}$ in Case 2. Thus, by (3.2) and by Hölder's inequality we obtain

$$\int_{B_{2r}(x_0)} \varphi_{\delta}^{\frac{4\mu-4}{2-\mu}} dx \le c\mathcal{L}^2 \left(B_{2r}(x_0) \right)^s$$

for some positive exponent s and (4.15) in combination with our previous results yields

$$\left(1 - c\mathcal{L}^2 \left(B_{2r}(x_0)\right)^s\right) \int_{B_{2r}(x_0)} \eta^6 D^2 F_\delta(\nabla^2 u_\delta) (\partial_\alpha \nabla^2 u_\delta, \partial_\alpha \nabla^2 u_\delta) \le c(\eta).$$

From this inequality we deduce: if we restrict ourselves to radii $r \leq r_0$ for some $r_0 > 0$ independent of δ , then it holds $\int_{B_{2r}(x_0)} |\nabla \varphi_\delta|^2 dx \leq c(r) < \infty$, thus (4.1) and (4.2) are established in Case 2.

We now turn to the

proof of Theorem 1.4 part (c). The basis for our further proof is the well known blow-up technique whose idea together with appropriate references is explained in the monograph [Gia]. We also suggest to consult the paper [EG]. Our arguments follow these ideas and their higher order version given in [AF], section 3, where now some adjustments become necessary due to the presence of the error term $\int_{\Omega-D} (u-f)^2 dx$ in our situation.

For disks $B_{\rho}(x) \Subset \Omega$ we define the excess function by

$$E(x,\rho) := \oint_{B_{\rho}(x)} \left| \nabla^2 u(y) - (\nabla^2 u)_{x,\rho} \right|^2 dy,$$

where $u \in W^{2,1}(\Omega)$ is the minimizer from part (a). Note, that due to part (b) of Theorem 1.4 the excess is well defined. By $(\nabla^2 u)_{x,\rho} := \int_{B_{\rho}(x)} \nabla^2 u(y) \, dy$ we denote the mean value of $\nabla^2 u$ on the disk $B_{\rho}(x)$. The essential step is to show the following excess-decay lemma:

Lemma 4.2 (Blow-up Lemma)

Given L > 0, define the constant $C^*(L)$ according to (4.36) below and set $C_* = C_*(L) := 2C^*(L)$. Then, for any $\tau \in (0, \frac{1}{2})$ there is an $\varepsilon = \varepsilon(L, \tau)$ such that whenever

$$|(\nabla^2 u)_{x,r}| \le L, \ E(x,r) + r \le \varepsilon, \tag{4.26}$$

then also

$$E(x,\tau r) \le \tau^2 C_*(L)(E(x,r)+r)$$
 (4.27)

for disks $B_r(x) \Subset \Omega$.

Remark 4.1(a) Due to Lebesgue's differentiation theorem, condition (4.26) is valid for \mathcal{L}^2 -almost all points $x \in \Omega$, i.e. the set

$$\Omega_0 := \left\{ x \in \Omega : \limsup_{r \to 0} |(\nabla^2 u)_{x,r}| < \infty \right\} \cap \left\{ x \in \Omega : \liminf_{r \to 0} E(x,r) = 0 \right\}$$

has full Lebesgue measure.

(b) That in fact ∇²u is Hölder continuous on Ω₀ and that Ω₀ is an open subset of Ω follows from Lemma 4.2 in a standard way, as e.g. outlined in detail on p. 95 ff. in the monograph [Gia]: by iteration, inequality (4.27) yields (0 < α < 1)</p>

$$E(x,\tau r) \le \tau^{2\alpha} (E(x,r)+r),$$

where τ is such that $C_*(L)\tau^{2-2\alpha} = 1$. This implies

$$E(x,\rho) \le c \left(\frac{\rho}{r}\right)^{2\alpha} \left(E(x,r)+r\right)$$

for all $\rho \leq r$ and from this inequality together with Morrey's integral characterization of Hölder continuity (cf. [Gia], chapter III, Theorem 1.3) we get our claim.

Indirect proof of the Blow-up Lemma. Fix L > 0. If the statement of the lemma is false, then there is a $\tau \in (0, \frac{1}{2})$ and a sequence $B_{r_k}(x_k) \Subset \Omega$ of disks with

$$\left| (\nabla^2 u)_{x_k, r_k} \right| \le L, \ E(x_k, r_k) + r_k =: \lambda_k^2 \to 0,$$
 (4.28)

but at the same time

$$E(x_k, \tau r_k) > \tau^2 C_*(L) \lambda_k^2. \tag{4.29}$$

We rescale the function u by setting

$$\begin{aligned} a_k &:= (u)_{x_k, r_k}, \ A_k &:= (\nabla u)_{x_k, r_k}, \ \Theta_k = (\nabla^2 u)_{x_k, r_k}, \\ u_k(z) &:= \frac{1}{\lambda_k r_k^2} \left[u(x_k + r_k z) - r_k A_k \cdot z - a_k - \frac{r_k^2}{2} \Theta_k(z, z) + \frac{r_k^2}{2} \oint_{B_1(0)} \Theta_k(y, y) dy \right], \end{aligned}$$

where $z \in B_1(0)$. These scalings are chosen in such a way that $(u_k)_{0,1} = 0$, $(\nabla u_k)_{0,1} = 0$, $(\nabla^2 u_k)_{0,1} = 0$ and we further have

$$\nabla u_k(z) = \frac{1}{\lambda_k r_k} \left[\nabla u(x_k + r_k z) - A_k - \frac{1}{2} r_k \nabla (\Theta_k^{\alpha\beta} z_\alpha z_\beta) \right],$$
$$\nabla^2 u_k(z) = \frac{1}{\lambda_k} \left[\nabla^2 u(x_k + r_k z) - \Theta_k \right]$$

as well as

$$\int_{B_1(0)} |\nabla^2 u_k(z)|^2 dz = \lambda_k^{-2} E(x_k, r_k) \leq_{(4.28)} 1.$$
(4.30)

The vanishing of the averages along with (4.30) and Poincaré's inequality yields (after passing to a suitable subsequence)

$$u_k \to \hat{u} \text{ in } W^{2,2}(B_1(0))$$
 (4.31)

and consequently

$$\lambda_k \nabla^2 u_k \to 0 \text{ in } L^2(B_1(0)) \text{ and a.e.}$$
 (4.32)

According to (4.28) we further have

$$\Theta_k \to : \Theta \tag{4.33}$$

for a 2×2 -matrix Θ . We claim that the function \hat{u} fulfills the following constant coefficient elliptic system (implying the smoothness of \hat{u}):

$$\int_{B_1(0)} D^2 F(\Theta)(\nabla^2 \hat{u}, \nabla^2 \psi) \, dz = 0 \,\,\forall \psi \in C_0^\infty(B_1(0)).$$
(4.34)

Fix ψ and set $\varphi(x) := \psi\left(\frac{x-x_k}{r_k}\right), x \in B_{r_k}(x_k)$. By the minimality of u, it holds

$$0 = \int_{\substack{B_{r_k}(x_k) \\ =: S_1}} DF(\nabla^2 u) : \nabla^2 \varphi \, dx + \lambda \int_{\substack{B_{r_k}(x_k) - D \\ =: S_2}} (u - f) \varphi \, dx$$

On any open subset $\Omega^* \subseteq \Omega$, both u and f are bounded (recall $u \in W^{3,s}_{\text{loc}}(\Omega)$, s < 2). Thus we can estimate S_2 by

$$|S_2| \le c \int_{B_{r_k}(x_k)} |\varphi| \, dx = c \int_{B_{r_k}(x_k)} \left| \psi\left(\frac{x - x_k}{r_k}\right) \right| \, dx = cr_k^2 \int_{B_1(0)} |\psi(z)| \, dz$$
$$\le C(\psi)r_k^2.$$

After transformation the integral S_1 becomes

$$S_{1} = \int_{B_{1}(0)} DF(\Theta_{k} + \lambda_{k}\nabla^{2}u_{k}) : \nabla^{2}\psi \, dz$$
$$= \int_{B_{1}(0)} \int_{0}^{1} \frac{d}{ds} DF(\Theta_{k} + s\lambda_{k}\nabla^{2}u_{k}) : \nabla^{2}\psi \, ds \, dz$$
$$= \int_{B_{1}(0)} \int_{0}^{1} D^{2}F(\Theta_{k} + s\lambda_{k}\nabla^{2}u_{k})(\nabla^{2}u_{k}, \nabla^{2}\psi)\lambda_{k} \, ds \, dz$$

and together with our estimate for S_2 this yields

$$\left| \int_{B_1(0)} \int_0^1 D^2 F(\Theta_k + s\lambda_k \nabla^2 u_k) (\nabla^2 u_k, \nabla^2 \psi) \, ds \, dz \right| \le C(\psi) \lambda_k^{-1} r_k^2. \tag{4.35}$$

Because of (4.28), $\frac{r_k}{\lambda_k} \leq \lambda_k \to 0$ for $k \to \infty$ and thus (note that r_k is bounded) also $\frac{r_k^2}{\lambda_k} \to 0$. Now we turn to the left-hand side of (4.35). Let $\delta > 0$ be given. By (4.32) and Egorov's Theorem there is a set $S \subset B_1(0)$ with $\mathcal{L}^2(B_1(0) - S) < \delta$ and $\lambda_k \nabla^2 u_k \Rightarrow 0$ a.e. on S. With (4.31) and (4.32) it follows:

$$\int_{S} \int_{0}^{1} D^{2} F(\Theta_{k} + \lambda_{k} s \nabla^{2} u_{k}) (\nabla^{2} u_{k}, \nabla^{2} \psi) \, ds \, dz \to \int_{S} D^{2} F(\Theta) (\nabla^{2} \hat{u}, \nabla^{2} \psi) \, dz.$$

At the same time, due to the boundedness of $D^2 {\cal F}$ and by Hölder's inequality we find

$$\left| \int_{B_{1}(0)-S} \int_{0}^{1} D^{2}F(\Theta_{k} + \lambda_{k}s\nabla^{2}u_{k})(\nabla^{2}u_{k}, \nabla^{2}\psi) \, ds \, dz \right|$$

$$\leq c \|\nabla^{2}u_{k}\|_{2;B_{1}(0)}\|\nabla^{2}\psi\|_{2;B_{1}(0)-S}$$

$$\leq C \|\nabla^{2}\psi\|_{2;B_{1}(0)-S} \leq C(\psi)\delta^{\frac{1}{2}},$$

and since δ can be chosen arbitrarily small, this proves

$$\int_{B_1(0)} \int_0^1 D^2 F(\Theta_k + s\lambda_k \nabla^2 u_k) (\nabla^2 u_k, \nabla^2 \psi) \, ds \, dz \to \int_{B_1(0)} D^2 F(\Theta) (\nabla^2 \hat{u}, \nabla^2 \psi) \, dz$$

and (4.34) follows. We can therefore rely on the results in [GM] and [Kr] on higher order elliptic systems (see also the comments subsequent to (3.10) in [AF]) and find a constant $C^*(L)$ such that

$$\oint_{B_{\tau}(0)} |\nabla^2 \hat{u} - (\nabla^2 \hat{u})_{0,\tau}|^2 \, dz \le C^*(L)\tau^2, \tag{4.36}$$

which together with the definition of $C_*(L)$ contradicts (4.29) as soon as (4.31) is improved towards

$$\nabla^2 u_k \to \nabla^2 \hat{u} \text{ in } L^2_{\text{loc}}(B_1(0)).$$
 (4.37)

In fact, after scaling (4.29) reads

$$\int_{B_{\tau}(0)} |\nabla^2 u_k - (\nabla^2 u_k)_{0,\tau}|^2 \, dz = \lambda_k^{-2} E(x_k, \tau r_k) > \tau^2 C_*(L),$$

and hence, along with (4.37)

$$\oint_{B_{\tau}(0)} |\nabla^2 \hat{u} - (\nabla^2 \hat{u})_{0,\tau}|^2 \, dz \ge \tau^2 C_*(L).$$

Therefore, in order to complete the proof of the Blow-up Lemma we need to verify (4.37). To do this, we proceed just like in [AF] and notice that we have (cf. (3.14) therein)

$$\lim_{k \to \infty} \int_{B_{\rho}(0)} \left(1 + |\Theta_k| + \lambda_k |\nabla^2 \hat{u}| + \lambda_k |\nabla^2 w_k| \right)^{-\mu} |\nabla^2 w_k|^2 \, dz = 0 \tag{4.38}$$

where $\rho \in (0, 1)$ and $w_k := u_k - \hat{u}$. Since the derivation of (4.38) is somewhat lengthy, we postpone its proof to the end and continue to establish (4.37). Fix $\rho \in (0, 1)$ and choose $M \ge 1$: it holds

$$\int_{B_{\rho}(0)} |\nabla^2 w_k|^2 dz = \int_{B_{\rho}(0) \cap \left[\lambda_k |\nabla^2 u_k| \le M\right]} |\nabla^2 w_k|^2 dz + \varepsilon_k,$$

$$\varepsilon_k := \int_{B_{\rho}(0) \cap \left[\lambda_k |\nabla^2 u_k| > M\right]} |\nabla^2 w_k|^2 dz.$$

Due to $\nabla^2 \hat{u} \in L^{\infty}_{\text{loc}}(B_1(0))$ and the boundedness of the sequence Θ_k equation (4.38) implies

$$\lim_{k \to \infty} \int_{B_{\rho}(0) \cap \left[\lambda_k |\nabla^2 u_k| \le M\right]} |\nabla^2 w_k|^2 \, dz = 0.$$

$$(4.39)$$

Let

$$\varphi_{k} := \lambda_{k}^{-1} \left\{ \left(1 + |\Theta_{k} + \lambda_{k} \nabla^{2} u_{k}| \right)^{1 - \frac{\mu}{2}} - \left(1 + |\Theta_{k}| \right)^{1 - \frac{\mu}{2}} \right\},\$$

i.e. we consider the scaled version of φ from (4.5). We claim the validity of

$$\sup_{k} \int_{B_{\rho}(0)} |\nabla \varphi_{k}|^{2} dz \le c(\rho) < \infty.$$
(4.40)

Accepting this inequality for the moment, we further observe

$$|\varphi_k| = \lambda_k^{-1} \left| \int_0^1 \frac{d}{ds} \left(1 + |\Theta_k + s\lambda_k \nabla^2 u_k| \right)^{1-\frac{\mu}{2}} ds \right| \le c |\nabla^2 u_k|,$$

so that (4.30) implies the $L^2(B_1(0))$ -boundedness of the φ_k and thus

$$\sup_{k} \|\varphi_{k}\|_{1,2;B_{\rho}(0)} < \infty.$$
(4.41)

By the definition of the φ_k , for $M \ge M_0$ sufficiently large and independent of k (note that the sequence Θ_k is bounded) we have on $B_{\rho}(0) \cap [\lambda_k |\nabla^2 u_k| > M]$

$$\varphi_k \ge \frac{1}{2}\lambda_k^{-1} (\lambda_k |\nabla^2 u_k|)^{1-\frac{\mu}{2}} = \frac{1}{2}\lambda_k^{-\frac{\mu}{2}} |\nabla^2 u_k|^{1-\frac{\mu}{2}}$$

and therefore

$$|\nabla^2 u_k|^2 \le (2\varphi_k)^{\frac{4}{2-\mu}} \lambda_k^{\frac{2\mu}{2-\mu}} \text{ on } B_\rho(0) \cap \left[\lambda_k |\nabla^2 u_k| > M\right].$$

According to (4.41), $\varphi_k^{\frac{4}{2-\mu}}$ is uniformly integrable, so that

$$\int_{B_{\rho}(0)\cap \left[\lambda_{k}|\nabla^{2}u_{k}|>M\right]} |\nabla^{2}u_{k}|^{2} dz \to 0 \text{ for } k \to \infty.$$

From $\lambda_k |\nabla^2 u_k| \to 0$ a.e. (cf. (4.32)) it follows

$$\lim_{k \to \infty} \int_{\substack{B_{\rho}(0) \cap \left[\lambda_k | \nabla^2 u_k | > M\right]}} |\nabla^2 \hat{u}| \, dz = 0,$$

and (4.39) implies $\nabla^2 w_k \to 0$ in $L^2_{loc}(B_1(0))$, i.e. (4.37) holds which proves part (c) of Theorem 1.4 as soon as (4.38) and (4.40) have been established, what is to follow next.

ad (4.40). We return to the Euler equation (4.8) choosing $v := \eta^6 \partial_\alpha (u_\delta - P)$, where P denotes a polynomial of degree ≤ 2 and η is specified in the same way as after (4.8). We obtain

$$\int_{B_{2r}(x_0)} \eta^6 D^2 F_{\delta}(\nabla^2 u_{\delta}) \left(\partial_{\alpha} \nabla^2 u_{\delta}, \partial_{\alpha} \nabla^2 u_{\delta} \right) dx$$

= $-\int_{B_{2r}(x_0)} D^2 F_{\delta}(\nabla^2 u_{\delta}) \left(\partial_{\alpha} \nabla^2 u_{\delta}, \nabla^2 \eta^6 \partial_{\alpha} [u_{\delta} - P] + 2 \nabla \eta^6 \otimes \nabla \partial_{\alpha} (u_{\delta} - P) \right) dx$
+ $\lambda \int_{B_{2r}(x_0) - D} (u_{\delta} - f) \partial_{\alpha} \left(\eta^6 \partial_{\alpha} (u_{\delta} - P) \right) dx.$

From (4.3) it follows $u_{\delta} \in L^{\infty}_{loc}(\Omega)$ uniformly. Applying the Cauchy-Schwarz inequality to the first integral on the right-hand side and using the boundedness of D^2F we get the following estimate, which corresponds to inequality (2.11) in [AF]:

$$\begin{split} \int_{B_{2r}(x_0)} \eta^6 D^2 F_{\delta}(\nabla^2 u_{\delta}) \left(\partial_{\alpha} \nabla^2 u_{\delta}, \partial_{\alpha} \nabla^2 u_{\delta} \right) dx \\ &\leq c \Biggl\{ r^{-4} \int_{B_{2r}(x_0)} |\nabla(u_{\delta} - P)|^2 dx + r^{-2} \int_{B_{2r}(x_0)} |\nabla^2(u_{\delta} - P)|^2 dx \\ &+ \int_{B_{2r}(x_0)} |\nabla^2(u_{\delta} - P)| dx + r^{-1} \int_{B_{2r}(x_0)} |\nabla(u_{\delta} - P)| dx \Biggr\} \\ &\leq c \Biggl\{ r^{-4} \int_{B_{2r}(x_0)} |\nabla(u_{\delta} - P)|^2 dx + r^{-2} \int_{B_{2r}(x_0)} |\nabla^2(u_{\delta} - P)|^2 dx + r^2 \Biggr\}, \end{split}$$

where we have applied Young's inequality. We pass to the limit $\delta \to 0$ (recall the convergences stated in front of (4.5)) and get by the boundedness of D^2F and lower semicontinuity

$$\int_{B_{r}(x_{0})} |\nabla \varphi|^{2} dx$$

$$\leq c \left\{ r^{-4} \int_{B_{2r}(x_{0})} |\nabla u - \nabla P|^{2} dx + r^{-2} \int_{B_{2r}(x_{0})} |\nabla^{2}u - \nabla^{2}P|^{2} dx + r^{2} \right\}.$$

Now, if $\rho \in (0,1)$ and if we choose in the beginning $\eta \equiv 1$ on $B_{\rho r}(x_0)$, spt $\eta \subset$

 $B_r(x_0)$, etc., then it is clear that in place of the latter inequality we obtain

$$\int_{B_{\rho r}(x_0)} |\nabla \varphi|^2 dx$$

$$\leq c(\rho) \left\{ r^{-4} \int_{B_r(x_0)} |\nabla u - \nabla P|^2 dx + r^{-2} \int_{B_r(x_0)} |\nabla^2 u - \nabla^2 P|^2 dx + r^2 \right\}.$$
(4.42)

Since

$$\int_{B_{\rho}(0)} |\nabla \varphi_k|^2 \, dz = \lambda_k^{-2} \int_{B_{\rho r_k}(x_k)} |\nabla \varphi|^2 \, dx,$$

and $\lambda_k^{-2} r_k^2 \to 0$ it is now immediate that (4.40) is a consequence of (4.42) and the properties of the sequence u_k provided we choose the polynomial P as done in the definition of the functions u_k , i.e.

$$P_k(z) := r_k A_k \cdot z - a_k - \frac{1}{2} r_k^2 \Theta_k(z, z) + \frac{1}{2} r_k^2 \oint_{B_1(0)} \Theta_k(y, y) dy.$$

ad (4.38) . Take a cut-off function $\eta \in C_0^{\infty}(B_1(0)), 0 \le \eta \le 1$. Then a Taylor expansion yields

$$\lambda_{k}^{-2} \int_{B_{1}(0)} \eta \left[F(\Theta_{k} + \lambda_{k} \nabla^{2} u_{k}) - F(\Theta_{k} + \lambda_{k} \nabla^{2} \hat{u}) \right] dz$$

$$- \lambda_{k}^{-1} \int_{B_{1}(0)} \eta DF(\Theta_{k} + \lambda_{k} \nabla^{2} \hat{u}) : \nabla^{2} w_{k} dz$$

$$= \int_{B_{1}(0)} \int_{0}^{1} \eta D^{2} F\left(\Theta_{k} + \lambda_{k} \nabla^{2} \hat{u} + s\lambda_{k} \nabla^{2} w_{k}\right) (\nabla^{2} w_{k}, \nabla^{2} w_{k}) (1 - s) ds dz$$

$$(4.43)$$

$$\geq c \int_{B_1(0)} \int_{B_1(0)} \int_{0} \eta \left(1 + |\Theta_k + \lambda_k \nabla^2 \hat{u} + s\lambda_k \nabla^2 w_k| \right)^{-\mu} |\nabla^2 w_k|^2 (1-s) \, ds \, dz.$$

If we just consider the integral from s = 0 to $s = \frac{1}{2}$ instead of the whole interval [0, 1] in the latter term, it follows

r.h.s. of (4.43)
$$\geq c \int_{B_1(0)} \eta \left(1 + |\Theta_k| + \lambda_k |\nabla^2 \hat{u}| + \lambda_k |\nabla^2 w_k|^2 \right)^{-\mu} |\nabla^2 w_k|^2 dz$$
 (4.44)

and (4.38) will follow once we have shown that the left-hand side of (4.43) converges to zero as $k \to \infty$. Note that obviously the left-hand side of (4.43) is nonnegative and hence it suffices to give a suitable upper bound. To this purpose we make use of the convexity of F and obtain

$$\eta F(\Theta_k + \lambda_k \nabla^2 u_k) - \eta F(\Theta_k + \lambda_k \nabla^2 \hat{u})$$

$$= \eta F(\Theta_k + \lambda_k \nabla^2 u_k) - \left\{ \eta F(\Theta_k + \lambda_k \nabla^2 \hat{u}) + (1 - \eta) F(\Theta_k + \lambda_k \nabla^2 u_k) \right\}$$

$$+ (1 - \eta) F(\Theta_k + \lambda_k \nabla^2 u_k) + (1 - \eta) F(\Theta_k + \lambda_k \nabla^2 u_k)$$

$$\leq \eta F(\Theta_k + \lambda_k \nabla^2 u_k) + (1 - \eta) F(\Theta_k + \lambda_k \nabla^2 u_k) - F(\Theta_k + \eta \lambda_k \nabla^2 \hat{u} + (1 - \eta) \lambda_k \nabla^2 u_k)$$

$$= F(\Theta_k + \lambda_k \nabla^2 u_k) - F\left(\Theta_k + \lambda_k \left[\eta \nabla^2 \hat{u} + (1-\eta) \nabla^2 u_k\right]\right),$$

hence it follows

l.h.s. of (4.43)

$$\leq \lambda_{k}^{-2} \int_{B_{1}(0)} F(\Theta_{k} + \lambda_{k} \nabla^{2} u_{k}) dz$$

$$- \lambda_{k}^{-2} \int_{B_{1}(0)} F\left(\Theta_{k} + \lambda_{k} \left[\eta \nabla^{2} \hat{u} + (1 - \eta) \nabla^{2} u_{k}\right]\right) dz$$

$$- \lambda_{k}^{-1} \int_{B_{1}(0)} \eta DF(\Theta_{k} + \lambda_{k} \nabla^{2} \hat{u}) : \nabla^{2} w_{k} dz =: I_{1} - I_{2} - I_{3}.$$

$$(4.45)$$

The minimality of u implies

$$I_{1} = \lambda_{k}^{-2} \int_{B_{1}(0)} F\left(\nabla^{2} u(r_{k}z + x_{k})\right) dz = \lambda_{k}^{-2} r_{k}^{-2} \int_{B_{r_{k}}(x_{k})} F(\nabla^{2} u) dx$$

$$\leq \lambda_{k}^{-2} r_{k}^{-2} \Biggl\{ \int_{B_{r_{k}}(x_{k})} F(\nabla^{2} v) dx + \frac{\lambda}{2} \int_{B_{r_{k}}(x_{k}) - D} |v - f|^{2} dx - \frac{\lambda}{2} \int_{B_{r_{k}}(x_{k}) - D} |u - f|^{2} dx \Biggr\}$$

$$(4.46)$$

for all $v \in W^{2,1}(\Omega) \cap L^2(\Omega - D)$ with spt $(u - v) \Subset B_{r_k}(x_k)$. Now set $v_k(z) := u_k(z) + \eta(z)(\hat{u} - u_k)(z), \ z \in B_1(0),$ and define

$$\tilde{v}_k(z) := \lambda_k r_k^2 v_k(z) + P_k(z)$$

with $P_k(z)$ as introduced after (4.42). Finally we let

$$\hat{v}_k(x) := \tilde{v}_k\left(\frac{x-x_k}{r_k}\right)$$

with the result that spt $(u - \hat{v}_k) \in B_{r_k}(x_k)$ as well as

$$\begin{aligned} \nabla^2 \hat{v}_k(x) &= r_k^{-2} \nabla^2 \tilde{v}_k \left(\frac{x - x_k}{r_k} \right) \\ &= \lambda_k \nabla^2 v_k \left(\frac{x - x_k}{r_k} \right) + \nabla^2 P_k \left(\frac{x - x_k}{r_k} \right) r_k^{-2} \\ &= \lambda_k \nabla^2 \Big\{ u_k + \eta (\hat{u} - u_k) \Big\} \left(\frac{x - x_k}{r_k} \right) + \Theta_k, \end{aligned}$$

which means that we have

$$\lambda_k^{-2} r_k^{-2} \int_{B_{r_k}(x_k)} F(\nabla^2 \hat{v}_k) dx$$

= $\lambda_k^{-2} \int_{B_1(0)} F(\Theta_k + \lambda_k \nabla^2 \{u_k + \eta(\hat{u} - u_k)\}) dz.$

Going back to (4.46) it follows

$$I_{1} \leq \overbrace{\lambda_{k}^{-2} \int_{B_{1}(0)} F(\Theta_{k} + \lambda_{k} \nabla^{2} \{u_{k} + \eta(\hat{u} - u_{k})\}) dz}_{+\frac{\lambda}{2} \lambda_{k}^{-2} r_{k}^{-2} \int_{B_{r_{k}}(x_{k}) - D} \left(|f - \hat{v}_{k}|^{2} - |f - u|^{2}\right) dx.$$

$$(4.47)$$

Using that f is in $L^{\infty}(\Omega - D)$, we can estimate the second term on the right-hand

side of (4.47) by

$$\begin{split} \lambda_{k}^{-2} r_{k}^{-2} & \int \limits_{B_{r_{k}}(x_{k})-D} \left(|f - \hat{v}_{k}|^{2} - |f - u|^{2} \right) dx \\ &\leq c \lambda_{k}^{-2} r_{k}^{-2} \int \limits_{B_{r_{k}}(x_{k})} |\hat{v}_{k} - u| \underbrace{(1 + |u| + |\hat{v}_{k}|)}_{\text{bounded!}} dx \\ &\leq c \lambda_{k}^{-2} r_{k}^{-2} \int \limits_{B_{r_{k}}(x_{k})} |\hat{v}_{k} - u| dx \\ &= c \lambda_{k}^{-2} \int \limits_{B_{1}(0)} |\tilde{v}_{k}(z) - u(x_{k} + r_{k}z)| dz \\ &= c \lambda_{k}^{-2} \int \limits_{B_{1}(0)} |\lambda_{k} r_{k}^{2} v_{k}(z) + P_{k}(z) - u(x_{k} + r_{k}z)| dz \\ &= c \lambda_{k}^{-1} r_{k}^{2} \int \limits_{B_{1}(0)} |v_{k}(z) - r_{k}^{-2} \lambda_{k}^{-1} \left(\left(u(x_{k} + r_{k}z) - P_{k}(z) \right) \right) \right) | dz \\ &= c \lambda_{k}^{-1} r_{k}^{2} \int \limits_{B_{1}(0)} |v_{k} - u_{k}| dz \\ &= c \lambda_{k}^{-1} r_{k}^{2} \int \limits_{B_{1}(0)} \eta |\hat{u} - u_{k}| dz \\ &\leq c \lambda_{k}^{-1} r_{k}^{2} =: \varepsilon_{k} \to 0 \text{ as } k \to \infty, \end{split}$$

where the last estimate uses (4.31). The above estimate combined with (4.45) and (4.47) now implies

l.h.s. of (4.43)
$$\leq \widetilde{I}_1 - I_2 - I_3 + \frac{\lambda}{2}\varepsilon_k.$$
 (4.48)

Starting from (4.48), we can follow the arguments in [AF], p. 209, very closely: let

$$X_k := \Theta_k + \lambda_k \big[(1 - \eta) \nabla^2 u_k + \eta \nabla^2 \hat{u} \big], \ Z_k := 2 \nabla \eta \otimes \nabla (\hat{u} - u_k) + \nabla^2 \eta (\hat{u} - u_k)$$

and observe that by another Taylor expansion we have

$$\widetilde{I}_{1} - I_{2} = \lambda_{k}^{-1} \int_{B_{1}(0)} DF(X_{k}) : Z_{k} dz + \int_{B_{1}(0)} \int_{0}^{1} D^{2}F(X_{k} + s\lambda_{k}Z_{k})(Z_{k}, Z_{k})(1-s) ds dz \leq \lambda_{k}^{-1} \int_{B_{1}(0)} DF(X_{k}) : Z_{k} dz + c \int_{B_{1}(0)} |Z_{k}|^{2} dz,$$

since $D^2 F$ is bounded. By the convergence $u_k \to \hat{u}$ in $W^{1,2}(B_1(0))$ (recall (4.31)) we find that $c \int_{B_1(0)} |Z_k|^2 dz$ converges to zero and (4.48) implies

l.h.s. of (4.43)

$$\leq \lambda_{k}^{-1} \int_{B_{1}(0)} DF(X_{k}) : Z_{k} dz$$

$$-\lambda_{k}^{-1} \int_{B_{1}(0)} \eta DF(\Theta_{k} + \lambda_{k} \nabla^{2} \hat{u}) : \nabla^{2} w_{k} dz + \varepsilon_{k}$$

$$(4.49)$$

$$= \lambda_k^{-1} \int_{B_1(0)} \left(DF(X_k) - DF(\Theta_k + \lambda_k \nabla^2 \hat{u}) \right) : Z_k \, dz$$
$$- \lambda_k^{-1} \int_{B_1(0)} DF(\Theta_k + \lambda_k \nabla^2 \hat{u}) : \nabla^2(\eta w_k) \, dz + \varepsilon_k$$
$$=: \lambda_k^{-1} I_4 - \lambda_k^{-1} I_5 + \varepsilon_k$$

for another appropriate sequence $\varepsilon_k \to 0$. With the same idea as in [AF], p. 211, the integral I_4 can be estimated by

$$\begin{split} \lambda_k^{-1} I_4 &= \int\limits_{B_1(0)} \int\limits_0^1 D^2 F(\Theta_k + \lambda_k \nabla^2 \hat{u} + s\lambda_k (1 - \eta) \nabla^2 w_k) (\nabla^2 w_k, Z_k) (1 - \eta) \, ds \, dz \\ &\leq \\ \underset{\text{Hölder}}{\leq} c \underbrace{\|\nabla^2 w_k\|_{2;B_1(0)}}_{\text{bounded by (4.31)}} \underbrace{\|Z_k\|_{2;B_1(0)}}_{\to 0 \text{ by (4.31)}}, \end{split}$$

moreover we have

$$\lambda_k^{-1} I_5 = \lambda_k^{-1} \int_{B_1(0)} \int_0^1 D^2 F \left(\Theta_k + s\lambda_k \nabla^2 \hat{u}\right) \left(\lambda_k \nabla^2 \hat{u}, \nabla^2 (\eta w_k)\right) ds dz$$
$$= \int_{B_1(0)} \int_0^1 D^2 F \left(\Theta_k + s\lambda_k \nabla^2 \hat{u}\right) \left(\nabla^2 \hat{u}, \nabla^2 (\eta w_k)\right) ds dz$$
$$\longrightarrow 0 \text{ for } k \to \infty,$$

according to (4.31) and consequently

r.h.s. of
$$(4.49) \longrightarrow 0, k \to \infty,$$

which finally proves (4.38).

To prove the assertion concerning the Hausdorff-dimension of the singular set we notice that we have (see Remark 4.1 (a))

$$\Omega - \Omega_0 = \left\{ x \in \Omega : \limsup_{r \to 0} |(\nabla^2 u)_{x,r}| = \infty \right\}$$
$$\cup \left\{ x \in \Omega : \liminf_{r \to 0} E(x,r) > 0 \right\} =: \Omega_1 \cup \Omega_2.$$

Since $\nabla^2 u \in W^{1,s}_{\text{loc}}(\Omega)$ for all s < 2 (compare the calculations after (4.4)), it follows from [Gia], Theorem 2.1, p. 100, that

$$\mathcal{H}^{2-s+\kappa}(\Omega_1) = 0 \quad \forall \kappa > 0$$

and hence $\mathcal{H}^{\varepsilon}(\Omega_1) = 0$ for $\varepsilon > 0$ arbitrarily small. Further (using the Sobolev-Poincaré inequality) it holds

$$E(x,r)^{\frac{1}{2}} \leq cr \oint_{B_r(x)} |\nabla^3 u| dy \leq c \left(r^{s-2} \int_{B_r(x)} |\nabla^3 u|^s dy \right)^{\frac{1}{s}},$$

and [Gia], Theorem 2.2, p. 101, implies that $|\nabla^3 u| \in L^s_{\text{loc}}(\Omega)$ together with the above estimate yields $\mathcal{H}^{2-s}(\Omega_2) = 0$ and thus $\mathcal{H}^{\varepsilon}(\Omega_2) = 0$ for any $\varepsilon > 0$ which concludes the proof of Theorem 1.4 (c). It remains to give the

proof of Theorem 1.4 part (d): Let $\sigma_{\delta} := DF_{\delta}(\nabla^2 u_{\delta})$. By part (b) of Lemma 3.2 we have

$$\begin{aligned} \partial_{\alpha}\sigma_{\delta} : \partial_{\alpha}\sigma_{\delta} &= D^{2}F_{\delta}(\nabla^{2}u_{\delta})\big(\partial_{\alpha}\nabla^{2}u_{\delta},\partial_{\alpha}\sigma_{\delta}\big) \\ &\leq D^{2}F_{\delta}(\nabla^{2}u_{\delta})\big(\partial_{\alpha}\nabla^{2}u_{\delta},\partial_{\alpha}\nabla^{2}u_{\delta}\big)^{\frac{1}{2}}D^{2}F_{\delta}(\nabla^{2}u_{\delta})\big(\partial_{\alpha}\sigma_{\delta},\partial_{\alpha}\sigma_{\delta}\big)^{\frac{1}{2}} \end{aligned}$$

so that $|\nabla \sigma_{\delta}|^2 \leq \Phi_{\delta} |D^2 F_{\delta}(\nabla^2 u_{\delta})|^{\frac{1}{2}} |\nabla \sigma_{\delta}|$ where we have abbreviated

$$\Phi_{\delta} := D^2 F_{\delta}(\nabla^2 u_{\delta}) \left(\partial_{\alpha} \nabla^2 u_{\delta}, \partial_{\alpha} \nabla^2 u_{\delta} \right)^{\frac{1}{2}}.$$

According to inequality (4.2) we know

$$\Phi_{\delta} \in L^2_{\text{loc}}(\Omega)$$
 uniformly in δ .

By the condition of μ -ellipticity (1.16) it holds $|D^2 F_{\delta}(Z)| \leq c(1+\delta)$ and thus

$$|\nabla \sigma_{\delta}| \le c(1+\delta)\Phi_{\delta}$$

which implies $\sigma_{\delta} \in W^{1,2}_{\text{loc}}(\Omega)$ uniformly in δ , and in particular $\sigma_{\delta} \to: \overline{\sigma}$ in $W^{1,2}_{\text{loc}}(\Omega)$. But then it follows $\overline{\sigma} = \sigma$, since (due to $u_{\delta} \in W^{3,s}_{\text{loc}}(\Omega)$ uniformly for s < 2) $\nabla^2 u_{\delta} \to \nabla^2 u$ a.e., which finishes the proof of part (d) and thereby the proof of Theorem 1.4.

References

- [Ad] R.A. Adams, Sobolev spaces, Academic Press, New York-London, 1975, Pure and Applied Mathematics, Vol. 65.
- [AF] D. Apushkinskaya, M. Fuchs Partial regularity for higher order variational problems under anisotropic growth conditions, Ann. Acad. Sci. Fenn. Math. 32, 199-214 (2007).
- [AFF] E. Acerbi, I. Fonseca, N. Fusco, Regularity results for equilibria in a variational model for fracture, Proceedings of the Royal Society of Edinburgh: Section A Mathematics, Volume 127, Issue 05, pp 889-902 (1997).
- [AFP] L. Ambrosio, N. Fusco, D. Pallara, *Functions of bounded variation and* free discontinuity problems, Clarendon Press, Oxford (2000).
- [AG] G. Anzelotti, M. Giaquinta, Convex functionals and partial regularity, Archive for Rational Mechanics and Analysis, Volume 102, Issue 3, pp 243-272 (1988).
- [BC] C. Brito-Loeza, K. Chen, On high-order denoising models and fast algorithms for vector-valued images, IEEE Trans. Image Process. 19, no. 6, 1518–1527 (2010).
- [BF1] M. Bildhauer, M. Fuchs *Higher order variational problems on twodimensional domains*, Ann. Acad. Sci. Fenn. Math. 31, 349-362 (2006).

- [BF2] M. Bildhauer, M. Fuchs, A variational approach to the denoising of images based on different variants of the TV-regularization, Appl. Math. Optim. 66 (3) 331-361 (2012).
- [BF3] M. Bildhauer, M. Fuchs, On some perturbations of the total variation image inpainting method. Part I: regularity theory, J. Math. Sciences 202(2), 154-169 (2014).
- [BF4] M. Bildhauer, M. Fuchs, On some perturbations of the total variation image inpainting method. Part II: relaxation and dual variational formulation, J. Math. Sciences 205 (2), 121-140 (2015).
- [BFW] M. Bildhauer, M. Fuchs, J. Weickert, An alternative approach towards the higher order denoising of images. Analytical aspects, to appear in Zap. Nauchn. Sem. St.-Petersburg. Odtel. Mat. Inst. Steklov (POMI).
- [BKP] K. Bredies, K. Kunisch, T. Pock, Total generalized variation, SIAM J. Imaging Sciences, Vol. 3, No. 3, pp. 492-526 (2010).
- [BS] L. Beck, T. Schmidt, On the Dirichlet problem for variational integrals in BV, J. Reine Angew. Math. 674, 113-194 (2013).
- [De] F. Demengel, Fonctions à hessien borné, Annales de l'institut Fourier, tome 34, nº 2, p. 155-190 (1984).
- [DT] F. Demengel, R. Temam, Convex functions of a measure and applications, Indiana University Mathematics Journal, Vol. 33, No. 5 (1984).
- [EG] L. C. Evans, R. F. Gariepy, Blowup, compactness and partial regularity in the calculus of variations, Indiana University Mathematics Journal, Vol. 36, No. 2, pp. 361-372 (1987).
- [FF] I. Fonseca, N. Fusco, Regularity results for anisotropic image segmentation models, Annali della Scuola Normale Superiore di Pisa, Classe di Scienze 4^e série, tome 24, n^o 3, p. 463-499 (1997).
- [FT] M. Fuchs, C. Tietz, Existence of generalized minimizers and of dual solutions for a class of variational problems with linear growth related to image recovery, J. Math. Sciences 210 (4), 458-475 (2015).
- [Gia] M. Giaquinta, Multiple integrals in the calculus of variations and nonlinear elliptic systems, Annals of Mathematics Studies, Princeton University Press (1983).
- [Giu] E. Giusti, *Minimal surfaces and functions of bounded variation*, Monographs in Mathematics, Vol. 80, Birkhäuser Verlag, Basel (1984).

- [GM] M. Giaquinta, G. Modica, Regularity results for some classes of higher order non linear elliptic systems, Journal f
 ür die reine und angewandte Mathematik, Vol. 0311_0312, pp. 145-169 (1979).
- [GMS] M. Giaquinta, G. Modica, J. Souček, Cartesian currents in the calculus of variations I, Ergebnisse der Mathematik und ihrer Grenzgebiete, 3. Folge. A Series of Modern Surveys in Mathematics, Vol. 37, Springer, Berlin-Heidelberg (1998).
- [JS] R.L. Jerrard, H.M. Soner, Functions of bounded higher variation, Indiana Univ. Math. J., 51, 645-677 (2002).
- [Kr] M. Kronz, Partial regularity results for minimizers of quasiconvex functionals of higher order, Annales de l'I.H.P. Analyse non linéaire, Vol 19, Issue: 1, page 81-112 (2002).
- [LLT] M. Lysaker, A. Lundervold, X.-C. Tai, Noise removal using fourth-order partial differential equation with applications to medical magnetic resonance images in space and time, IEEE Transactions on Image Processing 12, 1579-1590 (2003).
- [Ma] V. Maz'ja, Sobolev spaces, Springer Series in Soviet Mathematics, Springer-Verlag Berlin Heidelberg (1985).
- [MS] N.G. Meyers, J. Serrin, H = W, Proc. N. A. S. Bd. 51, Nr. 6, New York (1964), 1055–1056.
- [MT] J. Müller, C. Tietz, Existence and almost everywhere regularity of generalized minimizers for a class of variational problems with linear growth related to image inpainting, Technical Report No. 363, Department of Mathematics, Saarland University, Saarbrücken, Germany, July 2015. http://www.math.uni-sb.de/service/preprints/preprint363.pdf
- [Mü] J. Müller, A density result for Sobolev functions and functions of higher order bounded variation with additional integrability constraints, to appear in Ann. Acad. Sci. Fenn. Math.
- [MZ] J. Malý, W. Ziemer, Fine regularity of solutions of elliptic partial differential equations, Mathematical Surveys and Monographs Vol. 51, American Mathematical Society (1997).
- [Re] Yu. G. Reschetnyak, Weak convergence of completely additive vector functions on a set, Sibirsk. Maz. Ž. 9 1386-1394 (1968) (Translated).
- [ROF] L. I. Rudin, S. Osher, E. Fatemi, Nonlinear total variation based noise removal algorithms, Physica D 60: 259–268, Elsevier (1992).

- [St] E.M. Stein, Singular integrals and differentiability properties of functions, Princeton University Press, Princeton, New Jersey (1970).
- [SS] S. Setzer, G. Steidl, Variational methods with higher order derivatives in image processing, Approximation Theory XII: San Antonio 2007, M. Neamtu and L. L. Schumaker, eds., Nashboro Press, Brentwood, TN, pp. 360-385 (2008).
- [Ti] C. Tietz, Existence and regularity theorems for variants of the TV-image inpainting method in higher dimensions and with vector-valued data. PhD thesis, Saarbrücken (2016).

Martin Fuchs Saarland University Department of Mathematics P.O. Box 15 11 50 66041 Saarbrücken Germany fuchs@math.uni-sb.de Jan Müller Saarland University Department of Mathematics P.O. Box 15 11 50 66041 Saarbrücken Germany jmueller@math.uni-sb.de